

Flat deformations of a semi-Riemannian metric
admitting a symmetry group

by

CAROT, J. Universitat Illes Balears

and

LLOSA, J. Universitat de Barcelona

19th September 2007

Index

- [1] Flat deformation of a semi-Riemannian metric
- [2] 1-parameter symmetry group
- [3] Flat deformation theorem and symmetries
- [4] The quotient metric
- [5] The inverse problem
- [6] The flat deformation law as a PDS
- [7] The reduced PDS
- [8] Geometrical meaning of the constraints
- [9]

[1]

Flat deformation of a semi-Riemannian metric

Flat deformation theorem (2005)

Given a semi-Riemannian analytic metric, γ , on a manifold \mathcal{M} , it exists a 2-form F and a scalar function c such that:

- 1. an arbitrary scalar constraint $\Psi(c, F, x) = 0$, $x \in \mathcal{M}$ is fulfilled and*
- 2. the deformed metric $\eta := c\gamma + \epsilon M$, is semi-Riemannian and flat*

where $|\epsilon| = 1$, $M(V, W) = \gamma(F_V, F_W)$, $F_V := i_V F$.

We shall limit ourselves to the case of a 4-dimensional spacetime (\mathcal{M}, g) .

Some algebraic remarks

Given $F \in \Lambda^2 \mathcal{M}$, it exists a null tetrad $\{\mu, \nu, \kappa, \lambda\}$

such that either:

Singular case:

$$\underline{F = \kappa \wedge \mu}, \quad M = -\kappa \otimes \kappa$$

$$\boxed{\gamma = \frac{1}{c} \eta - \frac{\epsilon}{c} \kappa \otimes \kappa}$$

with κ isotropic and η flat (conformal Kerr-Schild metric) or

Non-singular case:

$$\underline{F = -B \mu \wedge \nu + E \kappa \wedge \lambda},$$

$$M = -B^2 (\mu \otimes \mu + \nu \otimes \nu) - E^2 (\kappa \otimes \lambda + \lambda \otimes \kappa)$$

$$\eta = (c - \epsilon B^2) \gamma - \epsilon (B^2 + E^2) (\kappa \otimes \lambda + \lambda \otimes \kappa)$$

$$\boxed{\eta = a\gamma + bH}$$

Prop. 1 *Given a Lorentzian analytic metric γ , there exist two scalar functions, a and b , and a hyperbolic 2-plane H such that the metric*

$$\underline{\eta := a\gamma + bH} \quad \text{is Lorentzian and flat.}$$

$\eta := a\gamma - b(\kappa \otimes \lambda + \lambda \otimes \kappa)$ (Recalls a conformal Kerr-Schild transformation)

Let k and l be two vectors such that $\kappa = \gamma(k, -)$ and $\lambda = \gamma(l, -)$

The endomorphism $\mathbb{H} = -k \otimes \lambda - l \otimes \kappa$ associated to H is a 2-dimensional projector on a hyperbolic 2-plane $\mathcal{H}_x \subset T_x\mathcal{M}$

$$\mathbb{H}^2 = \mathbb{H} \quad \text{and} \quad \text{trace } \mathbb{H} = 2$$

$K := \gamma - H$ (complementary 2-plane)

$$\gamma = H + K \quad \text{and} \quad \eta = aK + (a + b)H$$

The *almost-product structure* defined by H is compatible with both, γ and η .

Assume that γ admits a Killing vector X , $\mathcal{L}_X \gamma = 0$.

Does it exist a flat deformation law $\eta := a\gamma + bH$ such that $\mathcal{L}_X \eta = 0$?

(i.e., such that X is also a Killing vector for η)

This is equivalent to $\mathcal{L}_X a = \mathcal{L}_X b = 0$, $\mathcal{L}_X H = 0$

[3]

1-parameter symmetry group

(\mathcal{M}, η) is a semi-Riemannian 4-manifold and G is a connected 1-parameter Lie group acting smoothly on \mathcal{M}

$$\psi : G \times \mathcal{M} \longrightarrow \mathcal{M}, \quad (g, x) \longrightarrow gx .$$

leaving η invariant: $\underline{g^* \eta_{gx} = \eta_x .}$

$\mathcal{S} = \{Gx, x \in \mathcal{M}\}$ is the class of all orbits and $\pi : x \in \mathcal{M} \rightarrow Gx \in \mathcal{S}$ is the canonical projection.

We assume that \mathcal{S} is a manifold, π is smooth and $\pi_* : T\mathcal{M} \rightarrow T\mathcal{S}$ jacobian map.

$$\begin{aligned} \forall x \in \mathcal{M}, \quad \psi_x : G \rightarrow \mathcal{M} & \quad \text{is smooth and } \psi_{x*} : TG \rightarrow T\mathcal{M} \\ g \rightarrow gx & \quad T_e G \rightarrow \mathcal{G}_x \subset T_x \mathcal{M} \end{aligned}$$

If X is an infinitesimal generator of the action of G , $\mathcal{G} = \text{span}[X]$ and

$$g_* X_x = X_{gx}, \quad \forall g \in G \quad \text{and} \quad x \in \mathcal{M}$$

[2]

Projectable vectors and tensors

$$\xi := \eta(X, \cdot) \in \Lambda^1 \mathcal{M}$$

$$\text{Assume } l := \eta(X, X) = \langle \xi, X \rangle \neq 0$$

$$g^* \xi_{gx} = \xi_x, \forall g \in G, \quad \text{or, locally } \mathcal{L}_X \xi = 0$$

Any $V \in T_x \mathcal{M}$ can be separated in two components that are, respectively, transverse to ξ and parallel to X :

$$T\mathcal{M} = \xi^\perp \oplus \text{span}[X], \quad V = V^\perp + \frac{\langle \xi, V \rangle}{l} X$$

Killing equation

$$\mathcal{L}_X \eta = 0 \quad \Leftrightarrow \quad \nabla \xi \text{ skewsymmetric} \quad \boxed{\nabla \xi = \frac{1}{2} d\xi}$$

$$\mathcal{L}_X \xi = 0 \quad \Rightarrow \quad i_X (d\xi) = -d(i_X \xi) = -dl$$

$$\boxed{d\xi = df \wedge \xi + \Theta}$$

$$\text{where } f := \log |l| \quad \text{and} \quad i_X \Theta = 0$$

Def. 1: $Y \in \mathcal{X}(\mathcal{M})$ is projectable if

$$x, y \in \mathcal{M}, \quad \pi x = \pi y \Rightarrow \pi_* Y_x = \pi_* Y_y$$

Prop. 2: $Y \in \mathcal{X}(\mathcal{M})$ is projectable if, and only if,

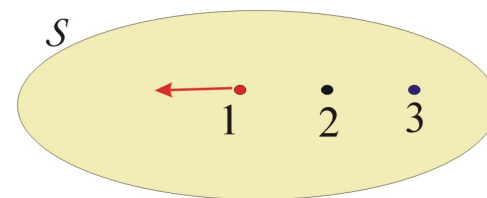
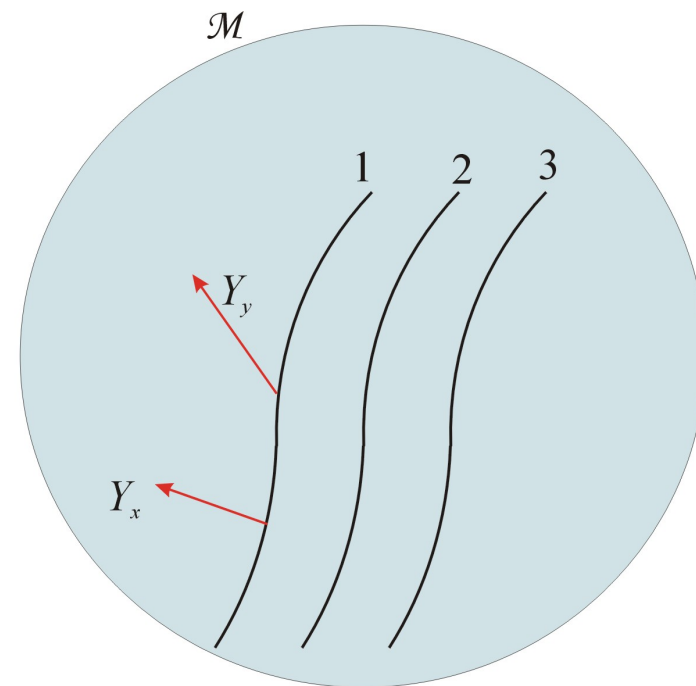
$$\pi_* (\mathcal{L}_X Y) = 0$$

For transverse vector fields

$$\pi_* (\mathcal{L}_X Y) = 0 \quad \Leftrightarrow \quad \mathcal{L}_X Y = 0$$

Class of projectable transverse vector fields

$$\mathcal{X}_\pi(\mathcal{M}) = \{Y \in \mathcal{X}(\mathcal{M}) \mid \mathcal{L}_X Y = 0, \langle \xi, Y \rangle = 0\}$$



Prop. 3: Let $\vec{w} \in \mathcal{X}(\mathcal{S})$, then:

(a) it exists a unique vector field $W \in \mathcal{X}_\pi(\mathcal{M})$ such that $\pi_* W = \vec{w}$,

(b) $\pi_* : \mathcal{X}_\pi(\mathcal{M}) \rightarrow \mathcal{X}(\mathcal{S})$ is bijective and we write $W = \pi_*^{-1} \vec{w}$.

$\pi^* : T_{\pi x}^* \mathcal{S} \longrightarrow T_x^* \mathcal{M}$ is the pull-back map $\langle \pi^* \lambda, Z \rangle = \langle \lambda, \pi_* Z \rangle$.

$\pi^* \lambda$ is transverse: $\langle \pi^* \lambda, X \rangle = 0$ and $\mathcal{L}_X (\pi^* \lambda) = 0$

$\alpha \in T^* \mathcal{M}$ can be separated in two components, transverse to X and parallel to ξ

$$\alpha = \alpha^\perp + \frac{\langle \alpha, X \rangle}{l} \xi, \quad T^* \mathcal{M} = X^\perp \oplus \text{span} [\xi]$$

$$\Lambda_\pi^1 \mathcal{M} := \{ \alpha \in \Lambda^1 \mathcal{M} \mid \mathcal{L}_X \alpha = 0, \langle \alpha, X \rangle = 0 \}.$$

Prop. 4: $\pi^*(\Lambda^1 \mathcal{S}) = \Lambda_\pi^1 \mathcal{M}$ and $\pi^* : \Lambda^1 \mathcal{S} \longrightarrow \Lambda_\pi^1 \mathcal{M}$ is bijective.

Transverse G -preserved covariant tensors:

$$\mathcal{T}_{n\pi} \mathcal{M} := \{ T \in \mathcal{T}_n \mathcal{M} \mid T(X, \cdot) = T(\cdot, X) = \dots = 0, \mathcal{L}_X T = 0 \}$$

[4]

The quotient metric

$h := \eta - \frac{1}{l} \xi \otimes \xi$ is symmetric, transverse $\text{Rad } h = \text{Ker } \pi_* = \text{span } [X]$
and preserved by the group action, $g^* h_{gx} = h_x$.

(Because the action of G preserves both η , ξ and l .)

It can be easily proved that it exists $\underline{h} \in \mathcal{T}_2\mathcal{S}$, non-degenerate, such that $\pi^* \underline{h} = h$

Riemannian connection for \underline{h}

Let $\vec{v}, \vec{w} \in \mathcal{X}(\mathcal{S})$ and $V = \pi_*^{-1} \vec{v}$, $W = \pi_*^{-1} \vec{w} \in \mathcal{X}_\pi(\mathcal{M})$.

Although $\nabla_V W \notin \mathcal{X}_\pi(\mathcal{M})$, we have that $\mathcal{L}_X(\nabla_V W) = 0$ because,
 $\mathcal{L}_X V = \mathcal{L}_X W = 0$ and, as the G -action preserves η , then $\mathcal{L}_X \nabla = 0$

Define:

$$D_{\vec{v}} \vec{w} := \pi_* (\nabla_V W)$$

It is a connection on \mathcal{S} , which is symmetric and $D_{\vec{v}}\underline{h} = 0$, hence Riemannian.

Some useful relations:

$$\nabla_V W = \pi_*^{-1} (D_{\vec{v}} \vec{w}) + \frac{1}{2l} d\xi(V, W) X$$

$$\underline{h}(\vec{y}, \pi_* \nabla_V X) = \frac{1}{2} d\xi(V, Y), \quad \langle \xi, \nabla_V X \rangle = \frac{1}{2} \langle dl, V \rangle$$

Riemannian-Christoffel tensors



$$K(Y, Z; V, W) = \eta (Y, \nabla_V \nabla_W Z - \nabla_W \nabla_V Z - \nabla_{[V, W]} Z)$$

$$\underline{K}(\vec{y}, \vec{z}; \vec{v}, \vec{w}) = \underline{h} (\vec{y}, D_{\vec{v}} D_{\vec{w}} \vec{z} - D_{\vec{w}} D_{\vec{v}} \vec{z} - D_{[\vec{v}, \vec{w}]} \vec{z})$$

(a) For transverse Y, Z, V, W , $\vec{y} = \pi_* Y$ and so on.

$$\begin{aligned} K(Y, Z; V, W) = \underline{K}(\vec{y}, \vec{z}; \vec{v}, \vec{w}) + \frac{1}{4l} (\Theta(V, Z) \Theta(W, Y) - \\ \Theta(V, Y) \Theta(W, Z) - 2 \Theta(V, W) \Theta(Y, Z)) \end{aligned}$$

$$(b) \quad K(X, Z; V, W) = -\frac{1}{2} \nabla_V d\xi(W, Z) + \frac{1}{2} \nabla_W d\xi(V, Z) = \frac{1}{2} \nabla d\xi(Z, V, W)$$

$$(c) \quad K(X, V; X, W) = -\frac{1}{2} \nabla dl(W, V) + \frac{1}{4} l(Vf)(Wf) + \frac{1}{4} h(\Theta_V, \Theta_W)$$

where $\Theta_V := i_V \Theta$.

$$\text{Ric}(Z, W) = \underline{\text{Ric}}(\vec{z}, \vec{w}) - \frac{1}{2l} h(\Theta_Z, \Theta_W) - \frac{1}{2} \nabla df(Z, W) - \frac{1}{4} (Zf)(Wf)$$

[5]

The inverse problem

Let G be a 1-parameter Lie group acting on \mathcal{M} and let the quotient $\mathcal{S} = \mathcal{M}/G$ be a manifold with a semi-Riemannian metric \underline{h} .

Is there a non-degenerate metric η on \mathcal{M} such that $\mathcal{L}_X \eta = 0$ and having \underline{h} as the quotient metric?

It depends on the choice of $\xi \in \Lambda^1 \mathcal{M}$ such that $\langle \xi, X \rangle \neq 0$, with constant sign on \mathcal{M} , and $\mathcal{L}_X \xi = 0$. Then we take

$$\eta = \pi^* \underline{h} + \frac{1}{\langle \xi, X \rangle} \xi \otimes \xi$$

How to choose ξ ?

Since $\mathcal{L}_X \xi = 0$, $d\xi = df \wedge \xi + \Theta$, with $f := \log |\langle \xi, X \rangle|$ and $i_X \Theta = 0$

$$d^2 = 0 \quad \Rightarrow \quad \xi = e^f (du + \beta)$$

$$f \in \pi^* \Lambda^0 \mathcal{S}, \quad \beta \in \pi^* \Lambda^1 \mathcal{S}, \quad u \in \Lambda^0 \mathcal{M}, \quad |\langle du, X \rangle| = 1$$

Equations above merely give the values of Riemann-Christoffel tensor K on \mathcal{M} . ♠

However, if the output K is prescribed, then they become conditions on \underline{h} and ξ (alternatively, on \underline{h} , β and f).

These equations are solved in \mathcal{S} . Then the solutions are pulled-back to \mathcal{M} .

[6]

The flat deformation law as a PDS

γ is G -invariant,

find $\eta = a\gamma + bH$, flat and G -invariant

Find a, b and H such that $K(\eta) = 0$ on $\mathcal{U} \subset \mathcal{S}$ and then π^* pulls them back to $\pi^{-1}\mathcal{U} \subset \mathcal{M}$

X is a Killing vector for both γ and η :

$$\gamma = \pi^*p + \frac{1}{\bar{l}}\bar{\xi} \otimes \bar{\xi}, \quad \bar{\xi} := i_X\gamma, \quad \bar{l} := \langle \bar{\xi}, X \rangle = \gamma(X, X), \quad p \in \mathcal{T}_2\mathcal{S}$$

$$\eta = \pi^*\underline{h} + \frac{1}{l}\xi \otimes \xi, \quad \xi := i_X\eta, \quad l := \langle \xi, X \rangle, \quad \underline{h} \in \mathcal{T}_2\mathcal{S}$$

$K_{\alpha\beta\mu\nu} = 0$ are 20 independent equations for 6 unknowns. (Overdetermined.)

$$K_{\alpha\beta\mu\nu} \equiv L_{\alpha\beta\mu\nu} + \frac{2}{l} (L_{\alpha\beta[\mu\xi\nu]} + L_{\mu\nu[\alpha\xi\beta]}) + \frac{4}{l^2} \xi_{[\beta}L_{\alpha][\mu\xi\nu]}$$

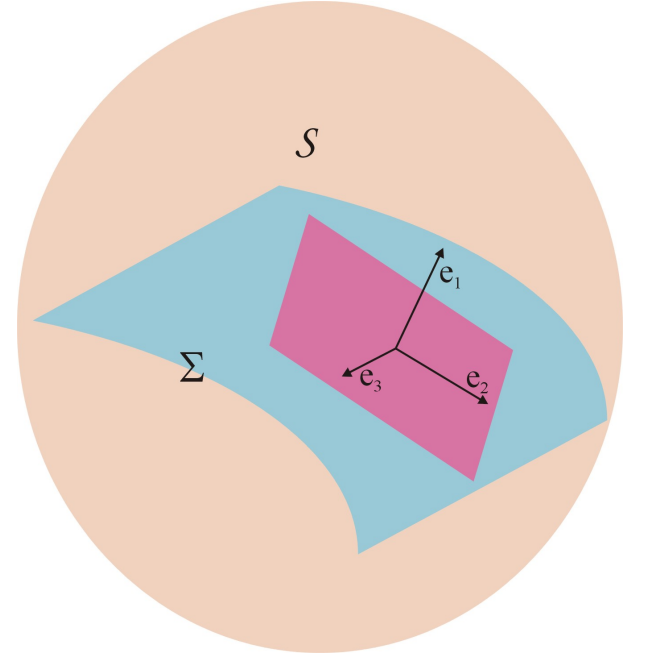
$e_0 = X$ and e_1, e_2, e_3 natural base for Gaussian normal coordinates (x^1, x^2, x^3) , $x^1 = 0$ on Σ .

$$L_{abcd} := \underline{K}_{abcd} - \frac{1}{2l} (\Theta_{ab}\Theta_{cd} + \Theta_{[ac}\Theta_{b]d})$$

$$L_{bcd} := \frac{1}{2} D_b \Theta_{cd} + \frac{1}{2} \Theta_{b[cd} f_{c]}$$

$$L_{bd} := -\frac{l}{2} \left(D_b f_d + \frac{1}{2} f_b f_d \right) - \frac{1}{4} \Theta_b^a \Theta_{ad}$$

$$L_{abcd} = 0, \quad L_{bcd} = 0, \quad L_{bd} = 0$$



Reduced PDS: $L_{11} = 0, \quad L_{11j} = 0, \quad \rho_{ij} := L_{iaj}^a - \frac{1}{2} L_{ac}^{ac} h_{ij} = 0$

Constraints (on Σ that extend to a neighbourhood by the 2nd Bianchi identity):

$$L_{aj} = 0, \quad \rho_{ij} := L_{1ab}^a - \frac{1}{2} L_{ac}^{ac} h_{1b} = 0, \quad \epsilon^{cda} L_{jcd} = 0$$

[7]

The reduced PDS

6 unknowns: a, b, H

$$\gamma = \pi^* p + \frac{1}{\bar{l}} \bar{\xi} \otimes \bar{\xi}$$

It exists a triad $\{\omega, \tau, \zeta\}$ such that $p = -s\omega \otimes \omega + \tau \otimes \tau + \zeta \otimes \zeta$ and

$$H = s (\beta \otimes \beta - \omega \otimes \omega), \quad \beta = \frac{m}{\bar{l}} \bar{\xi} - s'' \sqrt{\frac{\bar{l} - sm^2}{|\bar{l}|}} \tau$$

$m = +\sqrt{H(X, X)}$, $s = \text{sign } H(X, X)$ and $s'' = \text{sign } \bar{l}$.

New unknowns: a, b, m and the p -orthonormal triad $\{\omega, \tau, \zeta\}$

$$\partial_1^2 \omega \cong \Omega_1 \tau + \Omega_2 \zeta, \quad \partial_1^2 \tau \cong s \Omega_1 \omega + \Omega_3 \zeta, \quad \partial_1^2 \zeta \cong s \Omega_2 \omega - \Omega_3 \tau$$

$$n := \frac{ss'' b (\bar{l} - sm^2) a}{\bar{l} a + sbm^2}, \quad y := ss'' b m \sqrt{\frac{\bar{l} - sm^2}{|\bar{l}|}}$$

$$L_{11} = 0 \longrightarrow l \partial_1^2 f \cong 0$$

$$L_{11i} = 0 \longrightarrow y \left(\partial_1^2 \tau_i - \tau_i \partial_1^2 f + \tau_i \partial_1^2 \log y \right) \cong 0$$

$$\rho_{ij} = 0 \longrightarrow -\frac{1}{2} \left(\bar{h}^{11} \delta_i^k \delta_j^l + \bar{h}^{1k} \bar{h}^{1l} \underline{h}_{ij} - \bar{h}^{11} \bar{h}^{kl} \underline{h}_{ij} \right) \partial_1^2 \underline{h}_{kl} \cong 0$$

with

$$\begin{aligned} \partial_1^2 \underline{h}_{ij} \cong & \partial_1^2 (a + b) \omega_i \omega_j + \partial_1^2 (a + n) \tau_i \tau_j + \partial_1^2 a \zeta_i \zeta_j \\ & + 2s(n - b) \Omega_1 \omega_{(i} \tau_{j)} - 2sb \Omega_2 \omega_{(i} \zeta_{j)} + 2n \Omega_3 \zeta_{(i} \tau_{j)} \end{aligned}$$

To be solved for $\partial_1^2 a$, $\partial_1^2 b$, $\partial_1^2 m$ and Ω_c , $c = 1, 2, 3$.

Characteristic determinant:

$$\begin{aligned} \chi = \frac{4ss''}{|\bar{l}|} b^4 m \tau_1 \zeta_1^2 \left(-s'\bar{l} + \bar{l}\zeta_1^2 + sm^2\tau_1^2 \right) (\bar{l}a + sbm^2) \\ \left([\bar{l} - sm^2]\zeta_1^2 + s''m^2[\tau_1^2 + \zeta_1^2] \right) \left(\bar{h}^{11} \right)^3 \end{aligned}$$

[8]

Geometrical meaning of the constraints

Let η be a solution of the reduced PDS.

$$\left. \begin{aligned} K_{ijkl} &= -2\rho_1^1 h_{j[l} h_{ik]} & K_{1jkl} &= 2h_{j[l} \rho_{1k]} - 2\rho_1^1 h_{j[l} h_{1k]} & K_{0ijk} &= -2\mu^1_i \epsilon_{1jk} \\ K_{01jk} &= 2\mu^l_l \epsilon_{1jk} & K_{0j1k} &= -\mu^l_j \epsilon_{l1k} & K_{0ajk} &= L_{aj} \end{aligned} \right\}$$

The fulfilling of the constraints is equivalent to (for $\alpha, \beta, \mu, \nu \neq 1$)

$$K_{\alpha\beta\mu\nu} = 0 \quad \text{and} \quad K_{1\beta\mu\nu} = 0$$

$\mathcal{N} := \pi^{-1}\Sigma$ is a hypersurface of \mathcal{M} . $J : \mathcal{N} \rightarrow \mathcal{M}$

$\bar{\nu} = \pi^* dx^1 \in \Lambda^1 \mathcal{M}$ (recall Gaussian γ -normal coordinates) is orthogonal to \mathcal{N} .

(\mathcal{M}, η) and (\mathcal{M}, γ) are two Riemannian structures. Let n and \bar{n} be the respective unit vectors normal to \mathcal{N} , and ν and $\bar{\nu}$ the corresponding covectors, $\bar{\nu} \propto \nu$

$K_{\alpha\beta\mu\nu} = 0$ and $K_{1\beta\mu\nu} = 0$ whenever $\alpha, \beta, \mu, \nu \neq 1$ is equivalent to

$$\underline{J^*K = 0} \quad \text{and} \quad \underline{J^*(i_n K) = 0}$$

J^*K is connected to $K(\vartheta)$ and Φ (Gauss) and $J^*(i_n K)$ is connected to $\nabla\Phi$ (Codazzi-Mainardi).

A particular solution is $\Phi = 0$ and $K^{(\vartheta)} = 0$

\mathcal{N} has two couples of fundamental forms: $(\vartheta = J^*\eta, \Phi)$ and $(\varphi = J^*\gamma, \phi)$

$$\Phi(v, w) = \langle \nu, \nabla_v w \rangle \quad \text{and} \quad \phi(v, w) = \langle \bar{\nu}, \bar{\nabla}_v w \rangle, \quad v, w \in T\mathcal{N}$$

If $\underline{\Phi = 0}$, then $\phi(v, w) = -\langle \bar{\nu}, B(v, w) \rangle$, $B := \nabla - \bar{\nabla}$

which results in a condition on the normal derivatives of the unknowns:

$$\bar{\nabla}_1 \eta_{\mu\nu} = \phi_{\mu\nu} + \bar{\nabla}_{(\mu} \eta_{\nu)1}, \quad \mu, \nu \neq 1$$