

Flat deformations of a semi-Riemannian metric  
admitting a symmetry group

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[1]

## Flat deformation of a semi-Riemannian metric

### Flat deformation theorem (2005)

*Given a semi-Riemannian analytic metric,  $\gamma$ , on a manifold  $\mathcal{M}$ , it exists a 2-form  $F$  and a scalar function  $c$  such that:*

- 1. an arbitrary scalar constraint  $\Psi(c, F, x) = 0$ ,  $x \in \mathcal{M}$  is fulfilled and*
- 2. the deformed metric  $\eta := c\gamma + \epsilon M$ , is semi-Riemannian and flat*

*where  $|\epsilon| = 1$ ,  $M(V, W) = \gamma(F_V, F_W)$ ,  $F_V := i_V F$ .*

We shall limit ourselves to the case of a 4-dimensional spacetime  $(\mathcal{M}, g)$ .

**Some algebraic remarks**

Given  $F \in \Lambda^2 \mathcal{M}$ , it exists a null tetrad  $\{\mu, \nu, \kappa, \lambda\}$

such that either:

**Singular case:**

$$\underline{F = \kappa \wedge \mu}, \quad M = -\kappa \otimes \kappa$$

$$\boxed{\gamma = \frac{1}{c} \eta - \frac{\epsilon}{c} \kappa \otimes \kappa}$$

with  $\kappa$  isotropic and  $\eta$  flat (conformal Kerr-Schild metric) or

**Non-singular case:**

$$\underline{F = -B \mu \wedge \nu + E \kappa \wedge \lambda},$$

$$M = -B^2 (\mu \otimes \mu + \nu \otimes \nu) - E^2 (\kappa \otimes \lambda + \lambda \otimes \kappa)$$

$$\eta = (c - \epsilon B^2) \gamma - \epsilon (B^2 + E^2) (\kappa \otimes \lambda + \lambda \otimes \kappa)$$

$$\boxed{\eta = a\gamma + bH}$$

**Prop. 1** *Given a Lorentzian analytic metric  $\gamma$ , there exist two scalar functions,  $a$  and  $b$ , and a hyperbolic 2-plane  $H$  such that the metric*

$$\underline{\eta := a\gamma + bH} \quad \text{is Lorentzian and flat.}$$

$\eta := a\gamma - b(\kappa \otimes \lambda + \lambda \otimes \kappa)$  (Recalls a conformal Kerr-Schild transformation)

Let  $k$  and  $l$  be two vectors such that  $\kappa = \gamma(k, -)$  and  $\lambda = \gamma(l, -)$

The endomorphism  $\mathbb{H} = -k \otimes \lambda - l \otimes \kappa$  associated to  $H$  is a 2-dimensional projector on a hyperbolic 2-plane  $\mathcal{H}_x \subset T_x\mathcal{M}$

$$\mathbb{H}^2 = \mathbb{H} \quad \text{and} \quad \text{trace } \mathbb{H} = 2$$

$K := \gamma - H$  (complementary 2-plane)

$$\gamma = H + K \quad \text{and} \quad \eta = aK + (a + b)H$$

The *almost-product structure* defined by  $H$  is compatible with both,  $\gamma$  and  $\eta$ .

Assume that  $\gamma$  admits a Killing vector  $X$ ,  $\mathcal{L}_X \gamma = 0$ .

Does it exist a flat deformation law  $\eta := a\gamma + bH$  such that  $\mathcal{L}_X \eta = 0$  ?

(i.e., such that  $X$  is also a Killing vector for  $\eta$ )

This is equivalent to  $\mathcal{L}_X a = \mathcal{L}_X b = 0$ ,  $\mathcal{L}_X H = 0$

[3]

## 1-parameter symmetry group

$(\mathcal{M}, \eta)$  is a semi-Riemannian 4-manifold and  $G$  is a connected 1-parameter Lie group acting smoothly on  $\mathcal{M}$

$$\psi : G \times \mathcal{M} \longrightarrow \mathcal{M}, \quad (g, x) \longrightarrow gx .$$

leaving  $\eta$  invariant:  $\underline{g^* \eta_{gx} = \eta_x .}$

$\mathcal{S} = \{Gx, x \in \mathcal{M}\}$  is the class of all orbits and  $\pi : x \in \mathcal{M} \rightarrow Gx \in \mathcal{S}$  is the canonical projection.

We assume that  $\mathcal{S}$  is a manifold,  $\pi$  is smooth and  $\pi_* : T\mathcal{M} \rightarrow T\mathcal{S}$  jacobian map.

$$\begin{aligned} \forall x \in \mathcal{M}, \quad \psi_x : G \rightarrow \mathcal{M} & \quad \text{is smooth and } \psi_{x*} : TG \rightarrow T\mathcal{M} \\ g \rightarrow gx & \quad T_e G \rightarrow \mathcal{G}_x \subset T_x \mathcal{M} \end{aligned}$$

If  $X$  is an infinitesimal generator of the action of  $G$ ,  $\mathcal{G} = \text{span}[X]$  and

$$g_* X_x = X_{gx}, \quad \forall g \in G \quad \text{and} \quad x \in \mathcal{M}$$

[2]

## Projectable vectors and tensors

$$\xi := \eta(X, \cdot) \in \Lambda^1 \mathcal{M}$$

$$\text{Assume } l := \eta(X, X) = \langle \xi, X \rangle \neq 0$$

$$g^* \xi_{gx} = \xi_x, \forall g \in G, \quad \text{or, locally } \mathcal{L}_X \xi = 0$$

Any  $V \in T_x \mathcal{M}$  can be separated in two components that are, respectively, transverse to  $\xi$  and parallel to  $X$ :

$$T\mathcal{M} = \xi^\perp \oplus \text{span}[X], \quad V = V^\perp + \frac{\langle \xi, V \rangle}{l} X$$

### Killing equation

$$\mathcal{L}_X \eta = 0 \quad \Leftrightarrow \quad \nabla \xi \text{ skewsymmetric} \quad \boxed{\nabla \xi = \frac{1}{2} d\xi}$$

$$\mathcal{L}_X \xi = 0 \quad \Rightarrow \quad i_X (d\xi) = -d(i_X \xi) = -dl$$

$$\boxed{d\xi = df \wedge \xi + \Theta} \quad \text{where } f := \log |l| \quad \text{and } i_X \Theta = 0$$



**Def. 1:**  $Y \in \mathcal{X}(\mathcal{M})$  is projectable if

$$x, y \in \mathcal{M}, \quad \pi x = \pi y \Rightarrow \pi_* Y_x = \pi_* Y_y$$

**Prop. 2:**  $Y \in \mathcal{X}(\mathcal{M})$  is projectable if, and only if,

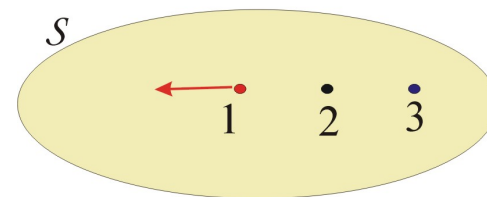
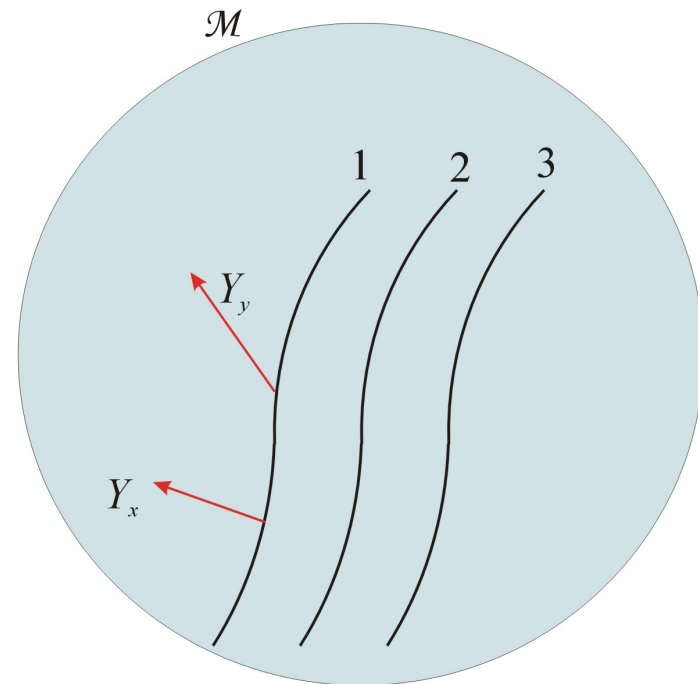
$$\pi_* (\mathcal{L}_X Y) = 0$$

For transverse vector fields

$$\pi_* (\mathcal{L}_X Y) = 0 \quad \Leftrightarrow \quad \mathcal{L}_X Y = 0$$

Class of projectable transverse vector fields

$$\mathcal{X}_\pi(\mathcal{M}) = \{Y \in \mathcal{X}(\mathcal{M}) \mid \mathcal{L}_X Y = 0, \langle \xi, Y \rangle = 0\}$$



**Prop. 3:** Let  $\vec{w} \in \mathcal{X}(\mathcal{S})$ , then:

(a) it exists a unique vector field  $W \in \mathcal{X}_\pi(\mathcal{M})$  such that  $\pi_* W = \vec{w}$ ,

(b)  $\pi_* : \mathcal{X}_\pi(\mathcal{M}) \rightarrow \mathcal{X}(\mathcal{S})$  is bijective and we write  $W = \pi_*^{-1} \vec{w}$ .

$\pi^* : T_{\pi x}^* \mathcal{S} \longrightarrow T_x^* \mathcal{M}$  is the pull-back map  $\langle \pi^* \lambda, Z \rangle = \langle \lambda, \pi_* Z \rangle$ .

$\pi^* \lambda$  is transverse:  $\langle \pi^* \lambda, X \rangle = 0$  and  $\mathcal{L}_X (\pi^* \lambda) = 0$

$\alpha \in T^* \mathcal{M}$  can be separated in two components, transverse to  $X$  and parallel to  $\xi$

$$\alpha = \alpha^\perp + \frac{\langle \alpha, X \rangle}{l} \xi, \quad T^* \mathcal{M} = X^\perp \oplus \text{span} [\xi]$$

$$\Lambda_\pi^1 \mathcal{M} := \{ \alpha \in \Lambda^1 \mathcal{M} \mid \mathcal{L}_X \alpha = 0, \langle \alpha, X \rangle = 0 \}.$$

**Prop. 4:**  $\pi^*(\Lambda^1 \mathcal{S}) = \Lambda_\pi^1 \mathcal{M}$  and  $\pi^* : \Lambda^1 \mathcal{S} \longrightarrow \Lambda_\pi^1 \mathcal{M}$  is bijective.

Transverse  $G$ -preserved covariant tensors:

$$\mathcal{T}_{n\pi} \mathcal{M} := \{ T \in \mathcal{T}_n \mathcal{M} \mid T(X, \cdot) = T(\cdot, X) = \dots = 0, \mathcal{L}_X T = 0 \}$$

[4]

## The quotient metric

$h := \eta - \frac{1}{l} \xi \otimes \xi$  is symmetric, transverse  $\text{Rad } h = \text{Ker } \pi_* = \text{span } [X]$   
and preserved by the group action,  $g^* h_{gx} = h_x$ .

(Because the action of  $G$  preserves both  $\eta$ ,  $\xi$  and  $l$ .)

It can be easily proved that it exists  $\underline{h} \in \mathcal{T}_2\mathcal{S}$ , non-degenerate, such that  $\pi^* \underline{h} = h$

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### Riemannian connection for $\underline{h}$

Let  $\vec{v}, \vec{w} \in \mathcal{X}(\mathcal{S})$  and  $V = \pi_*^{-1} \vec{v}$ ,  $W = \pi_*^{-1} \vec{w} \in \mathcal{X}_\pi(\mathcal{M})$ .

Although  $\nabla_V W \notin \mathcal{X}_\pi(\mathcal{M})$ , we have that  $\mathcal{L}_X(\nabla_V W) = 0$  because,  
 $\mathcal{L}_X V = \mathcal{L}_X W = 0$  and, as the  $G$ -action preserves  $\eta$ , then  $\mathcal{L}_X \nabla = 0$

Define:

$$D_{\vec{v}} \vec{w} := \pi_* (\nabla_V W)$$

It is a connection on  $\mathcal{S}$ , which is symmetric and  $D_{\vec{v}}\underline{h} = 0$ , hence Riemannian.

Some useful relations:

$$\nabla_V W = \pi_*^{-1} (D_{\vec{v}} \vec{w}) + \frac{1}{2l} d\xi(V, W) X$$

$$\underline{h}(\vec{y}, \pi_* \nabla_V X) = \frac{1}{2} d\xi(V, Y), \quad \langle \xi, \nabla_V X \rangle = \frac{1}{2} \langle dl, V \rangle$$

## Riemannian-Christoffel tensors



$$K(Y, Z; V, W) = \eta (Y, \nabla_V \nabla_W Z - \nabla_W \nabla_V Z - \nabla_{[V, W]} Z)$$

$$\underline{K}(\vec{y}, \vec{z}; \vec{v}, \vec{w}) = \underline{h} (\vec{y}, D_{\vec{v}} D_{\vec{w}} \vec{z} - D_{\vec{w}} D_{\vec{v}} \vec{z} - D_{[\vec{v}, \vec{w}]} \vec{z})$$

(a) For transverse  $Y, Z, V, W$ ,  $\vec{y} = \pi_* Y$  and so on.

$$K(Y, Z; V, W) = \underline{K}(\vec{y}, \vec{z}; \vec{v}, \vec{w}) + \frac{1}{4l} (\Theta(V, Z) \Theta(W, Y) - \Theta(V, Y) \Theta(W, Z) - 2 \Theta(V, W) \Theta(Y, Z))$$

$$(b) \quad K(X, Z; V, W) = -\frac{1}{2} \nabla_V d\xi(W, Z) + \frac{1}{2} \nabla_W d\xi(V, Z) = \frac{1}{2} \nabla d\xi(Z, V, W)$$

$$(c) \quad K(X, V; X, W) = -\frac{1}{2} \nabla dl(W, V) + \frac{1}{4} l(Vf)(Wf) + \frac{1}{4} h(\Theta_V, \Theta_W)$$

where  $\Theta_V := i_V \Theta$ .

$$\text{Ric}(Z, W) = \underline{\text{Ric}}(\vec{z}, \vec{w}) - \frac{1}{2l} h(\Theta_Z, \Theta_W) - \frac{1}{2} \nabla df(Z, W) - \frac{1}{4} (Zf)(Wf)$$

[5]

## The inverse problem

Let  $G$  be a 1-parameter Lie group acting on  $\mathcal{M}$  and let the quotient  $\mathcal{S} = \mathcal{M}/G$  be a manifold with a semi-Riemannian metric  $\underline{h}$ .

Is there a non-degenerate metric  $\eta$  on  $\mathcal{M}$  such that  $\mathcal{L}_X \eta = 0$  and having  $\underline{h}$  as the quotient metric?

It depends on the choice of  $\xi \in \Lambda^1 \mathcal{M}$  such that  $\langle \xi, X \rangle \neq 0$ , with constant sign on  $\mathcal{M}$ , and  $\mathcal{L}_X \xi = 0$ . Then we take

$$\eta = \pi^* \underline{h} + \frac{1}{\langle \xi, X \rangle} \xi \otimes \xi$$

**How to choose  $\xi$ ?**

Since  $\mathcal{L}_X \xi = 0$ ,  $d\xi = df \wedge \xi + \Theta$ , with  $f := \log |\langle \xi, X \rangle|$  and  $i_X \Theta = 0$

$$d^2 = 0 \quad \Rightarrow \quad \xi = e^f (du + \beta)$$

$$f \in \pi^* \Lambda^0 \mathcal{S}, \quad \beta \in \pi^* \Lambda^1 \mathcal{S}, \quad u \in \Lambda^0 \mathcal{M}, \quad |\langle du, X \rangle| = 1$$

Equations above merely give the values of Riemann-Christoffel tensor  $K$  on  $\mathcal{M}$ . ♠

However, if the output  $K$  is prescribed, then they become conditions on  $\underline{h}$  and  $\xi$  (alternatively, on  $\underline{h}$ ,  $\beta$  and  $f$ ).

These equations are solved in  $\mathcal{S}$ . Then the solutions are pulled-back to  $\mathcal{M}$ .

[6]

The flat deformation law as a PDS

$\gamma$  is  $G$ -invariant,

find  $\eta = a\gamma + bH$ , flat and  $G$ -invariant

Find  $a$ ,  $b$  and  $H$  such that  $K(\eta) = 0$  on  $\mathcal{U} \subset \mathcal{S}$  and then  $\pi^*$  pulls them back to  $\pi^{-1}\mathcal{U} \subset \mathcal{M}$

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$X$  is a Killing vector for both  $\gamma$  and  $\eta$ :

$$\gamma = \pi^*p + \frac{1}{\bar{l}}\bar{\xi} \otimes \bar{\xi}, \quad \bar{\xi} := i_X\gamma, \quad \bar{l} := \langle \bar{\xi}, X \rangle = \gamma(X, X), \quad p \in \mathcal{T}_2\mathcal{S}$$

$$\eta = \pi^*\underline{h} + \frac{1}{l}\xi \otimes \xi, \quad \xi := i_X\eta, \quad l := \langle \xi, X \rangle, \quad \underline{h} \in \mathcal{T}_2\mathcal{S}$$

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$K_{\alpha\beta\mu\nu} = 0$  are 20 independent equations for 6 unknowns. (Overdetermined.)

$$K_{\alpha\beta\mu\nu} \equiv L_{\alpha\beta\mu\nu} + \frac{2}{l} \left( L_{\alpha\beta[\mu\xi\nu]} + L_{\mu\nu[\alpha\xi\beta]} \right) + \frac{4}{l^2} \xi_{[\beta}L_{\alpha][\mu\xi\nu]}$$



$e_0 = X$  and  $e_1, e_2, e_3$  natural base for Gaussian normal coordinates  $(x^1, x^2, x^3)$ ,  $x^1 = 0$  on  $\Sigma$ .

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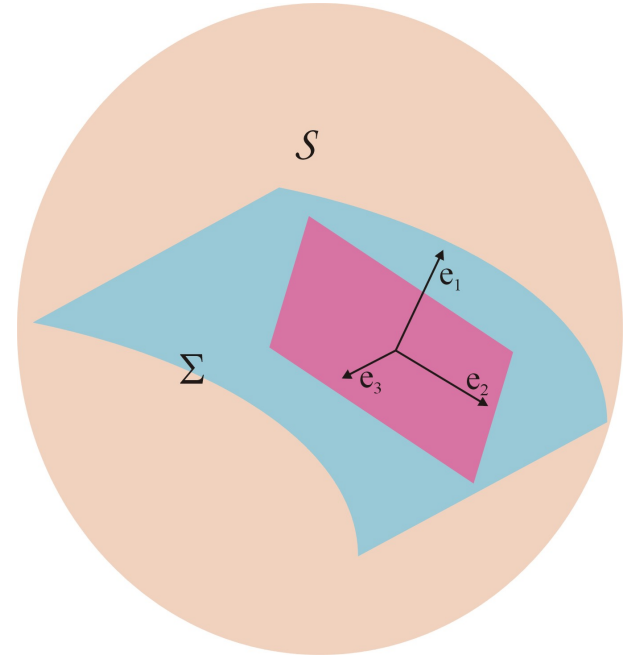
$$L_{abcd} := \underline{K}_{abcd} - \frac{1}{2l} (\Theta_{ab}\Theta_{cd} + \Theta_{[ac}\Theta_{b]d})$$

$$L_{bcd} := \frac{1}{2} D_b \Theta_{cd} + \frac{1}{2} \Theta_{b[dc]f}$$

$$L_{bd} := -\frac{l}{2} \left( D_b f_d + \frac{1}{2} f_b f_d \right) - \frac{1}{4} \Theta_b^a \Theta_{ad}$$

$$L_{abcd} = 0, \quad L_{bcd} = 0, \quad L_{bd} = 0$$


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**Reduced PDS:**  $L_{11} = 0, \quad L_{11j} = 0, \quad \rho_{ij} := L_{iaj}^a - \frac{1}{2} L_{ac}^{ac} h_{ij} = 0$

**Constraints** (on  $\Sigma$  that extend to a neighbourhood by the 2nd Bianchi identity):

$$L_{aj} = 0, \quad \rho_{ij} := L_{1ab}^a - \frac{1}{2} L_{ac}^{ac} h_{1b} = 0, \quad \epsilon^{cda} L_{jcd} = 0$$

[7]

The reduced PDS

6 unknowns:  $a, b, H$

$$\gamma = \pi^* p + \frac{1}{\bar{l}} \bar{\xi} \otimes \bar{\xi}$$

It exists a triad  $\{\omega, \tau, \zeta\}$  such that  $p = -s\omega \otimes \omega + \tau \otimes \tau + \zeta \otimes \zeta$  and

$$H = s (\beta \otimes \beta - \omega \otimes \omega), \quad \beta = \frac{m}{\bar{l}} \bar{\xi} - s'' \sqrt{\frac{\bar{l} - sm^2}{|\bar{l}|}} \tau$$

$m = +\sqrt{H(X, X)}$ ,  $s = \text{sign } H(X, X)$  and  $s'' = \text{sign } \bar{l}$ .

New unknowns:  $a, b, m$  and the  $p$ -orthonormal triad  $\{\omega, \tau, \zeta\}$

$$\partial_1^2 \omega \cong \Omega_1 \tau + \Omega_2 \zeta, \quad \partial_1^2 \tau \cong s \Omega_1 \omega + \Omega_3 \zeta, \quad \partial_1^2 \zeta \cong s \Omega_2 \omega - \Omega_3 \tau$$

$$n := \frac{ss'' b (\bar{l} - sm^2) a}{\bar{l} a + sbm^2}, \quad y := ss'' b m \sqrt{\frac{\bar{l} - sm^2}{|\bar{l}|}}$$

$$L_{11} = 0 \longrightarrow l \partial_1^2 f \cong 0$$

$$L_{11i} = 0 \longrightarrow y \left( \partial_1^2 \tau_i - \tau_i \partial_1^2 f + \tau_i \partial_1^2 \log y \right) \cong 0$$

$$\rho_{ij} = 0 \longrightarrow -\frac{1}{2} \left( \bar{h}^{11} \delta_i^k \delta_j^l + \bar{h}^{1k} \bar{h}^{1l} \underline{h}_{ij} - \bar{h}^{11} \bar{h}^{kl} \underline{h}_{ij} \right) \partial_1^2 \underline{h}_{kl} \cong 0$$

with

$$\begin{aligned} \partial_1^2 \underline{h}_{ij} \cong & \partial_1^2 (a + b) \omega_i \omega_j + \partial_1^2 (a + n) \tau_i \tau_j + \partial_1^2 a \zeta_i \zeta_j \\ & + 2s(n - b) \Omega_1 \omega_{(i} \tau_{j)} - 2sb \Omega_2 \omega_{(i} \zeta_{j)} + 2n \Omega_3 \zeta_{(i} \tau_{j)} \end{aligned}$$

To be solved for  $\partial_1^2 a$ ,  $\partial_1^2 b$ ,  $\partial_1^2 m$  and  $\Omega_c$ ,  $c = 1, 2, 3$ .

Characteristic determinant:

$$\begin{aligned} \chi = \frac{4ss''}{|\bar{l}|} b^4 m \tau_1 \zeta_1^2 \left( -s'\bar{l} + \bar{l}\zeta_1^2 + sm^2\tau_1^2 \right) (\bar{l}a + sbm^2) \\ \left( [\bar{l} - sm^2]\zeta_1^2 + s''m^2[\tau_1^2 + \zeta_1^2] \right) \left( \bar{h}^{11} \right)^3 \end{aligned}$$

[8]

## Geometrical meaning of the constraints

Let  $\eta$  be a solution of the reduced PDS.

$$\left. \begin{aligned} K_{ijkl} &= -2\rho_1^1 h_{j[l} h_{ik]} & K_{1jkl} &= 2h_{j[l} \rho_{1k]} - 2\rho_1^1 h_{j[l} h_{1k]} & K_{0ijk} &= -2\mu^1_i \epsilon_{1jk} \\ K_{01jk} &= 2\mu^l_l \epsilon_{1jk} & K_{0j1k} &= -\mu^l_j \epsilon_{l1k} & K_{0ajk} &= L_{aj} \end{aligned} \right\}$$

The fulfilling of the constraints is equivalent to (for  $\alpha, \beta, \mu, \nu \neq 1$ )

$$K_{\alpha\beta\mu\nu} = 0 \quad \text{and} \quad K_{1\beta\mu\nu} = 0$$

$\mathcal{N} := \pi^{-1}\Sigma$  is a hypersurface of  $\mathcal{M}$ .  $J : \mathcal{N} \rightarrow \mathcal{M}$

$\bar{\nu} = \pi^* dx^1 \in \Lambda^1 \mathcal{M}$  (recall Gaussian  $\gamma$ -normal coordinates) is orthogonal to  $\mathcal{N}$ .

$(\mathcal{M}, \eta)$  and  $(\mathcal{M}, \gamma)$  are two Riemannian structures. Let  $n$  and  $\bar{n}$  be the respective unit vectors normal to  $\mathcal{N}$ , and  $\nu$  and  $\bar{\nu}$  the corresponding covectors,  $\bar{\nu} \propto \nu$

$K_{\alpha\beta\mu\nu} = 0$  and  $K_{1\beta\mu\nu} = 0$  whenever  $\alpha, \beta, \mu, \nu \neq 1$  is equivalent to

$$\underline{J^*K = 0} \quad \text{and} \quad \underline{J^*(i_n K) = 0}$$

$J^*K$  is connected to  $K(\vartheta)$  and  $\Phi$  (Gauss) and  $J^*(i_n K)$  is connected to  $\nabla\Phi$  (Codazzi-Mainardi).

A particular solution is  $\Phi = 0$  and  $K^{(\vartheta)} = 0$

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$\mathcal{N}$  has two couples of fundamental forms:  $(\vartheta = J^*\eta, \Phi)$  and  $(\varphi = J^*\gamma, \phi)$

$$\Phi(v, w) = \langle \nu, \nabla_v w \rangle \quad \text{and} \quad \phi(v, w) = \langle \bar{\nu}, \bar{\nabla}_v w \rangle, \quad v, w \in T\mathcal{N}$$

If  $\underline{\Phi = 0}$ , then  $\phi(v, w) = -\langle \bar{\nu}, B(v, w) \rangle$ ,  $B := \nabla - \bar{\nabla}$

which results in a condition on the normal derivatives of the unknowns:

$$\bar{\nabla}_1 \eta_{\mu\nu} = \phi_{\mu\nu} + \bar{\nabla}_{(\mu} \eta_{\nu)1}, \quad \mu, \nu \neq 1$$