

# FORMULÁRIO

## Teoria de erros e representação de números no computador

**Erro absoluto e erro relativo:**  $(x, \tilde{x} \in \mathbb{R}, \quad x \approx \tilde{x})$

$$e_{\tilde{x}} = x - \tilde{x}, \quad \delta_{\tilde{x}} = \frac{e_{\tilde{x}}}{x}, \quad x \neq 0$$

erro absoluto :  $|e_{\tilde{x}}|$ , erro relativo :  $|\delta_{\tilde{x}}|$ ,  $x \neq 0$

**Erros de arredondamento:**  $(x = \sigma(0.a_1a_2\dots)_\beta\beta^t, \quad a_1 \neq 0; \quad \tilde{x} = fl(x) \in FP(\beta, n, t_1, t_2))$

$$|e_{\tilde{x}}| \leq \beta^{t-n}, \quad |\delta_{\tilde{x}}| \leq \beta^{1-n} := U, \quad (\text{arredondamento por corte})$$

$$|e_{\tilde{x}}| \leq \frac{1}{2}\beta^{t-n}, \quad |\delta_{\tilde{x}}| \leq \frac{1}{2}\beta^{1-n} := U, \quad (\text{arredondamento simétrico})$$

**Propagação de erros:**  $(x, \tilde{x} \in \mathbb{R}^n, \quad x \approx \tilde{x})$

$$e_{f(\tilde{x})} = f(x) - f(\tilde{x}) \approx \sum_{k=1}^n \frac{\partial f}{\partial x_k}(x) e_{\tilde{x}_k}$$

$$\delta_{f(\tilde{x})} = \frac{e_{f(\tilde{x})}}{f(x)} \approx \sum_{k=1}^n p_{f,k}(x) \delta_{\tilde{x}_k} \quad p_{f,k}(x) = \frac{x_k \frac{\partial f}{\partial x_k}(x)}{f(x)}$$

## Métodos iterativos para equações não-lineares

**Método da bissecção:**  $x_{k+1} = \frac{a_k + b_k}{2}, \quad f(a_k)f(b_k) < 0$

$$|x - x_{k+1}| \leq |x_{k+1} - x_k|, \quad |x - x_k| \leq \frac{b-a}{2^k}$$

**Método do ponto fixo:**  $x_{k+1} = g(x_k)$

$$|x - x_{k+1}| \leq \frac{L}{1-L} |x_{k+1} - x_k|,$$

$$|x - x_k| \leq L^k |x - x_0|, \quad |x - x_k| \leq \frac{L^k}{1-L} |x_1 - x_0|$$

**Método de Newton:**  $x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$

$$x - x_{k+1} = -\frac{f''(\xi_k)}{2f'(x_k)}(x - x_k)^2, \quad \text{com } \xi_k \text{ entre } z \text{ e } x_k$$

$$|x - x_k| \leq \frac{1}{\mathbb{K}} (\mathbb{K}|x - x_0|)^{2^k}$$

**Método da secante:**  $x_{k+1} = x_k - f(x_k) \frac{x_k - x_{k-1}}{f(x_k) - f(x_{k-1})}$

$$x - x_{k+1} = -\frac{f''(\xi_k)}{2f'(\eta_k)}(x - x_k)(x - x_{k-1}), \text{ com } \xi_k, \eta_k \text{ num intervalo que contém } z, x_k \text{ e } x_{k-1}$$

$$|x - x_{k+1}| \leq \mathbb{K} |x - x_k| |x - x_{k-1}|, \quad \mathbb{K} = \frac{\max |f''|}{2 \min |f'}}$$

## Normas e Condicionamento

$$\|\mathbf{A}\|_\infty = \max_{1 \leq i \leq n} \sum_{j=1}^n |a_{ij}|$$

$$\text{cond}(\mathbf{A}) = \|\mathbf{A}\| \|\mathbf{A}^{-1}\|$$

$$\|\mathbf{A}\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^n |a_{ij}|$$

$$\|\delta_{\mathbf{x}}\| \leq \frac{\text{cond}(\mathbf{A})}{1 - \text{cond}(\mathbf{A}) \|\delta_{\mathbf{A}}\|} (\|\delta_{\mathbf{A}}\| + \|\delta_{\mathbf{b}}\|), \text{ sistema } \mathbf{Ax} = \mathbf{b}$$

$$\|\mathbf{A}\|_2 = (\rho(\mathbf{A}^T \mathbf{A}))^{1/2}$$

## Métodos iterativos para sistemas lineares

$$\mathbf{Ax} = \mathbf{b} \Leftrightarrow \mathbf{x} = \mathbf{Cx} + \mathbf{d} \quad \rightarrow \quad \mathbf{x}^{(k+1)} = \mathbf{Cx}^{(k)} + \mathbf{d}$$

$$\|\mathbf{x} - \mathbf{x}^{(k)}\| \leq \|\mathbf{C}\|^k \|\mathbf{x} - \mathbf{x}^{(0)}\|, \quad \|\mathbf{x} - \mathbf{x}^{(k)}\| \leq \frac{\|\mathbf{C}\|^k}{1 - \|\mathbf{C}\|} \|\mathbf{x}^{(1)} - \mathbf{x}^{(0)}\|$$

$$\|\mathbf{x} - \mathbf{x}^{(k+1)}\| \leq \frac{\|\mathbf{C}\|}{1 - \|\mathbf{C}\|} \|\mathbf{x}^{(k+1)} - \mathbf{x}^{(k)}\|$$

Método de Jacobi:  $\mathbf{C} = -\mathbf{D}^{-1}(\mathbf{L} + \mathbf{U}) \quad x_i^{(k+1)} = (b_i - \sum_{j=1, j \neq i}^n a_{ij} x_j^{(k)}) / a_{ii}$

Método de Gauss-Seidel:

$$\mathbf{C} = -(\mathbf{L} + \mathbf{D})^{-1} \mathbf{U}$$

$$x_i^{(k+1)} = (b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k+1)} - \sum_{j=i+1}^n a_{ij} x_j^{(k)}) / a_{ii}$$

## Método de Newton para sistemas não-lineares

$$\mathbf{J}(\mathbf{x}^{(k)}) \Delta \mathbf{x}^{(k)} = -\mathbf{f}(\mathbf{x}^{(k)}) \quad \mathbf{x}^{(k+1)} = \mathbf{x}^{(k)} + \Delta \mathbf{x}^{(k)}$$