Master in Mathematics and Applications - Técnico, Lisbon Numerical Functional Analysis and Optimization - Fall Semester 2016

Midterm Exam - November 10th, 2016 - Solutions

1. Show that

$$\langle x, y \rangle := x_1 y_1 + 2 x_1 y_2 + 2 x_2 y_1 + 5 x_2 y_2, \qquad x = (x_1, x_2), \ y = (y_1, y_2),$$

defines an inner product on \mathbb{R}^2 . (Hint: Express $\langle x, y \rangle$ as $x^T A y$ with some $A \in \mathbb{R}^{2 \times 2}$.) [1.5] Solution: We can write

$$x_1y_1 + 2x_1y_2 + 2x_2y_1 + 5x_2y_2 = x^T \begin{bmatrix} 1 & 2 \\ 2 & 5 \end{bmatrix} y =: x^T A y = (x, A y),$$

where (\cdot, \cdot) is the usual inner product in \mathbb{R}^2 . The eigenvalues, $\lambda_1 = 3 - 2\sqrt{2}$ and $\lambda_2 = 3 - 2\sqrt{2}$, of matrix A are both positive. The matrix A is thus symmetric and positive definite. Therefore

$$\langle x, x \rangle > 0 \ \forall x \in \mathbb{R}^2 \setminus \{0\}, \quad \text{and} \quad \langle x, x \rangle = 0 \quad \Leftrightarrow \quad x = 0$$

The other inner product properties for $\langle \cdot, \cdot \rangle$ follow from the properties of the standard Eucldean inner product (\cdot, \cdot) .

2. Let V be a Hilbert space equipped with the inner product (\cdot, \cdot) . Let $a \in V, a \neq 0$ be given and consider the functional $f: V \to \mathbb{R}$ defined through f(u) = (u, a)(u, u). Show that f is Fréchet differentiable at $u \in V$ and determine the Fréchet derivative f'(u). Compute also f''(u). [2.0]

<u>Solution</u>: Note first that both inner products, (u, a) and (u, u), are twice continuously differentiable as continuous bilinear forms from $V \times V$ to \mathbb{R} and well defined since $a, u \in V$. We have

$$f(u+h) - f(u) = (u+h,a)(u+h,u+h) - (u,a)(u,u)$$
$$= (h,a)(u,u) + 2(u,a)(h,u) + (u,a)(h,h) + 2(h,a)(h,u) + (h,a)(h,h)$$

where we have used the symmetry of the inner product (\cdot, \cdot) . Defining

$$T(u)h := (h, a)(u, u) + 2(u, a)(h, u),$$

we see that

$$|f(u+h) - f(u) - T(u)h| \le 3||a|| ||u|| ||h||^2 + ||a|| ||h||^3 = \mathcal{O}(||h|||^2) = o(||h||)$$

where $||u|| = \sqrt{(u, u)}$ and where we have used the Cauchy-Schwarz inequality. The operator T(u): $V \to \mathbf{R}$ thus coincides with the (unique) Fréchet derivative of f at u, i.e.

$$f'(u)h = (h, a)(u, u) + 2(u, a)(h, u).$$

Moreover

$$f'(u+k)h - f'(u)h = (h,a)(u+k,u+k) + 2(u+k,a)(h,u+k) - (h,a)(u,u) - 2(u,a)(h,u)$$
$$= 2(h,a)(k,u) + 2(k,a)(h,u) + 2(u,a)(h,k) + 2(k,a)(h,k) + (h,a)(k,k),$$

where

$$2(k,a)(h,k) + (h,a)(k,k) = \mathcal{O}(||k||^2) = o(||k||) .$$

It thus follows that the symmetric bilinear operator $f''(u):V\times V\to \mathbb{R}$ defined by

$$f''(u)hk = 2(h, a)(k, u) + 2(k, a)(h, u) + 2(u, a)(h, k) + 2$$

is the second-order Fréchet derivative of f at u.

3. Consider the initial value problem

$$\begin{cases} u''(t) = -u'(t) \sin u(t) + t, & 0 < t < 1, \\ u(0) = \alpha, & u'(0) = \beta, \end{cases}$$
(1)

where $\alpha, \beta \in \mathbb{R}$.

a) Show that the initial value problem (1) can be written in the form u = T(u), where

$$T(u)(t) = \int_0^t \cos u(s) \, ds + (\beta - \cos \alpha) \, t + \alpha + \frac{t^3}{6} \,, \qquad 0 \le t < 1 \,. \tag{1.5}$$

<u>Solution</u>: Integrating the differential equation from 0 to t, we get

$$u'(t) = u'(0) - \int_0^t u'(s) \sin u(s) \, ds + \frac{t^2}{2} = \beta + \cos u(t) - \cos \alpha + \frac{t^2}{2} \, .$$

Integrating again from 0 to t, we have

$$u(t) = u(0) + \beta t + \int_0^t \cos u(s) \, ds - t \, \cos \alpha + \frac{t^3}{6} = \int_0^t \cos u(s) \, ds + (\beta - \cos \alpha)t + \alpha + \frac{t^3}{6} \, ,$$

which shows that u = T(u).

b) Let V = C[0,1] and choose $\alpha = \beta = 0$. Show that the operator $T: V \to V$ admits a unique fixed point $u \in V$. [1.5]

<u>Solution</u>: With $\alpha = \beta = 0$ we have the integral equation

$$u(t) = \int_0^t \cos u(s) \, ds + \frac{t^3}{6} - t \, .$$

Defining

$$T(u)(t) = \int_0^t \cos u(s) \, ds + \frac{t^3}{6} - t \,, \qquad 0 \le t \le 1 \,,$$

we obtain

$$\begin{aligned} |T(u)(t) - T(v)(t)| &= \left| \int_0^t (\cos u(s) - \cos v(s)) \, ds \right| \le \int_0^t |\cos u(s) - \cos v(s)| \, ds \\ &\le \max_{\xi \in \mathbb{R}} |\sin \xi| \int_0^t |u(s) - v(s)| \, ds = \int_0^t |u(s) - v(s)| \, ds \le t \, ||u - v||_V, \quad \forall t \in [0, 1], \\ |T^2(u)(t) - T^2(v)(t)| \le \int_0^t |T(u)(s) - T(v)(s)| \, ds \le \int_0^t s \, ds \, ||u - v||_V = \frac{t^2}{2} \, ||u - v||_V, \quad \forall t \in [0, 1], \end{aligned}$$

where $||u||_V = \max_{t \in [0,1]} |u(t)|$. Hence,

$$|T^{2}(u)(t) - T^{2}(v)(t)| \leq \frac{1}{2} ||u - v||_{V} \quad \forall t \in [0, 1] \quad \Rightarrow \quad ||T^{2}(u) - T^{2}(v)||_{V} \leq \frac{1}{2} ||u - v||_{V},$$

that is, T^2 is a contraction in V and thus admits a unique fixed point $u \in V$. Moreover, if $S = T^2$, it holds

$$u = \lim_{k \to \infty} S^k(u) = \lim_{k \to \infty} S^k(T(u)) = \lim_{k \to \infty} T(S^k(u)) = \lim_{k \to \infty} T(u) = T(u)$$

so $u \in V$ is also the unique fixed point of T.

c) Approximate the solution of the nonlinear Volterra integral equation u = T(u) by Newton's method. Consider $\alpha = \beta = 0$, $u_0(t) = 0$ and compute the first iterate $u_1(t)$. [1.5]

Solution: Newton's method, applied to the nonlinear equation F(u) = u - T(u), reads as

$$F'(u_n)\Delta u_n = -F(u_n) \qquad \Leftrightarrow \Delta u_n(t) - \int_0^t \sin u_n(s) \,\Delta u_n(s) \,ds = -u_n(t) + \int_0^t \cos u_n(s) \,ds + \frac{t^3}{6} - t \,, \qquad n = 0, 1, \dots \,,$$

where $\Delta u_n(t) = u_{n+1}(t) - u_n(t)$. Choosing $u_0(t) = 0$, we obtain

$$\Delta u_0(t) = \int_0^t ds + \frac{t^3}{6} - t = \frac{t^3}{6} \qquad \Rightarrow \qquad u_1(t) = \frac{t^3}{6}$$

4. Consider a Broyden's type update for the inverse of the matrix A_k :

$$A_{k+1}^{-1} = A_k^{-1} + \frac{(s_k - A_k^{-1} y_k) s_k^T A_k^{-1}}{s_k^T A_k^{-1} y_k}, \quad k = 0, 1, \dots$$

Can we say that

$$\|A_{k+1}^{-1} - A_k^{-1}\|_2 \leq \|B^{-1} - A_k^{-1}\|_2,$$

for all nonsingular $B \in Q(y_k, s_k) = \{B \in \mathbb{R}^{N \times N} | Bs_k = y_k\}$? Justify your answer. You may assume that $s_k^T A_k^{-1} y_k \neq 0$. [2.0]

<u>Solution</u>: Given that $s_k = B^{-1}y_k$, we obtain

$$A_{k+1}^{-1} - A_k^{-1} = \frac{(s_k - A_k^{-1} y_k) s_k^T A_k^{-1}}{s_k^T A_k^{-1} y_k} = \left(B^{-1} - A_k^{-1}\right) \frac{y_k s_k^T A_k^{-1}}{s_k^T A_k^{-1} y_k}.$$

However, the matrix A_{k+1}^{-1} does not necessarily solve the minimization problem since, although

$$\|A_{k+1}^{-1} - A_k^{-1}\|_2 \le \|B^{-1} - A_k^{-1}\|_2 \left\| \frac{y_k s_k^T A_k^{-1}}{s_k^T A_k^{-1} y_k} \right\|,$$

where $\|\cdot\|$ can be either the Frobenius or the matrix 2-norm, we have

$$\left\|\frac{xy^T}{x^Ty}\right\|_F = \left\|\frac{xy^T}{x^Ty}\right\|_2 = \frac{\|x\|_2 \|y\|_2}{x^Ty} \ge 1 \qquad \forall x, y \in \mathbb{R} \setminus \{0\},$$

and the equality holds if and only if $x \parallel y$.

The so called "bad" Broyden's method which uses an approximation of the inverse of the Jacobian matrix is formulated as

$$A_{k+1}^{-1} = A_k^{-1} + \frac{(s_k - A_k^{-1} y_k) y_k}{y_k^T y_k}.$$

In this case, we do have

$$\|A_{k+1}^{-1} - A_k^{-1}\|_2 \leq \|B^{-1} - A_k^{-1}\|_2,$$

for all nonsingular $B \in Q(y_k, s_k) = \{B \in \mathbb{R}^{N \times N} | Bs_k = y_k\}$ but, as can be shown using Sherman-Morrison formula, this corresponds to a different update formula for A_k , namely

$$A_{k+1} = A_k + \frac{(y_k - A_k s_k) y_k^T A_k}{y_k^T A_k s_k}.$$