

# Geometric Mechanics

## Homework 3

Due on October 12

1. Prove that there exists a linear isomorphism  $\Omega : \mathfrak{so}(3) \rightarrow \mathbb{R}^3$  such that

$$A\xi = \Omega(A) \times \xi$$

for all  $\xi \in \mathbb{R}^3$  and  $A \in \mathfrak{so}(3)$ . Show that moreover

$$\Omega([A, B]) = \Omega(A) \times \Omega(B)$$

for all  $A, B \in \mathfrak{so}(3)$  (that is,  $\Omega$  is a Lie algebra isomorphism between  $\mathfrak{so}(3)$  and  $(\mathbb{R}^3, \times)$ ).

2. A general rigid body is any mechanical system of the form  $(\mathbb{R}^3 \times SO(3), \langle\langle\langle\cdot, \cdot\rangle\rangle\rangle, \mathcal{F})$ , with

$$\langle\langle\langle(v, V), (w, W)\rangle\rangle\rangle := \int_{\mathbb{R}^3} \langle v + V\xi, w + W\xi \rangle dm$$

for all  $(v, V), (w, W) \in T_{(x, S)}\mathbb{R}^3 \times SO(3)$  and  $(x, S) \in \mathbb{R}^3 \times SO(3)$ , where  $\langle\cdot, \cdot\rangle$  is the usual Euclidean inner product on  $\mathbb{R}^3$  and  $m$  is a positive finite measure on  $\mathbb{R}^3$  not supported on any straight line and satisfying  $\int_{\mathbb{R}^3} \|\xi\|^2 dm < +\infty$ . We further assume

$$\int_{\mathbb{R}^3} \xi dm = 0,$$

that is, the center of mass of the reference configuration is placed at the origin.

- (a) Show that the kinetic energy of the rigid body is

$$K(v, V) = \frac{1}{2}M\langle v, v \rangle + \frac{1}{2}\langle\langle V, V \rangle\rangle,$$

where  $M = m(\mathbb{R}^3)$  is the total mass of the rigid body and  $\langle\langle\cdot, \cdot\rangle\rangle$  is the metric for the rigid body with a fixed point determined by  $m$ .

- (b) The motion of a rigid body falling in a constant gravitational field  $-ge_z$  is determined by the conservative force given by the potential energy

$$U(x, S) = \int_{\mathbb{R}^3} V(x + S\xi) dm,$$

where  $V : \mathbb{R}^3 \rightarrow \mathbb{R}$  is the function  $V(x) = \langle x, ge_z \rangle$  (called the gravitational potential). Show that

$$U(x, S) = Mg\langle x, e_z \rangle,$$

and use this to argue that the projection of any motion on  $SO(3)$  is a geodesic of  $(SO(3), \langle\langle\cdot, \cdot\rangle\rangle)$ . Would this still be true for a non-constant gravitational field (i.e. for a non-linear gravitational potential)?

- (c) Compute the motion of the rigid body's center of mass (i.e. the projection of the motion on  $\mathbb{R}^3$ ).