

# REPRESENTATIONS OF $SU(3)$ AND QUARKS

João Santos

IST - Department of Mathematics  
Algebraic and Geometric Methods in Engineering and Physics  
Prof. José Natário

February 2021

# INDEX

- ▶ Symmetries in Quantum Mechanics
- ▶ SU(3) flavour symmetry
- ▶ Representations of  $\mathfrak{sl}_3(\mathbb{C})$ 
  - The adjoint representation **8**
  - The fundamental representation (**3**) and its dual ( $\bar{\mathbf{3}}$ )
  - The representation **6**
  - The representation **10**
- ▶ Quarks and representations of  $\mathfrak{sl}_3(\mathbb{C})$
- ▶ References

# FROM CLASSICAL TO QUANTUM MECHANICS

- ▶ In Classical Mechanics, **symmetries** are related to **conserved quantities** by Noether's theorem;

# FROM CLASSICAL TO QUANTUM MECHANICS

- ▶ In Classical Mechanics, **symmetries** are related to **conserved quantities** by Noether's theorem;
- ▶ In Quantum Mechanics:

# FROM CLASSICAL TO QUANTUM MECHANICS

- ▶ In Classical Mechanics, **symmetries** are related to **conserved quantities** by Noether's theorem;
- ▶ In Quantum Mechanics:
  - **Particles** - states  $|\psi\rangle$  in a complex Hilbert space;

$$\langle\psi|\psi\rangle = 1 \quad , \quad i\frac{\partial}{\partial t}|\psi\rangle = \hat{H}|\psi\rangle$$

## FROM CLASSICAL TO QUANTUM MECHANICS

- ▶ In Classical Mechanics, **symmetries** are related to **conserved quantities** by Noether's theorem;
- ▶ In Quantum Mechanics:
  - **Particles** - states  $|\psi\rangle$  in a complex Hilbert space;

$$\langle\psi|\psi\rangle = 1 \quad , \quad i\frac{\partial}{\partial t}|\psi\rangle = \hat{H}|\psi\rangle$$

- **Observables** - hermitian operators  $\hat{A} = \hat{A}^\dagger$  ;

$$\langle\hat{A}\rangle = \langle\psi|\hat{A}|\psi\rangle \quad , \quad \frac{d}{dt}\langle\hat{A}\rangle = i\langle[\hat{H}, \hat{A}]\rangle$$

► Symmetry operator

$$\implies \text{Invariance } |\psi\rangle \rightarrow |\psi'\rangle = \hat{U} |\psi\rangle$$

► Symmetry operator

⇒ Invariance  $|\psi\rangle \rightarrow |\psi'\rangle = \hat{U} |\psi\rangle$

⇒ constraints on  $\hat{U}$



► Symmetry operator

⇒ Invariance  $|\psi\rangle \rightarrow |\psi'\rangle = \hat{U} |\psi\rangle$

⇒ constraints on  $\hat{U}$

- Normalization  $\langle\psi'|\psi'\rangle = \langle\psi|\psi\rangle = 1 \implies \hat{U}^\dagger \hat{U} = \mathbf{1}$

► Symmetry operator

⇒ Invariance  $|\psi\rangle \rightarrow |\psi'\rangle = \hat{U} |\psi\rangle$

⇒ constraints on  $\hat{U}$

- Normalization  $\langle\psi'|\psi'\rangle = \langle\psi|\psi\rangle = 1 \implies \hat{U}^\dagger \hat{U} = \mathbf{1}$
- Preserve system eigenvalues  $[\hat{H}, \hat{U}] = 0$

► Symmetry operator

$$\implies \text{Invariance } |\psi\rangle \rightarrow |\psi'\rangle = \hat{U} |\psi\rangle$$

$$\implies \text{constraints on } \hat{U}$$

- Normalization  $\langle \psi' | \psi' \rangle = \langle \psi | \psi \rangle = 1 \implies \hat{U}^\dagger \hat{U} = \mathbf{1}$

- Preserve system eigenvalues  $[\hat{H}, \hat{U}] = 0$

►  $|\psi\rangle \in \mathbb{C}^n \implies \mathbf{U} \in \mathbf{SU}(n) \implies U = e^V$  ,  $V \in \mathfrak{su}_n$

► Symmetry operator

$$\implies \text{Invariance } |\psi\rangle \rightarrow |\psi'\rangle = \hat{U} |\psi\rangle$$

$$\implies \text{constraints on } \hat{U}$$

- Normalization  $\langle \psi' | \psi' \rangle = \langle \psi | \psi \rangle = 1 \implies \hat{U}^\dagger \hat{U} = \mathbf{1}$
- Preserve system eigenvalues  $[\hat{H}, \hat{U}] = 0$

$$\text{► } |\psi\rangle \in \mathbb{C}^n \implies \mathbf{U} \in \mathbf{SU}(n) \implies U = e^V \quad , \quad V \in \mathfrak{su}_n$$

$$\mathfrak{su}_n = \{V \in \text{Mat}_n(\mathbb{C}) : V^\dagger = -V, \text{tr}(V) = 0\}$$

$$V = \sum_{j=1}^{n^2-1} \alpha_j B_j = \sum_{j=1}^{n^2-1} \alpha_j (i\tilde{B}_j) = i\alpha \cdot \tilde{B} \quad , \quad \tilde{B}_j^\dagger = \tilde{B}_j$$

► Symmetry operator

$$\implies \text{Invariance } |\psi\rangle \rightarrow |\psi'\rangle = \hat{U} |\psi\rangle$$

$$\implies \text{constraints on } \hat{U}$$

- Normalization  $\langle \psi' | \psi' \rangle = \langle \psi | \psi \rangle = 1 \implies \hat{U}^\dagger \hat{U} = \mathbf{1}$
- Preserve system eigenvalues  $[\hat{H}, \hat{U}] = 0$

$$\text{► } |\psi\rangle \in \mathbb{C}^n \implies \mathbf{U} \in \mathbf{SU}(n) \implies U = e^V, \quad V \in \mathfrak{su}_n$$

$$\mathfrak{su}_n = \{V \in \text{Mat}_n(\mathbb{C}) : V^\dagger = -V, \text{tr}(V) = 0\}$$

$$V = \sum_{j=1}^{n^2-1} \alpha_j B_j = \sum_{j=1}^{n^2-1} \alpha_j (i\tilde{B}_j) = i\alpha \cdot \tilde{B}, \quad \tilde{B}_j^\dagger = \tilde{B}_j$$

$$\text{► } [\hat{H}, U] = 0 \implies [\hat{H}, \tilde{B}_j] = 0$$

▶ Symmetry operator

$$\implies \text{Invariance } |\psi\rangle \rightarrow |\psi'\rangle = \hat{U} |\psi\rangle$$

$$\implies \text{constraints on } \hat{U}$$

- Normalization  $\langle \psi' | \psi' \rangle = \langle \psi | \psi \rangle = 1 \implies \hat{U}^\dagger \hat{U} = \mathbf{1}$
- Preserve system eigenvalues  $[\hat{H}, \hat{U}] = 0$

$$\text{▶ } |\psi\rangle \in \mathbb{C}^n \implies \mathbf{U} \in \mathbf{SU}(n) \implies U = e^V, \quad V \in \mathfrak{su}_n$$

$$\mathfrak{su}_n = \{V \in \text{Mat}_n(\mathbb{C}) : V^\dagger = -V, \text{tr}(V) = 0\}$$

$$V = \sum_{j=1}^{n^2-1} \alpha_j B_j = \sum_{j=1}^{n^2-1} \alpha_j (i\tilde{B}_j) = i\alpha \cdot \tilde{B}, \quad \tilde{B}_j^\dagger = \tilde{B}_j$$

$$\text{▶ } [\hat{H}, U] = 0 \implies [\hat{H}, \tilde{B}_j] = 0 \longrightarrow \tilde{B}_j \text{ are } \mathbf{observables} \text{ and } \mathbf{conserved} \\ \mathbf{quantities.}$$

## MOTIVATION

► **Heisenberg** -  $m_p \approx m_n$  ,  $V_{pp} \approx V_{pn} \approx V_{nn}$

$$p = \begin{pmatrix} 1 \\ 0 \end{pmatrix} , \quad n = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

## MOTIVATION

- ▶ **Heisenberg** -  $m_p \approx m_n$  ,  $V_{pp} \approx V_{pn} \approx V_{nn}$

$$p = \begin{pmatrix} 1 \\ 0 \end{pmatrix} , \quad n = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

- ▶ Extension to **Quarks** -  $\hat{H} = \hat{H}_{kyn} + \hat{H}_{strong} + \hat{H}_{em}$



# MOTIVATION

- ▶ **Heisenberg** -  $m_p \approx m_n$  ,  $V_{pp} \approx V_{pn} \approx V_{nn}$

$$p = \begin{pmatrix} 1 \\ 0 \end{pmatrix} , \quad n = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

- ▶ Extension to **Quarks** -  $\hat{H} = \hat{H}_{kyn} + \hat{H}_{strong} + \hat{H}_{em}$
- First SU(2) symmetry for up ( $u$ ) and down ( $d$ ) quarks

## MOTIVATION

- **Heisenberg** -  $m_p \approx m_n$  ,  $V_{pp} \approx V_{pn} \approx V_{nn}$

$$p = \begin{pmatrix} 1 \\ 0 \end{pmatrix} , \quad n = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

- Extension to **Quarks** -  $\hat{H} = \hat{H}_{kyn} + \hat{H}_{strong} + \hat{H}_{em}$
- First SU(2) symmetry for up ( $u$ ) and down ( $d$ ) quarks
  - Later extended to SU(3) with introduction of strange ( $s$ ) quark

$$u = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} , \quad d = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} , \quad s = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$|\psi\rangle = \begin{pmatrix} u \\ d \\ s \end{pmatrix} \rightarrow |\psi'\rangle = \begin{pmatrix} u' \\ d' \\ s' \end{pmatrix} = U \begin{pmatrix} u \\ d \\ s \end{pmatrix} \quad , \quad U \in SU(3)$$

$$|\psi\rangle = \begin{pmatrix} u \\ d \\ s \end{pmatrix} \rightarrow |\psi'\rangle = \begin{pmatrix} u' \\ d' \\ s' \end{pmatrix} = U \begin{pmatrix} u \\ d \\ s \end{pmatrix}, \quad U \in SU(3)$$

► **Physics choice** -  $U = e^{i\alpha \cdot T}$ ,  $\alpha \in \mathbb{R}^8$ ,  $T_i = \frac{1}{2}\lambda_i$

•  $\lambda_i$  - **Gell-Mann matrices**:

$$\lambda_1 = \begin{pmatrix} 0 & 1 & \\ 1 & 0 & \\ & & 0 \end{pmatrix} \quad \lambda_2 = \begin{pmatrix} 0 & -i & \\ i & 0 & \\ & & 0 \end{pmatrix} \quad \lambda_3 = \begin{pmatrix} 1 & & \\ & -1 & \\ & & 0 \end{pmatrix}$$

$$\lambda_4 = \begin{pmatrix} 0 & & 1 \\ & 0 & \\ 1 & & 0 \end{pmatrix} \quad \lambda_5 = \begin{pmatrix} 0 & & -i \\ & 0 & \\ i & & 0 \end{pmatrix} \quad \lambda_6 = \begin{pmatrix} 0 & & \\ & 0 & 1 \\ & 1 & 0 \end{pmatrix}$$

$$\lambda_7 = \begin{pmatrix} 0 & & \\ & 0 & -i \\ & i & 0 \end{pmatrix} \quad \lambda_8 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 & & \\ & 1 & \\ & & -2 \end{pmatrix}$$

# SU(3) FLAVOUR STATES

▶ 8 generators of SU(3)  $\implies$

# SU(3) FLAVOUR STATES

- ▶ 8 generators of SU(3)  $\implies$   
8 conserved quantities -  
basis of eigenvectors.

# SU(3) FLAVOUR STATES

- ▶ 8 generators of SU(3)  $\implies$   
8 conserved quantities -  
basis of eigenvectors.
- ▶ Mutually commuting operators:

# SU(3) FLAVOUR STATES

- ▶ 8 generators of SU(3)  $\implies$   
8 conserved quantities -  
basis of eigenvectors.
- ▶ Mutually commuting operators:
  - 3<sup>rd</sup> component of **isospin** -  
 $I_3 = T_3 = \frac{1}{2}\lambda_3$



# SU(3) FLAVOUR STATES

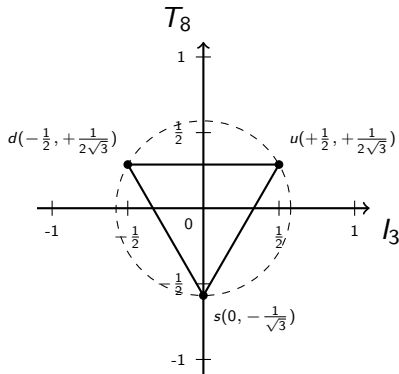
- ▶ 8 generators of SU(3)  $\implies$   
8 conserved quantities -  
basis of eigenvectors.
- ▶ Mutually commuting operators:
  - 3<sup>rd</sup> component of **isospin** -  
 $I_3 = T_3 = \frac{1}{2}\lambda_3$
  - Flavour **hypercharge** -  
 $Y = \frac{2}{\sqrt{3}}T_8 = \frac{1}{\sqrt{3}}\lambda_8$

# SU(3) FLAVOUR STATES

- ▶ 8 generators of SU(3)  $\implies$   
8 conserved quantities -  
basis of eigenvectors.
- ▶ Mutually commuting operators:
  - 3<sup>rd</sup> component of **isospin** -  
 $I_3 = T_3 = \frac{1}{2}\lambda_3$
  - Flavour **hypercharge** -  
 $Y = \frac{2}{\sqrt{3}}T_8 = \frac{1}{\sqrt{3}}\lambda_8$
- ▶ Gell-Mann-Nishijima formula :  
 $Q = I_3 + \frac{Y}{2}$

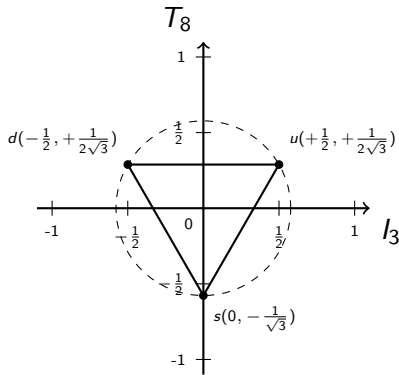
# SU(3) FLAVOUR STATES

- ▶ 8 generators of SU(3)  $\implies$   
8 conserved quantities -  
basis of eigenvectors.
- ▶ Mutually commuting operators:
  - 3<sup>rd</sup> component of **isospin** -  
 $I_3 = T_3 = \frac{1}{2}\lambda_3$
  - Flavour **hypercharge** -  
 $Y = \frac{2}{\sqrt{3}} T_8 = \frac{1}{\sqrt{3}}\lambda_8$
- ▶ Gell-Mann-Nishijima formula :  
 $Q = I_3 + \frac{Y}{2}$



# SU(3) FLAVOUR STATES

- ▶ 8 generators of SU(3)  $\implies$   
8 conserved quantities -  
basis of eigenvectors.
- ▶ Mutually commuting operators:
  - 3<sup>rd</sup> component of **isospin** -  
 $I_3 = T_3 = \frac{1}{2}\lambda_3$
  - Flavour **hypercharge** -  
 $Y = \frac{2}{\sqrt{3}}T_8 = \frac{1}{\sqrt{3}}\lambda_8$
- ▶ Gell-Mann-Nishijima formula :  
 $Q = I_3 + \frac{Y}{2}$



We now focus on the study of **representations of  $\mathfrak{sl}_3(\mathbb{C})$**

# $\mathfrak{sl}_3(\mathbb{C})$ AND ITS CARTAN SUBLALGEBRA $\mathfrak{h}$

- ▶  $\mathfrak{sl}_3(\mathbb{C}) = \{A \in \text{Mat}_{3 \times 3}(\mathbb{C}) : \text{tr}(A) = 0\}$
- ▶ Basis for  $\mathfrak{sl}_3(\mathbb{C}) \rightarrow \{H_1, H_2, E_{12}, E_{13}, E_{23}, E_{21}, E_{31}, E_{32}\}$

# $\mathfrak{sl}_3(\mathbb{C})$ AND ITS CARTAN SUBLALGEBRA $\mathfrak{h}$

- ▶  $\mathfrak{sl}_3(\mathbb{C}) = \{A \in Mat_{3 \times 3}(\mathbb{C}) : tr(A) = 0\}$
- ▶ Basis for  $\mathfrak{sl}_3(\mathbb{C}) \rightarrow \{H_1, H_2, E_{12}, E_{13}, E_{23}, E_{21}, E_{31}, E_{32}\}$

- ▶ **Adjoint representation :**

$$ad : \mathfrak{sl}_3(\mathbb{C}) \rightarrow L(\mathfrak{sl}_3(\mathbb{C}))$$

$$X \mapsto ad_X$$

$$ad_X(Y) = [X, Y]$$

# $\mathfrak{sl}_3(\mathbb{C})$ AND ITS CARTAN SUBLALGEBRA $\mathfrak{h}$

- ▶  $\mathfrak{sl}_3(\mathbb{C}) = \{A \in \text{Mat}_{3 \times 3}(\mathbb{C}) : \text{tr}(A) = 0\}$
- ▶ Basis for  $\mathfrak{sl}_3(\mathbb{C}) \rightarrow \{H_1, H_2, E_{12}, E_{13}, E_{23}, E_{21}, E_{31}, E_{32}\}$

$$ad : \mathfrak{sl}_3(\mathbb{C}) \rightarrow L(\mathfrak{sl}_3(\mathbb{C}))$$

- ▶ **Adjoint representation :**

$$X \mapsto ad_X$$

$$ad_X(Y) = [X, Y]$$

- ▶ Basis for  $\mathfrak{h} \rightarrow \{H_1, H_2\}$

$$H_1 = \begin{pmatrix} 1 & & \\ & -1 & \\ & & 0 \end{pmatrix} \quad H_2 = \begin{pmatrix} 0 & & \\ & 1 & \\ & & -1 \end{pmatrix}$$

$$[H, E_{ij}] = \alpha_{ij}(H)E_{ij} \quad , \quad i, j = 1, 2, 3 \quad i \neq j \quad , \quad \forall H \in \mathfrak{h}$$

- ▶ Define **linear map**  $\lambda_i \in \mathfrak{h}^*$  returns element in  $i^{th}$  line  $i = 1, 2, 3$ .



- ▶ Define **linear map**  $\lambda_i \in \mathfrak{h}^*$  returns element in  $i^{\text{th}}$  line  $i = 1, 2, 3$ .
- ▶ **Roots** of  $\mathfrak{sl}_3(\mathbb{C}) \rightarrow \alpha_{ij} = \lambda_i - \lambda_j$

- ▶ Define **linear map**  $\lambda_i \in \mathfrak{h}^*$  returns element in  $i^{\text{th}}$  line  $i = 1, 2, 3$ .
- ▶ **Roots** of  $\mathfrak{sl}_3(\mathbb{C}) \rightarrow \alpha_{ij} = \lambda_i - \lambda_j$
- ▶ Alternative basis for  $\mathfrak{h} \rightarrow \{I_3, Y\}$  and  $\{I_3, T_8\}$

$$I_3 = \frac{1}{2}H_1 \quad , \quad Y = \frac{1}{3}(H_1 + 2H_2) \quad , \quad T_8 = \frac{\sqrt{3}}{2}Y$$

- ▶ Define **linear map**  $\lambda_i \in \mathfrak{h}^*$  returns element in  $i^{\text{th}}$  line  $i = 1, 2, 3$ .
- ▶ **Roots** of  $\mathfrak{sl}_3(\mathbb{C}) \rightarrow \alpha_{ij} = \lambda_i - \lambda_j$
- ▶ Alternative basis for  $\mathfrak{h} \rightarrow \{I_3, Y\}$  and  $\{I_3, T_8\}$

$$I_3 = \frac{1}{2}H_1 \quad , \quad Y = \frac{1}{3}(H_1 + 2H_2) \quad , \quad T_8 = \frac{\sqrt{3}}{2}Y$$

root	$(H_1, H_2)$	$(I_3, Y)$	$(I_3, T_8)$
$\alpha_{12}$	$(2, -1)$	$(1, 0)$	$(1, 0)$
$\alpha_{13}$	$(1, 1)$	$(\frac{1}{2}, 1)$	$(\frac{1}{2}, \frac{\sqrt{3}}{2})$
$\alpha_{23}$	$(-1, 2)$	$(-\frac{1}{2}, 1)$	$(-\frac{1}{2}, \frac{\sqrt{3}}{2})$
$\alpha_{21}$	$(-2, 1)$	$(-1, 0)$	$(-1, 0)$
$\alpha_{31}$	$(-1, -1)$	$(-\frac{1}{2}, -1)$	$(-\frac{1}{2}, -\frac{\sqrt{3}}{2})$
$\alpha_{32}$	$(1, -2)$	$(\frac{1}{2}, -1)$	$(\frac{1}{2}, -\frac{\sqrt{3}}{2})$

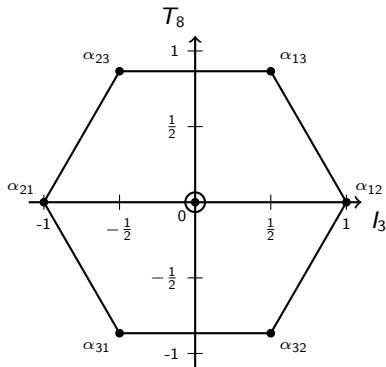
## Representation 8

- ▶ Define **linear map**  $\lambda_i \in \mathfrak{h}^*$  returns element in  $i^{\text{th}}$  line  $i = 1, 2, 3$ .
- ▶ **Roots** of  $\mathfrak{sl}_3(\mathbb{C}) \rightarrow \alpha_{ij} = \lambda_i - \lambda_j$
- ▶ Alternative basis for  $\mathfrak{h} \rightarrow \{I_3, Y\}$  and  $\{I_3, T_8\}$

$$I_3 = \frac{1}{2}H_1 \quad , \quad Y = \frac{1}{3}(H_1 + 2H_2) \quad , \quad T_8 = \frac{\sqrt{3}}{2}Y$$

root	$(H_1, H_2)$	$(I_3, Y)$	$(I_3, T_8)$
$\alpha_{12}$	$(2, -1)$	$(1, 0)$	$(1, 0)$
$\alpha_{13}$	$(1, 1)$	$(\frac{1}{2}, 1)$	$(\frac{1}{2}, \frac{\sqrt{3}}{2})$
$\alpha_{23}$	$(-1, 2)$	$(-\frac{1}{2}, 1)$	$(-\frac{1}{2}, \frac{\sqrt{3}}{2})$
$\alpha_{21}$	$(-2, 1)$	$(-1, 0)$	$(-1, 0)$
$\alpha_{31}$	$(-1, -1)$	$(-\frac{1}{2}, -1)$	$(-\frac{1}{2}, -\frac{\sqrt{3}}{2})$
$\alpha_{32}$	$(1, -2)$	$(\frac{1}{2}, -1)$	$(\frac{1}{2}, -\frac{\sqrt{3}}{2})$

Representation 8



## FUNDAMENTAL WEIGHTS

► Cartan matrix  $A$

$$A = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$$

## FUNDAMENTAL WEIGHTS

- ▶ Cartan matrix  $A$
- ▶ Fundamental weights:  $\theta_1$  and  $\theta_2$

$$A = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$$

$$\alpha_{12} = 2\theta_1 - \theta_2 \quad , \quad \alpha_{23} = -\theta_1 + 2\theta_2$$

$$\theta_1 = \lambda_1 \quad , \quad \theta_2 = -\lambda_3$$

$$\theta_i(H_j) = \delta_{ij} \quad , \quad i, j = 1, 2$$

## FUNDAMENTAL WEIGHTS

- ▶ Cartan matrix  $A$
- ▶ Fundamental weights:  $\theta_1$  and  $\theta_2$

$$A = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$$

$$\alpha_{12} = 2\theta_1 - \theta_2 \quad , \quad \alpha_{23} = -\theta_1 + 2\theta_2$$

$$\theta_1 = \lambda_1 \quad , \quad \theta_2 = -\lambda_3$$

$$\theta_i(H_j) = \delta_{ij} \quad , \quad i, j = 1, 2$$

- ▶ Weight lattice :  $\Lambda^w = \text{span}_{\mathbb{Z}}\{\theta_1, \theta_2\} \subset \mathfrak{h}^*$

# HIGHEST WEIGHT REPRESENTATIONS

- ▶ Every representation is completely reducible



# HIGHEST WEIGHT REPRESENTATIONS

- ▶ Every representation is completely reducible
- ▶ Every irrep  $(V, \pi)$  :
  - $\pi(H)$  simultaneously diagonalizable for  $V = \bigoplus_{w \in \Lambda^w} V_w$

$$\pi(H)v_1 = w_1(H)v_1 \quad , \quad v_1 \in V_{w_1} \quad w_1 \in \Lambda^w \subset \mathfrak{h}^*$$

# HIGHEST WEIGHT REPRESENTATIONS

- ▶ Every representation is completely reducible
- ▶ Every irrep  $(V, \pi)$  :

- $\pi(H)$  simultaneously diagonalizable for  $V = \bigoplus_{w \in \Lambda^w} V_w$

$$\pi(H)v_1 = w_1(H)v_1 \quad , \quad v_1 \in V_{w_1} \quad w_1 \in \Lambda^w \subset \mathfrak{h}^*$$

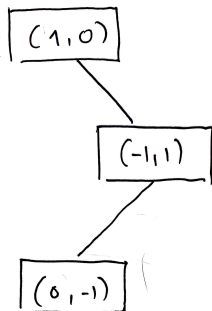
- $\pi$  is dominant weight representation
  1. Name highest weight;
  2. Obtain all other weights using the method studied in this course.

# FUNDAMENTAL REPRESENTATION

- ▶ Representation with **highest weight**  $w_{max} = \theta_1 = \lambda_1$

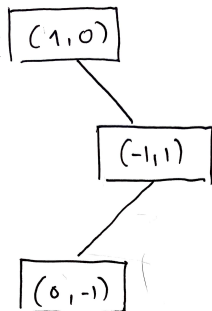
## FUNDAMENTAL REPRESENTATION

- Representation with **highest weight**  $w_{max} = \theta_1 = \lambda_1$

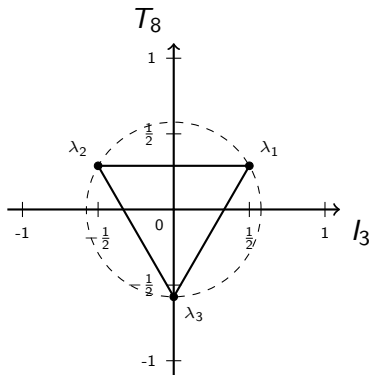


# FUNDAMENTAL REPRESENTATION

- Representation with **highest weight**  $w_{max} = \theta_1 = \lambda_1$



Representation 3

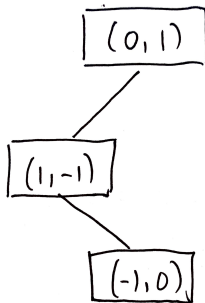


# DUAL OF THE FUNDAMENTAL REPRESENTATION

- ▶ Representation with **highest weight**  $w_{max} = \theta_2 = -\lambda_3$

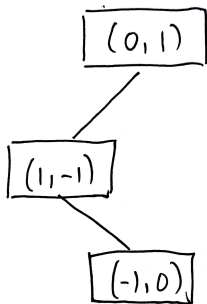
# DUAL OF THE FUNDAMENTAL REPRESENTATION

- ▶ Representation with **highest weight**  $w_{max} = \theta_2 = -\lambda_3$

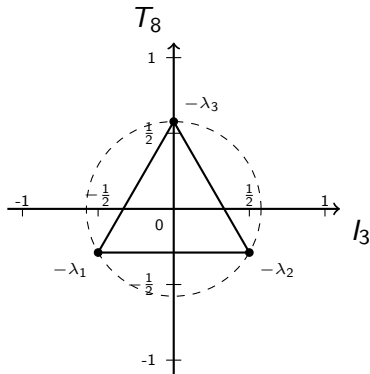


# DUAL OF THE FUNDAMENTAL REPRESENTATION

- Representation with **highest weight**  $w_{max} = \theta_2 = -\lambda_3$



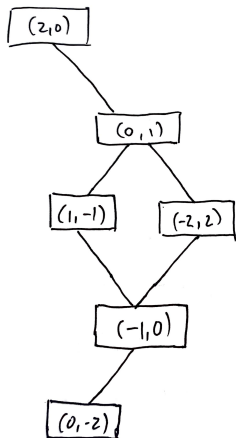
Representation  $\bar{\mathbf{3}}$



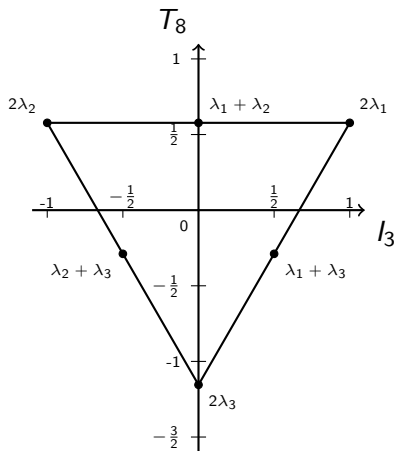
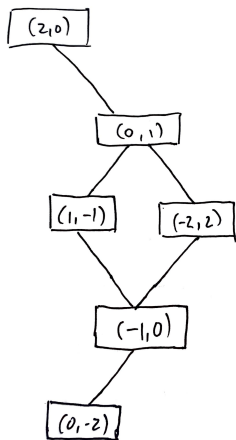


- ▶ Representation with **highest weight**  $w_{max} = 2\theta_1$

- Representation with **highest weight**  $w_{max} = 2\theta_1$



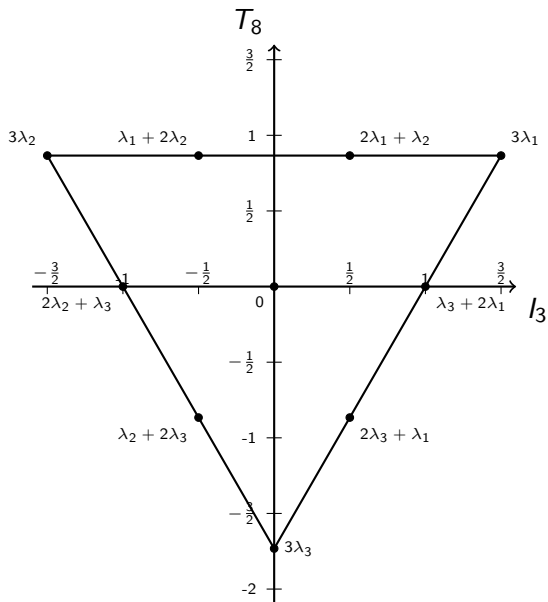
- Representation with **highest weight**  $w_{max} = 2\theta_1$



Representation 6

- ▶ Representation with **highest weight**

$$w_{max} = 3\theta_1$$



- Representation with **highest weight**  
 $w_{max} = 3\theta_1$   
 Representation **10**

# COMBINING QUARKS AND ANTIQUARKS

- ▶ States of multiple quarks - What is their flavour content?

# COMBINING QUARKS AND ANTIQUARKS

- ▶ States of multiple quarks - What is their flavour content?

## Proposition

If  $v_1$  is a weight vector of a representation  $R_1$  of  $\mathfrak{sl}_3(\mathbb{C})$  for a weight  $w_1$  and  $v_2$  is a weight vector of a representation  $R_2$  of  $\mathfrak{sl}_3(\mathbb{C})$  for a weight  $w_2$ , then  $v_1 \otimes v_2$  is a weight vector of  $R_1 \otimes R_2$  for the weight  $w_1 + w_2$ .

$$\begin{aligned}
 R_i(H)v_i &= w_i(H)v_i \quad , \quad i = 1, 2 \\
 (R_1 \otimes R_2)(H)(v_1 \otimes v_2) &= (w_1 + w_2)(H)(v_1 \otimes v_2)
 \end{aligned}$$

# COMBINING HILBERT SPACES

- ▶ System composed of **two parts**, each living in different Hilbert spaces  $\mathcal{V}$  and  $\mathcal{W}$ :

$$\mathcal{V} \otimes \mathcal{W}$$



# COMBINING HILBERT SPACES

- ▶ System composed of **two parts**, each living in different Hilbert spaces  $\mathcal{V}$  and  $\mathcal{W}$ :

$$\mathcal{V} \otimes \mathcal{W}$$

## EXAMPLE

**Two** particles in 1D box  $[0, 1]$

# COMBINING HILBERT SPACES

- ▶ System composed of **two parts**, each living in different Hilbert spaces  $\mathcal{V}$  and  $\mathcal{W}$ :

$$\mathcal{V} \otimes \mathcal{W}$$

## EXAMPLE

**Two** particles in 1D box  $[0, 1]$

$$\psi_{1,2} \in L^2([0, 1])$$

# COMBINING HILBERT SPACES

- ▶ System composed of **two parts**, each living in different Hilbert spaces  $\mathcal{V}$  and  $\mathcal{W}$ :

$$\mathcal{V} \otimes \mathcal{W}$$

## EXAMPLE

**Two** particles in 1D box  $[0, 1]$

$$\psi_{1,2} \in L^2([0, 1])$$

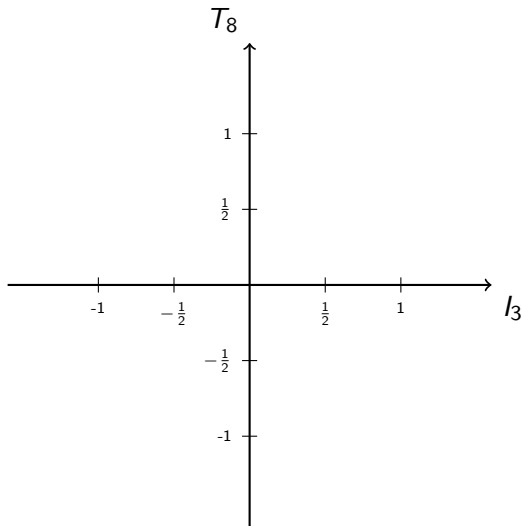
$$\psi \in L^2([0, 1] \times [0, 1]) \cong L^2([0, 1]) \otimes L^2([0, 1]) \rightarrow \psi = \psi_1 \otimes \psi_2$$

# LIGHT MESONS

Combining a quark ( $\mathbf{3}$ ) and  
an antiquark ( $\bar{\mathbf{3}}$ )

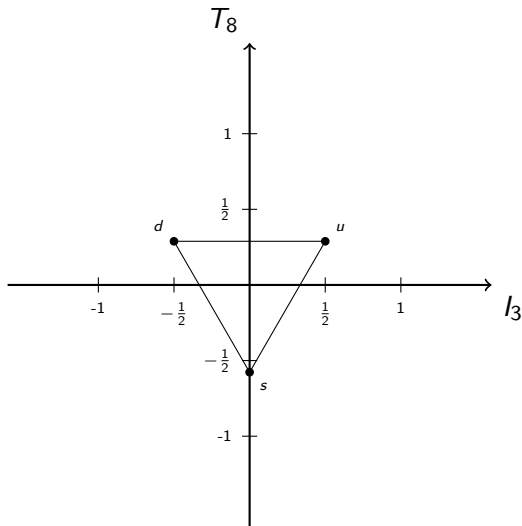
## LIGHT MESONS

Combining a quark ( $\mathbf{3}$ ) and  
an antiquark ( $\bar{\mathbf{3}}$ )



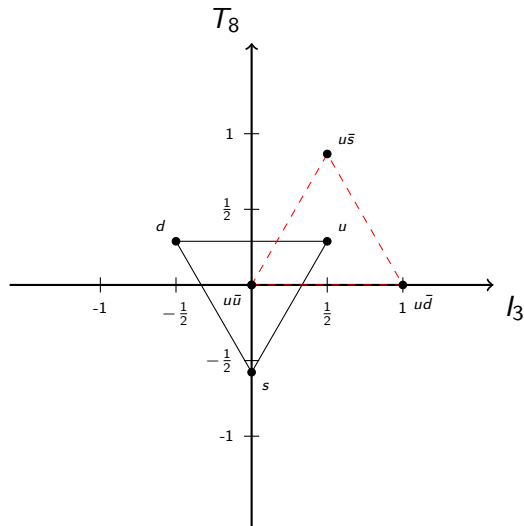
## LIGHT MESONS

Combining a quark ( $\mathbf{3}$ ) and  
an antiquark ( $\bar{\mathbf{3}}$ )



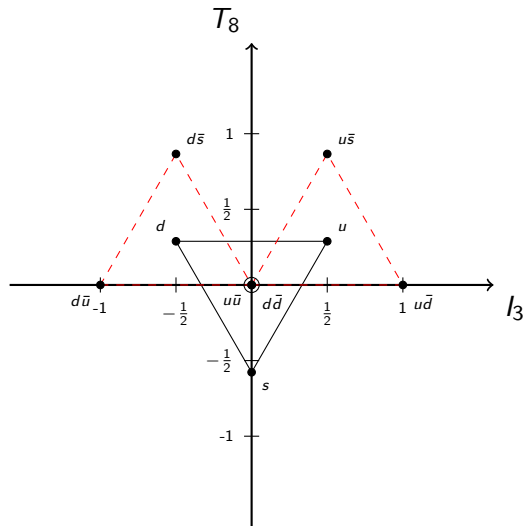
## LIGHT MESONS

Combining a quark ( $\mathbf{3}$ ) and  
an antiquark ( $\bar{\mathbf{3}}$ )



# LIGHT MESONS

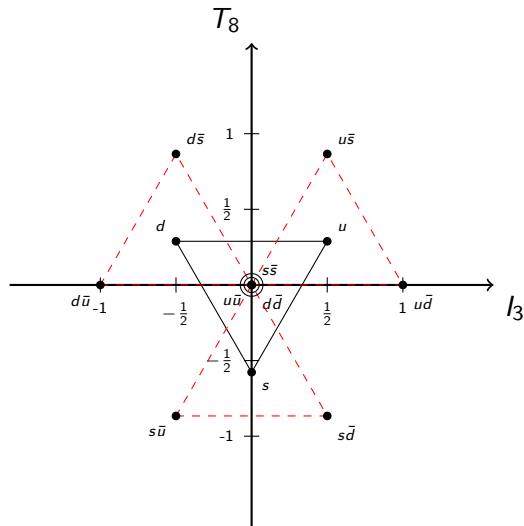
Combining a quark ( $\mathbf{3}$ ) and an antiquark ( $\bar{\mathbf{3}}$ )





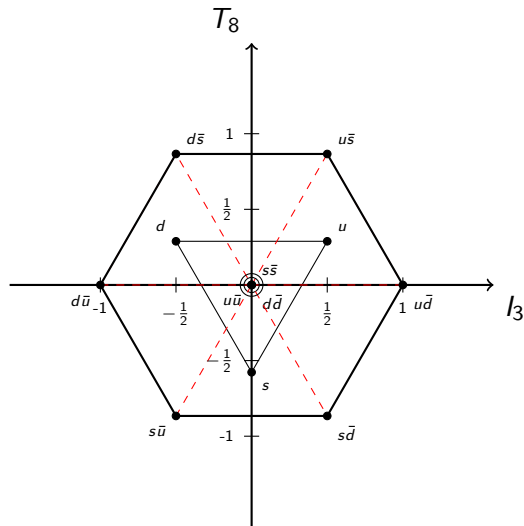
# LIGHT MESONS

Combining a quark ( $\mathbf{3}$ ) and an antiquark ( $\bar{\mathbf{3}}$ )



# LIGHT MESONS

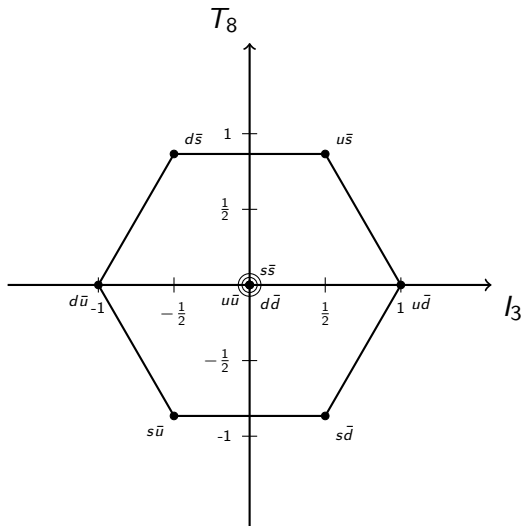
Combining a quark ( $\mathbf{3}$ ) and an antiquark ( $\bar{\mathbf{3}}$ )



## LIGHT MESONS

Combining a quark ( $\mathbf{3}$ ) and  
an antiquark ( $\bar{\mathbf{3}}$ )

$$\mathbf{3} \otimes \bar{\mathbf{3}} = \mathbf{8} \oplus \mathbf{1}$$



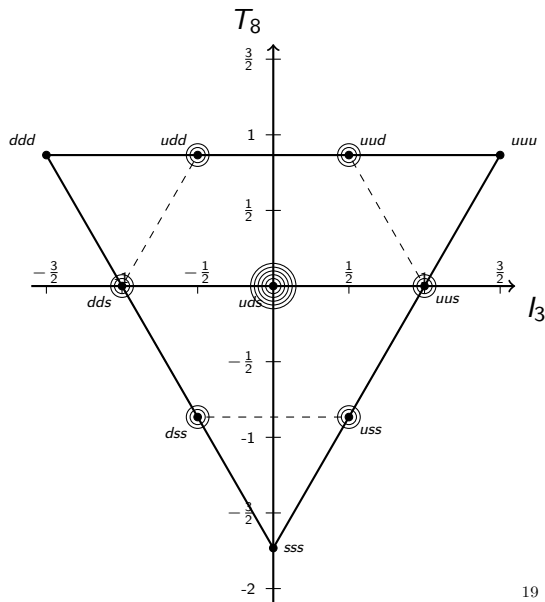
# UDS BARYONS

Combining three quarks (**3**):

## UDS BARYONS

Combining three quarks (**3**):

$$\begin{aligned} & \mathbf{3} \otimes \mathbf{3} \otimes \mathbf{3} \\ &= \mathbf{3} \otimes (\mathbf{6} \oplus \bar{\mathbf{3}}) \\ &= \mathbf{10} \oplus \mathbf{8} \oplus \mathbf{8} \oplus \mathbf{1} \end{aligned}$$



## REFERENCES

- ▶ Baez, John, and Huerta, John. 2010, *The Algebra of Grand Unified Theories*.
- ▶ Koerber, Cristopher, 2013, *Lie Algebra Representation Theory -  $SU(3)$ - Representations in Physics*. North Carolina State University
- ▶ Kosmann-Schwarzbach, Yvette. 2009. *Groups and Symmetries: From Finite Groups to Lie Groups*. Springer.
- ▶ Sakurai, J.J., and Napolitano, Jim . 1985. *Modern Quantum Mechanics*. Pearson.
- ▶ Thomson, Mark. 2013. *Modern Particle Physics*. Cambridge University Press.
- ▶ Lecture notes