

# Shapes of Spaces II

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Homology: a practical approach  
Summer School, Lisbon, July 2017<sup>1</sup>

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

<sup>1</sup>Nothing of what follows is due to me. See the list of references

Last lecture we saw that something called *homology* efficiently translated questions about shapes of spaces that otherwise seemed hard to answer into easy linear algebra.<sup>2</sup>

Today we look at it from a practical angle:

can homology tell us something about real data sets, and how can we calculate it?

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<sup>2</sup>Shout if I forget to digress on fusion reactors and Dan's talk    

How can one extract information about the *shape* underlying data?

## Carlsson's list <sup>3</sup>

- 1 Coordinates are not natural (enter geometry)
- 2 Metrics are not theoretically justified (enter topology)
- 3 Qualitative information needed (enter alg. topology)
- 4 Summaries are more valuable than individual parameter choices (enter functoriality)

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<sup>3</sup>This list could equally well advocate what statisticians call “cluster analysis” - which in some ways is the zero dimensional version of the below.

# Example: natural images (pictures!)

Digital pictures must be compressed.

Low contrast areas are uninteresting.

What do the high contrast  $3 \times 3$  patches of natural images look like?

Simplify to look at gray scale images – so that we're in  $\mathbb{R}^D$  <sup>4</sup>

The distribution is not uniform: there's a region of vastly higher density than the rest. We need to understand this region. <sup>5</sup>

How can we capture the *shape* of this region?

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<sup>4</sup>really discrete. . .

<sup>5</sup>compare w. linear regression. However, here we're not approximating with lines, but some other spaces – like ( $\simeq$  to) circles, spheres. . . – capable of expressing the data better.

## Example: the Čech complex of a point cloud

$$V = \{v_0, \dots, v_N\} \subseteq \mathbb{R}^d$$

Given  $r \geq 0$ .

A subset  $\sigma = \{v_{i_0}, \dots, v_{i_k}\} \subseteq V$  is a ( $k$ -dimensional) *face/simplex* in the Čech complex  $\check{C}(r)$  iff  $\sigma$  is contained in a closed ball of radius  $r$

The Čech complex  $\check{C}(r)$  is something called a<sup>6</sup> *simplicial complex* for which computing the homology is just linear algebra.

An important feature is that  $r$  can be varied, displaying the *persistent* shapes of the cloud.

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<sup>6</sup>insert “n abstract” if you want to

**Example: the Vietoris-Rips complex** of a point cloud


Given  $r \geq 0$ . Draw a

- 1 line between each pair of points (in the cloud) at most  $2r$  apart,
- 2 triangle (filled) between each triple of points at most  $2r$  apart
- 3 tetrahedron (filled) for each quadruple of points at most  $2r$  apart. . .

The result is the *Vietoris-Rips complex*<sup>7</sup> which is something called a *simplicial complex* for which computing the homology is just linear algebra.

An important feature is that  $r$  can be varied, displaying the *persistent* shapes of the cloud.

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<sup>7</sup> $VR(r)$  or  $VR(2r)$  depending on source 

# Simplicial complexes

A (finite, ordered) *simplicial complex* is a (finite, ordered) set

$$V = \{v_0, \dots, v_N\}$$

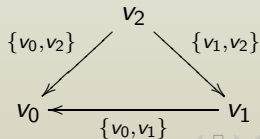
together with a set  $F$  of nonempty subsets (called faces or simplices) of  $V$ , having the properties that

- if  $\sigma \in F$  and  $\tau$  is a subset of  $\sigma$ , then  $\tau \in F$ .
- $\{v_i\} \in F$  for all  $i = 0, \dots, N$

The *dimension* of a face  $\sigma \in F$  is  $\dim \sigma = \#\sigma - 1$  (so that  $\dim\{v_3\} = 0$ )

**Example 1:** The **standard two-simplex**  $\Delta^2 = (V, F)$  with  $V = \{v_0, v_1, v_2\}$ ,  $F$  all nonempty subsets.

**Example 2:** Its boundary,  $\Sigma^1 = (V, F)$  with  $V = \{v_0, v_1, v_2\}$ ,  $F$  all *proper* subsets ( $V \notin F$ )



# Realization of $(V, F)$ , $V = \{v_0, \dots, v_N\}$

The *realization* of a face  $\sigma = \{v_{i_0}, \dots, v_{i_k}\} \in F$  is the convex hull of the unit vectors  $\{e_{i_0}, \dots, e_{i_k}\}$  in  $\mathbb{R}^{N+1}$ .

The *realization* of the simplicial complex  $(V, F)$  in  $\mathbb{R}^N$  is the union of the realization of its faces.

## Examples

1: The realization of  $\Delta^2$  is a 2-simplex: a filled triangle (and so  $\simeq$  a 2-disc).

2 The realization of  $\Sigma^1$  is a triangle (and so  $\simeq$  a circle).

*convex hull* of  $v_0, \dots, v_n$ : the set of all linear combinations  $a_0 v_0 + \dots + a_n v_n$  with the  $a_i$  non-negative reals and  $\sum a_i = 1$   
– it is a “ $k$ -simplex”.

Note: we index the coordinates of  $\mathbb{R}^{N+1}$  starting with zero.

*Standard unit vectors:*

$e_0 = (1, 0, \dots, 0), \dots, e_N = (0, \dots, 0, 1)$



# The chain complex, $(C_*K, \partial)$ , for $K = (V, F)$

Let  $C_nK$  be the vector space of all linear combinations

$$a_0\sigma_0 + \cdots + a_k\sigma_k \text{ with } a_i \in \mathbb{F} \text{ and } \sigma_i \in F \text{ of dimension } n$$

Given  $\sigma = \{v_{i_0}, \dots, v_{i_n}\}$  (with  $i_0 < i_1 < \dots < i_n$ ) let its *boundary* be

$$\begin{aligned} \partial_n\sigma = & \{\widehat{v_{i_0}}, v_{i_1}, \dots, v_{i_n}\} - \{v_{i_0}, \widehat{v_{i_1}}, \dots, v_{i_n}\} + \\ & \cdots + (-1)^n \{v_{i_0}, \dots, v_{i_{n-1}}, \widehat{v_{i_n}}\} \end{aligned}$$

Let  $\partial_n: C_nK \rightarrow C_{n-1}K$  be the resulting linear map.

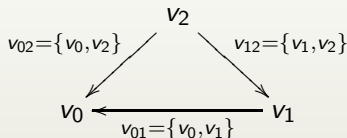
$\mathbb{F}$  is a “field”: think of  $\mathbb{F} = \mathbb{R}$  or  
 $\mathbb{F} = \mathbb{F}_2 = \{0, 1\}$ .

Notation:  $(v_0, \widehat{v_1}, v_2) = (v_0, v_2)$ , so that  
 $\partial_2(v_0, v_1, v_2) = (v_1, v_2) - (v_0, v_2) + (v_0, v_1)$ .

# Example, $\Sigma^1$

$\Sigma^1 = (V, F)$  with  $V = \{v_0, v_1, v_2\}$ ,  $F$  all *proper* subsets.

$\Sigma^1 =$  boundary of triangle:



$\dim C_0 K = 3$ ,  $\dim C_1 K = 3$ ,  $\dim C_2 K = 0 \dots$

- $C_0 K$ : basis  $(v_0, v_1, v_2)$ ,
- $C_1 K$ : basis  $(v_{12}, v_{02}, v_{01})$ ,
- $\partial_1 v_{ij} = v_j - v_i$ .

In these bases, the matrix for  $\partial_1$  is

$$[\partial_1] = \begin{bmatrix} 0 & -1 & -1 \\ -1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

Note that  $\partial_1(v_{12} - v_{02} + v_{01}) = 0$ ; we have a “cycle”.

Simplify: write  
 $v_1$  for  $\{v_1\}$  and  
 $v_{12}$  for  $\{v_1, v_2\}$

# Homology: that which counts

- $Z_n K = \ker \partial_n$  is the subspace of *cycles*  
**only cycles should count**: that  $\partial_n v = 0$  measures that  $v$  “wraps up” possibly capturing a “hole”.
- $B_n K = \text{im } \partial_{n+1}$  is the subspace of *boundaries*  
**boundaries should not count**, that  $v = \partial_{n+1} z$  means that the hole is *filled* by  $z$  (there *is* no hole!).

We define the  $n$ th *homology* as **that which counts**:

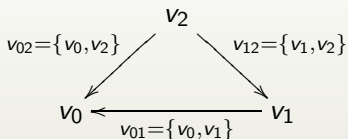
$$\begin{aligned} H_n K &= Z_n K / B_n K \\ &= Z_n K / \begin{array}{c} z_1 \sim z_2 \\ \Downarrow \\ z_1 - z_2 \in B_n K \end{array} \end{aligned}$$

$C_n K$ : linear combinations of  $n$ -simplices

$Z_n K = \ker \partial_n$  “cycles” (null space)  
 $B_n K = \text{im } \partial_{n+1}$  “boundaries” (column space)  
Fact/exercise:  $B_n K \subseteq Z_n K$

$\Sigma^1: V = \{v_0, v_1, v_2\}, F$  all proper subsets

$\Sigma^1 =$  boundary of triangle:



$$0 \xleftarrow{\partial_0} C_0 \Sigma^1 \xleftarrow{\partial_1} C_1 \Sigma^1 \xleftarrow{\partial_2} C_2 \Sigma^1 \dots$$

$$0 \xleftarrow{\begin{bmatrix} 0 & -1 & -1 \\ -1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}} \langle v_0, v_1, v_2 \rangle \xleftarrow{\quad} \langle v_{12}, v_{02}, v_{01} \rangle \xleftarrow{\quad} 0 \dots$$

$$Z_0 \Sigma^1 = C_0 \Sigma^1 = \mathbb{F} \langle v_0, v_1, v_2 \rangle,$$

$$B_0 \Sigma^1 = \langle v_1 - v_2, v_0 - v_2, v_0 - v_1 \rangle = \langle v_1 - v_2, v_0 - v_2 \rangle,$$

$$Z_1 \Sigma^1 = \langle v_{01} - v_{02} + v_{12} \rangle, B_1 K = 0.$$

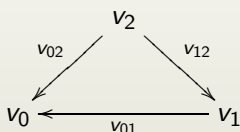
$$\dim H_k \Sigma^1 = \begin{cases} 1 & \text{if } k = 0, 1 \\ 0 & \text{otherwise.} \end{cases}$$

$Z_n K$ : the null space of  $[\partial_n]$   
 $B_n K$ : the column space of  $[\partial_{n+1}]$   
 $H_n K = Z_n K / \begin{matrix} z_1 \sim z_2 \\ \Downarrow \\ z_1 - z_2 \in B_n K \end{matrix}$

# Example $\Sigma^1$ (cont.)

$\Sigma^1 = (V, F)$  with  $V = \{v_0, v_1, v_2\}$ ,  $F$  all *proper* subsets.

bdry of  $\Delta^2$



$$\dim H_k \Sigma^1 = \begin{cases} 1 & \text{if } k = 0, 1 \\ 0 & \text{otherwise.} \end{cases}$$

$\dim H_1 \Sigma^1 = 1$  (with generator  $v_{12} - v_{02} + v_{01}$ ) corresponds to  $\dim \tilde{H}_1 S^1 = 1$  from Monday.

$\tilde{H}_1 D^2 = 0$  corresponds to  $H_1 \Delta^2 = 0$ : there

$$\partial_2 v_{012} = v_{12} - v_{02} + v_{01}$$

$\dim \tilde{H}_n S^n = 1,$   
 $\dim \tilde{H}_n D^{n+1} = 0 \Rightarrow$   
"Nobel Prize"

# Example $\Sigma^2$

$\Sigma^2 = (V, F)$  with  $V = \{v_0, v_1, v_2, v_3\}$ ,  $F$  all *proper* subsets.

$\Sigma^2 =$  boundary of  $\Delta^3$  (with *all* nonempty subsets of  $V$ ).

$\Sigma^2$  realizes to  $\simeq S^2$ .

$$C_0\Sigma^2 \xleftarrow[\partial_1 v_{ij} = v_j - v_i]{\partial_1} C_1\Sigma^2 \xleftarrow[\partial_2 v_{ijk} = v_{jk} - v_{ik} + v_{ij}]{\partial_2} C_2\Sigma^2$$

$$\mathbb{F}\langle \begin{matrix} v_0 & v_1 \\ v_2 & v_3 \end{matrix} \rangle \xleftarrow{\begin{bmatrix} -1 & -1 & -1 & 0 & 0 & 0 \\ 1 & 0 & 0 & -1 & -1 & 0 \\ 0 & 1 & 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 1 & 1 \end{bmatrix}} \mathbb{F}\langle \begin{matrix} v_{01} & v_{02} \\ v_{03} & v_{12} \\ v_{13} & v_{23} \end{matrix} \rangle \xleftarrow{\begin{bmatrix} 1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & -1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \end{bmatrix}} \mathbb{F}\langle \begin{matrix} v_{012} & v_{013} \\ v_{023} & v_{123} \end{matrix} \rangle$$

$H_2\Sigma^2 = Z_2\Sigma^2 = \langle v_{123} - v_{023} + v_{013} - v_{012} \rangle$ .

Corresponds to  $\dim \tilde{H}_2 S^2 = 1$  from Monday.

$\tilde{H}_2 D^3 = 0$  corresponds to  $H_2 \Delta^3 = 0$ : there

$$\partial_3 v_{0123} = v_{123} - v_{023} + v_{013} - v_{012}$$

$\dim \tilde{H}_n S^n = 1,$   
 $\dim \tilde{H}_n D^{n+1} = 0 \Rightarrow$   
"Nobel Prize"

Ex:  $\Sigma^n$  (all proper) /  $\Delta^{n+1}$  (all nonempty subsets)

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Finishing off the linear algebra <sup>8</sup> gives for  $n > 0$

$$\dim H_k \Sigma^n = \begin{cases} 1 & \text{if } k = 0, n \\ 0 & \text{otherwise} \end{cases}$$

$$\dim H_k \Delta^{n+1} = \begin{cases} 1 & \text{if } k = 0 \\ 0 & \text{otherwise} \end{cases}$$

essentially telling us that

- $\Sigma^n$  and  $\Delta^{n+1}$  are connected ( $\dim H_0 = 1$ )
- $\Delta^{n+1}$  has no “holes” ( $H_k \Delta^{n+1} = 0$ ,  $k > 0$ )
- $\Sigma^n$  has one “hole” in dim  $n$ .

Disclaimer: that this homology of simplicial complexes can serve the purpose of the invariants discussed on Monday is nontrivial (but *somewhere* I had to cheat!).

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<sup>8</sup>or, if you're lazy, letting a computer do it

# The Čech complex

Given a finite set  $V \subset \mathbb{R}^d$  and  $r \geq 0$

**Definition** Čech complex

$$\check{C}(r) = \{\sigma \subseteq V \mid \sigma \text{ is contained in a closed ball of radius } r\}$$

$\check{C}(r)$  grows with  $r$ .

**Extremes uninteresting:**

For small  $r$ :  $\check{C}(r) \leftrightarrow V$  (discrete).

For big  $r$ :  $\check{C}(r) \leftrightarrow \Delta^{\#V-1}$ .

**Idea:**

Important features of the point cloud shows up somewhere in the middle, and is more *persistent* than the noise.



# Example - the sixth roots of unity in $\mathbb{C} = \mathbb{R}^2$

$$V = \{e^{\frac{2\pi i}{6}k} \mid k = 0, \dots, 5\} \subseteq \mathbb{C}.$$

$$\check{C}(r) = \begin{cases} V & \text{if } 0 \leq r < 1/2 \\ \text{hexagon } [\simeq S^1] & \text{if } 1/2 \leq r < \sqrt{3}/2 \\ \text{cylinder } [\simeq S^1] & \text{if } \sqrt{3}/2 \leq r < 1 \\ \Delta^5 [\simeq D^5] & \text{if } 1 \leq r \end{cases}$$

$$\dim H_0 \check{C}(r) = \begin{cases} 6 & \text{if } 0 \leq r < \frac{1}{2} \\ 1 & \text{if } \frac{1}{2} \leq r < \infty \end{cases}$$

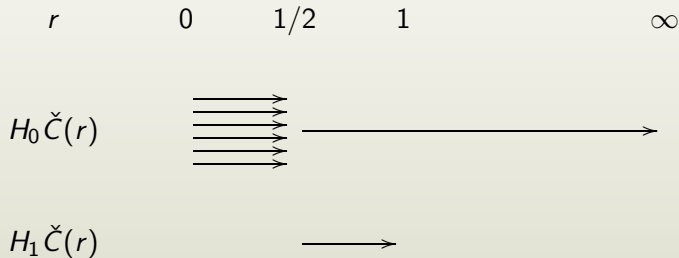
$$\dim H_1 \check{C}(r) = \begin{cases} 0 & \text{if } 0 \leq r < \frac{1}{2}, 1 \leq r < \infty \\ 1 & \text{if } \frac{1}{2} \leq r < 1 \end{cases}$$

$$\dim H_j \check{C}(r) = 0 \quad \text{for } j \neq 0, 1$$

$$\check{C}(r) = \{\sigma \subseteq V \mid \sigma \text{ in a closed } r\text{-ball}\}$$

## Bar codes, persistent homology

Typically, the homology classes are represented by *bar codes*.



In the example, the homology of a circle is fairly persistent.

# The Vietoris-Rips complex

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Given a finite set  $V \subset \mathbb{R}^d$  and  $r \geq 0$

**Definition** *Vietoris-Rips complex*

$$VR(r) = \{\sigma \subseteq V \mid \text{diam } \sigma \leq 2r\}$$

$VR(r)$  grows with  $r$ .

**Extremes uninteresting:**

For small  $r$ :  $VR(r) \leftrightarrow V$  (discrete).

For big  $r$ :  $VR(r) \leftrightarrow \Delta^{\#V-1}$ .

**Idea:**

Important features of the point cloud shows up somewhere in the middle, and is more *persistent* than the noise.

$$\text{diam } \sigma = \max\{|v - w| \mid v, w \in \sigma\}$$
$$s \leq t \Rightarrow VR(s) \subseteq VR(t)$$

# Example - the sixth roots of unity in $\mathbb{C} = \mathbb{R}^2$

$$V = \{e^{\frac{2\pi i}{6}k} \mid k = 0, \dots, 5\} \subseteq \mathbb{C}.$$

$$VR(r) = \begin{cases} V & \text{if } 0 \leq r < 1/2 \\ \text{hexagon } [\simeq S^1] & \text{if } 1/2 \leq r < \sqrt{3}/2 \\ \text{octahedron } [\simeq S^2] & \text{if } \sqrt{3}/2 \leq r < 1 \\ \Delta^5 [\simeq D^5] & \text{if } 1 \leq r \end{cases}$$

$$\dim H_0 VR(r) = \begin{cases} 6 & \text{if } 0 \leq r < \frac{1}{2} \\ 1 & \text{if } \frac{1}{2} \leq r < \infty \end{cases}$$

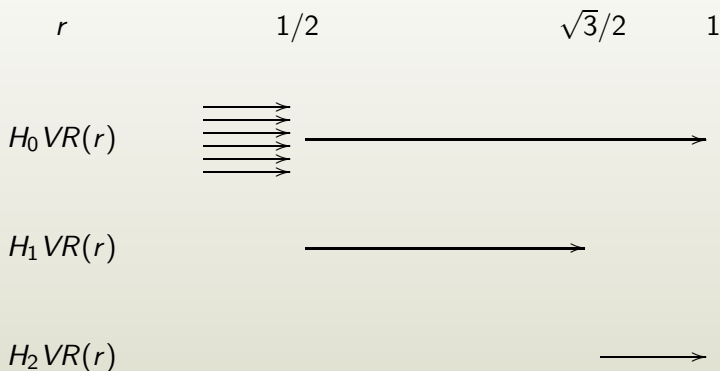
$$\dim H_1 VR(r) = \begin{cases} 0 & \text{if } 0 \leq r < \frac{1}{2}, \frac{\sqrt{3}}{2} \leq r < \infty \\ 1 & \text{if } \frac{1}{2} \leq r < \frac{\sqrt{3}}{2} \end{cases}$$

$$\dim H_2 VR(r) = \begin{cases} 0 & \text{if } 0 \leq r < \frac{\sqrt{3}}{2}, 1 \leq r < \infty \\ 1 & \text{if } \frac{\sqrt{3}}{2} \leq r < 1 \end{cases}$$

$$VR(r) = \{\sigma \subseteq V \mid \text{diam } \sigma \leq 2r\}$$

## Bar codes, persistent homology

Typically, the homology classes are represented by *bar codes*.



In the example, the most persistent feature is the homology of a circle, but it also shows a deficit of the Vietoris-Rips complex: fake high-D features can appear.<sup>9</sup>

<sup>9</sup>a shape inside the plane can't possibly have nontrivial  $H_2$ s



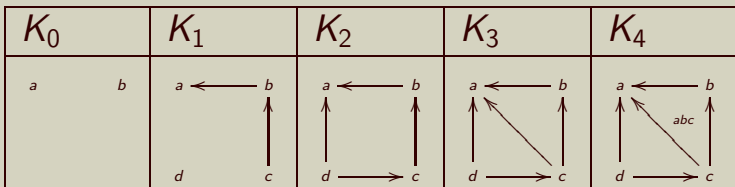
# Persistent homology **Example**

$K_0$	$K_1$	$K_2$	$K_3$	$K_4$
$a$ $b$	$a \longleftarrow b$ $d \longleftarrow c$	$a \longleftarrow b$ $d \longrightarrow c$	$a \longleftarrow b$ $d \longrightarrow c$	$a \longleftarrow b$ $d \longrightarrow c$
$H_0 =$ $\mathbb{F}\langle a, b \rangle$	$\mathbb{F}\langle a, d \rangle$	$\mathbb{F}\langle a \rangle$	$\mathbb{F}\langle a \rangle$	$\mathbb{F}\langle a \rangle$
$H_1 =$ $0$	$0$	$\mathbb{F}\langle z \rangle$	$\mathbb{F}\langle z, w \rangle$	$\mathbb{F}\langle z \rangle$

$$z = ab + bc + cd - ad,$$

$$w = ac + cd - ad$$

Draw *bar codes* for  $a, b, d, z, w$ !



Filtration degrees of simplices:

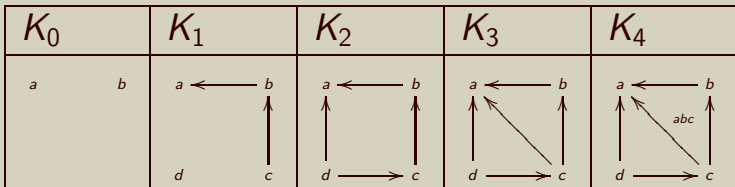
$a$	$b$	$c$	$d$	$ab$	$bc$	$ad$	$cd$	$ac$	$abc$
0	0	1	1	1	1	2	2	3	4

Keep the calculations as before, but insert a “ $t$ ” for each degree shift. Examples:

$$\partial(bc) = c - tb$$

$$\partial(abc) = t^3bc - tac + t^3ab$$





a	b	c	d	ab	bc	ad	cd	ac	abc
0	0	1	1	1	1	2	2	3	4

$$\mathbb{F}[t]\langle \begin{smallmatrix} a & b \\ c & d \end{smallmatrix} \rangle \xleftarrow{\partial_1} \mathbb{F}[t]\langle \begin{smallmatrix} ab & bc & ad \\ cd & ac \end{smallmatrix} \rangle \xleftarrow{\partial_2} \mathbb{F}[t]\langle abc \rangle$$

Keep the calculations as before, but insert a “ $t$ ” for each degree shift.

$$[\partial_1] = \begin{bmatrix} -t & \cdot & -t^2 & \cdot & -t^3 \\ t & -t & \cdot & \cdot & \cdot \\ \cdot & 1 & \cdot & -t & t^2 \\ \cdot & \cdot & t & t & \cdot \end{bmatrix}$$

$$[\partial_2] = \begin{bmatrix} t^3 \\ t^3 \\ \cdot \\ -t \end{bmatrix}$$

$H_0,$ 

a	b	c	d	ab	bc	ad	cd	ac	abc
0	0	1	1	1	1	2	2	3	4

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$$Z_0 = \mathbb{F}[t]\langle \begin{smallmatrix} a & b \\ c & d \end{smallmatrix} \rangle \xleftarrow{\partial_1} \mathbb{F}[t]\langle \begin{smallmatrix} ab & bc & ad \\ cd & ac & \end{smallmatrix} \rangle \xleftarrow{\partial_2} \mathbb{F}[t]\langle abc \rangle$$

$$[\partial_1] = \begin{bmatrix} -t & \cdot & -t^2 & \cdot & -t^3 \\ t & -t & \cdot & \cdot & \cdot \\ \cdot & 1 & \cdot & -t & t^2 \\ \cdot & \cdot & t & t & \cdot \end{bmatrix}, \quad \text{Col}[\partial_1] = \left\langle \begin{bmatrix} -t \\ t \\ \cdot \\ \cdot \end{bmatrix}, \begin{bmatrix} \cdot \\ 1 \\ \cdot \end{bmatrix}, \begin{bmatrix} -t^2 \\ \cdot \\ \cdot \\ t \end{bmatrix} \right\rangle$$

$B_0 = \langle -ta + tb, -tb + c, -t^2a + td \rangle \leftrightarrow \text{Col}[\partial_1]$ , so that  $H_0$  is spanned by  $a, b, c, d$  over  $\mathbf{F}[t]$  subject to the relations  $ta \sim tb$ ,  $c \sim tb$  and  $td \sim t^2a$ .

$$H_0 = \mathbb{F}[t]\langle a \rangle \oplus \frac{\mathbb{F}[t]\langle b - a \rangle}{t(b - a)} \oplus \frac{\mathbb{F}[t]\langle d - ta \rangle}{t(d - ta)}$$

The class  $a$  is born at 0 and never dies,  
 the class  $b - a$  is born at 0 and dies at 1  
 the class  $d - ta$  is born at 1 and dies at 2.

$\langle \dots \rangle$  is still "Span",  
 but now over  $\mathbb{F}[t]$

$H_1,$ 

a	b	c	d	ab	bc	ad	cd	ac	abc
0	0	1	1	1	1	2	2	3	4

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$$\mathbb{F}[t]\langle \begin{smallmatrix} a & b \\ c & d \end{smallmatrix} \rangle \xleftarrow{\partial_1} \mathbb{F}[t]\langle \begin{smallmatrix} ab & bc & ad \\ cd & ac & \end{smallmatrix} \rangle \xleftarrow{\partial_2} \mathbb{F}[t]\langle abc \rangle$$

$$[\partial_1] = \begin{bmatrix} -t & \cdot & -t^2 & \cdot & -t^3 \\ t & -t & \cdot & \cdot & \cdot \\ \cdot & 1 & \cdot & -t & t^2 \\ \cdot & \cdot & t & t & \cdot \end{bmatrix}, \quad [\partial_2] = \begin{bmatrix} t^3 \\ t^3 \\ \cdot \\ \cdot \\ -t \end{bmatrix}$$

Let  $z = tab + tbc + cd - ad$ ,  $w = t^2bc - ac + t^2ab$ . Then

$$Z_1 = \ker \partial_1 = \langle z, w \rangle$$

$$B_1 = \text{im} \partial_2 = \langle tw \rangle$$

$$H_1 = Z_1/B_1 = \mathbb{F}[t]\langle z \rangle \oplus \frac{\mathbb{F}[t]\langle w \rangle}{tw}$$

The class  $z$  is born at 2 and never dies

The class  $w$  is born at 3 and dies at 4.

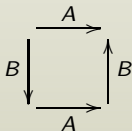
# Moral: Persistent homology is computable

– it is a combinatorial/linear algebra question safely left to computers.

With this tool one can discover the shape of point clouds. For instance, one finds that very many natural images lie in a region with the homology of a circle – corresponding to horizontal edges.

Another one corresponds to vertical edges.

Slightly less persistent, a third circle appears that intersect the other two – and analyzing the persistent homology one discovers a high density surface (see picture) containing these three circles.



Here TDA was a tool useful for *discovering* a phenomenon.