# **NOISE INDUCED CHANGES IN THE DYNAMICAL BEHAVIOUR OF NEURAL FIELDS** Pedro M. Lima<sup>1</sup>, Evelyn Buckwar<sup>2</sup>

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# FORMULATION OF THE PROBLEM

Neural Field Equations (NFE) are a powerful tool for analysing the dynamical behaviour of populations of neurons.

Literature on computational methods for NFE: [1], [2], [3] (deterministic case); [4] (stochastic models).

The main goal of the present work is to analyse the effect of noise in certain neural fields . The stochastic neural field equation with delay has the form:

 $dU_t(x) = \left(I(x,t) - \frac{1}{c}U_t(x) + \int_O K(|x-y|)S(U_{t-\tau}(y))dy\right)dt + \epsilon dW_t(x), \quad (1)$ 

where  $t \in [0, T]$ ,  $x \in \Omega = [-I, I] \subset R$ , S(x) is the Firing rate function; K is the Connectivity kernel; I is the External input;  $\tau$  is a delay, depending on the distance |x - y|;  $W_t$  is a Q-Wiener process. Initial condition:

 $U_t(x) = U_0(x, t), \quad t \in [-\tau_{max}, 0], \quad x \in \Omega,$  (2) where  $U_0(x, t)$  is some given stochastic process,  $\tau_{max}$  is the maximum value of the delay.

### NUMERICAL EXAMPLE

We investigate the effect of noise in the formation of spatio-temporal patterns in dynamic neural fields. The stability analysis of these patterns in the deterministic case was carried out in [5], p.37. This numerical example does not include delays. Firing rate function S(x) - Heaviside function; Connectivity kernel $K(x) = A \exp(-kx) (K \sin(\alpha x) + \cos(\alpha x));$ External input  $I(x) = -I_0 + B \exp\left(-\frac{x^2}{2\sigma^2}\right)$ .

#### Deterministic Case



## SPACE DISCRETIZATION

We apply a numerical scheme which uses the Galerkin method. Consider the following expansion of the solution:

$$U_t(x) = \sum_{k=0}^{\infty} u_t^k v_k(x), \qquad (3)$$

where  $v_k$  - eigenfunctions of the covariance operator of the noise in (1); we define

$$v_k(x) = \exp(ikx), \qquad k = 0, 1, ..., N.$$
 (4)

Take the inner product of equation (1) with the basis functions  $v_i$ :

$$dU_t, v_i) = \left[ (I(x, t), v_i) - \frac{1}{c} (U_t, v_i) + \left( \int_{\Omega} K(|x - y|) S(U_{t - \tau}(y)) dy, v_i \right) \right] dt + \epsilon (dW_t, v_i)$$
(5)

We expand  $dW_t$  as

$$dW_t(x) = \sum_{k=0}^{\infty} v_k(x) \lambda_k d\beta_t^k, \qquad (6)$$

where  $\beta_t^k$  - independent white noises in time ;  $\lambda_k$  are the eigenvalues of the covariance operator of the noise.

We define an approximate solution (3)

$$U_t^N(x) = \sum_{k=0}^{N-1} u_t^{k,N} v_k(x).$$

(7)

(10)

Fig. 1. Stationary solution Fig.2. Evolution of  $u_{min}(t)$ . Fig.3. Evolution of  $u_{max}(t)$  $u_{min}(t)$  and umax(t) are the minimum and the maximum of the solution (on the whole domain) at time t



The coefficients  $u_t^{k,N}$  satisfy the following nonlinear system of stochastic delay differential equations:

$$du_t^{i,N} = \left[ (I(x,t),v_i) - \frac{1}{c} u_t^{i,N} + (KS)^{i,N} (\bar{u}_{t-\tau}) \right] dt + \epsilon \lambda_i d\beta_t^i, \tag{8}$$

where  $(KS)^{i,N}(\bar{u}_{t-\tau})$  is given by

$$(KS)^{i,N}(\bar{u}_{t-\tau}) = h^2 \sum_{j=1}^{N} v_i(x) \left( \sum_{l=1}^{N} K(|x_l - y_j|) S\left( \sum_{k=1}^{N} u_{t-\tau}^k v_k(y_j) \right) \right)$$
(9)

i = 0, ..., N - 1. In this case we are introducing in [-I, I] a set of N equidistant gridpoints  $x_j = -I + j * h$ , j = 1, ..., N, where h = 2I/N, and using the rectangular rule to evaluate the integrals.

#### TIME DISCRETIZATION

we can apply the Euler-Maruyama method to the solution of the system (8). Let  $t_j = jh_t$ , j = 0, 1, ..., n;  $u_i^{k,N} \approx u_{t_i}^{k,N}$ .

In these notations, the Euler-Maruyama method may be written as  $u_{j+1}^{i,N} = \frac{u_j^{i,N} + h_t \left[ (I(x_i, t_j), v_i) + (KS)^{i,N} (\bar{u}_{t_j-\tau}) \right] + \sqrt{h_t} \epsilon \lambda_i w_i}{1 + \frac{1}{c} h_t},$  equation. From 10 trajectories, 6 have converged to the five-bump stationary solution (fig. 6), 3 have converged to the three-bump stationary solution (fig. 5) and one has converged to the one-bump stationary solution (fig. 4). In fig. 7 (fig. 8) the graphs of  $u_{min}(t)(u_{max}(t))$  are plotted for five different trajectories.

In the case  $\epsilon = 0.1$  the trajectories of the stochastic equation stabilize after a certain

# COMPUTATIONAL COMPLEXITY

The straightforward computation of each integral in (9) requires about  $N^3$ evaluations of the integrand function. However two of the sums in (9) can be evaluated efficiently by the Fast Fourier Transform (FFT). This reduces the number of function evaluations to  $O(N(\log N)^2)$ .

#### References

- [1] G. Faye and O. Faugeras, Some theoretical and numerical results for delayed neural field equations, Physica D 239 (2010) 561-578.
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- [3] P.M. Lima and E. Buckwar, Numerical solution of the neural field equations in the two-dimensional case, SIAM J. Sci. Comput. (to appear).
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time, but the resulting patterns (see Figs. 9-11) are rather different from the stationary solutions of the deterministic equation. In fig. 12 (fig. 13) the graphs of  $u_{min}(t)(u_{max}(t))$  are plotted for five different trajectories.

# **CONCLUSIONS AND FUTURE WORK**

- The Galerkin approximation combined with the Euler-Maruyama method provide an effective computational method for the numerical solution of stochastic neural field equations.
- The efficiency of the algorithm is guaranteed by the use of the Fast Fourier Transform for the evaluation of integrals.
- The numerical simulations carried out so far suggest that for sufficiently small noise the stochastic Neural Field Equations have stable stationary solutions, close to the ones of the deterministic case.
- Using this algorithm we plan to analyse other types of dynamic neural fields, including the case of finite propagation speed (delay equations).
- This algorithm can be extended to the case of multidimensional neural fields.