

# Mathematical Models in Neuroscience

## Lecture 2- From the Hodgkin-Huxley equations to neural fields and topological methods

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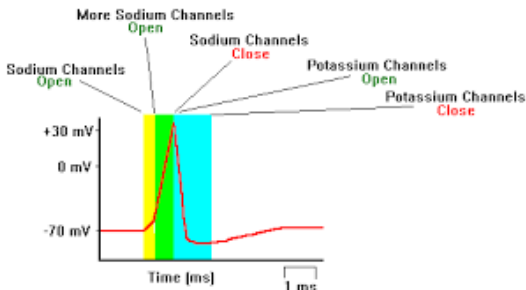
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# OUTLINE OF THE TALK

- 1 Hodgkin-Huxley equations
- 2 Fitzhugh-Nagumo equations
- 3 Leaky integrate and fire models
- 4 Neural fields
- 5 Representing neural networks by graphs
- 6 Using topological methods to evaluate the complexity of neuronal connections.
- 7 Mathematical tools of Neuroscience
- 8 Applications

# 1. HODGKIN-HUXLEY EQUATIONS

## 1.1 How is an action potential generated?



- The neuron membrane has a certain **resting potential** (about  $-70\text{ mV}$ ).
- As a result of **external stimulus**, the membrane potential increases.
- When the membrane potential attains a **certain threshold**, the **sodium channels open**.
- As **sodium ions** flow into the neuron, the membrane potential increases (**depolarization process**).
- When the membrane potential attains a **certain critical value**, the **sodium channels close** and the **potassium channels open**.
- As **potassium ions** flow out of the neuron, the membrane potential decreases (**repolarization process**).

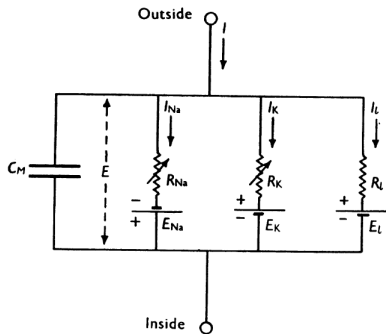
## 1.2 How can this process be described by a mathematical model?

In 1952 [A.H. Hodgkin and A.F.Huxley](#) introduced a mathematical model that describes the [ionic mechanism](#) underlying the initiation and propagation of action potentials (nervous stimulus) in an axon.

The Hodgkin-Huxley model describes the ionic exchanges between the [extracellular and intracellular medium](#), using the language of [electric circuits](#) (conductance, capacitance, current sources).

In 1963 A.H. Hodgkin and A.F.Huxley were awarded the [Nobel Prize in Physiology or Medicine](#) for this work.

# 1.3 HODGKIN-HUXLEY MODEL AND ELECTRIC CIRCUITS



Hodgkin and Huxley have described **ion currents** in the language of **electric circuits**.

The **ion channels** (sodium, potassium, leaky) are replaced by **electrical resistances** ( $R_{Na}$ ,  $R_K$ ,  $R_L$ ).

The **conductance** in the **leaky channel** is **constant** (the channel is always open). The other channels may **close or open** when the **membrane**

## 1.4 EQUATION OF MEMBRANNE POTENTIAL

The main physical variables in the description of the ion currents are the **membrane potential** and the **electrical conductances** (sodium, potassium and leaky).

The equation for the membrane potential ( $V_m$ ):

$$I = C_m \frac{dV_m}{dt} + g_k(V_m - V_k) + g_{Na}(V_m - V_{Na}) + g_l(V_m - V_l)$$

$I$ - current;  $V_m$  - membrane potential;

$g_k, g_{Na}, g_l$ - potassium, sodium, and leaky conductances;

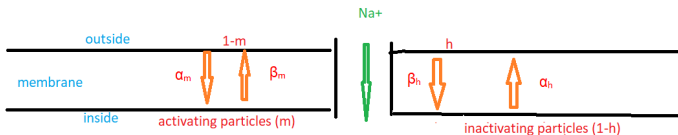
$V_k, V_{Na}, V_l$  - Potassium , sodium, and leaky reversal potentials.

The **leaky conductance** (conductance of the leaky channels) is constant.

The other conductances depend on the membrane potential.

## 1.5 How does the sodium conductance change?

There are particles that **activate the sodium channels** and particles that **block** them. These particles can move between inside and outside the membrane.



$m$ - part of the **activation particles** which are inside the membrane.

$h$ - part of the **inactivation particles** which are outside the membrane.

$$g_{Na} = \bar{g}_{Na} m^3 h,$$

$\bar{g}_{Na}$ - maximal value of the sodium conductance.

$\alpha_m, \beta_m, (\alpha_h, \beta_h)$  - **transfer rates** of the activation (inactivation) particles.

Depend on the membrane potential, but not on the time.

## 1.6 How does the potassium conductance change?

In the case of **potassium**, there are only **activation particles**  $n$ - part of the **activation particles** which are inside the membrane.

$$g_k = \bar{g}_k n^4,$$

$\bar{g}_k$ - maximal value of the potassium conductance.

$n$  satisfies the differential equation:

$$\frac{dn}{dt} = \alpha_n(V_m)(1 - n) - \beta_n(V_m)n.$$

$\alpha_n, \beta_n$  - **transfer rates** of the activation particles of the potassium channel.  
 $m$  and  $h$  satisfy similar equations.



## 1.7 FULL SYSTEM OF EQUATIONS

By coupling the equation for the membrane potential with the equations for  $n$ ,  $m$ ,  $h$ , we finally obtain a system of **4 nonlinear ordinary differential equations**, known as **Hodgkin-Huxley** equations:

$$I = C_m \frac{dV_m}{dt} + \bar{g}_k n^4 (V_m - V_k) + \bar{g}_{Na} m^3 h (V_m - V_{Na}) + g_l (V_m - V_l)$$

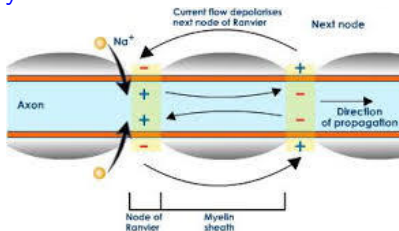
$$\frac{dn}{dt} = \alpha_n(V_m)(1 - n) - \beta_n(V_m)n$$

$$\frac{dm}{dt} = \alpha_m(V_m)(1 - m) - \beta_m(V_m)m$$

$$\frac{dh}{dt} = \alpha_h(V_m)(1 - h) - \beta_h(V_m)h$$

## 2. FITZHUGH-NAGUMO EQUATIONS

Further investigation of the propagation of nervous stimulus has lead to the [FitzHugh-Nagumo equations](#) (1962), which describe the propagation of signals in [myelinated axons](#).

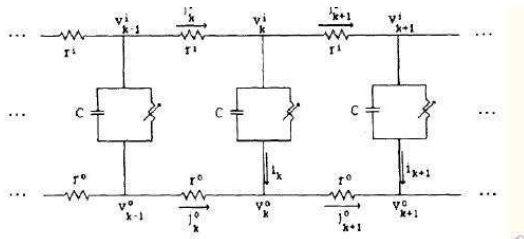


The [myelin](#) completely insulates the membrane, so that all the electric processes occur at the [Ranvier nodes](#).

## 2.1 AXONS AND ELECTRIC CIRCUITS

### Circuit Model

Impulse conduction in a myelinated axon can be simulated using a circuit model: the nodes of Ranvier correspond to **capacitors** and the space between them, to **resistances**.



## 2.2. Assumptions of the Nerve Conduction Model

- the nodes are uniformly spaced and electrically identical,
- the axon is infinite in extent,
- the cross-sectional variations in potential are negligible,
- a supra-threshold stimulus begins a signal which travels down the axon from node to node.

## 2.3.DISCRETE FITZHUGH-NAGUMO EQUATIONS

The propagation of nervous stimulus can be modeled by the following system of **difference equations**:

$$\begin{cases} \frac{1}{R}(v_{k+1} - 2v_k + v_{k-1}) = C \frac{dv_k}{dt} - f(v_k) + w_k \\ \sigma v_k - \gamma w_k = \frac{dw_k}{dt} \end{cases}, \quad k \in Z, \quad (1)$$

where  $v_k$  represents the **membrane potential at the k-th node**,  $w_k$  is the so-called **recovery variable**,  $\sigma$  and  $\gamma$  are non-negative rate constants,  $R$  and  $C$  are the axoplasmic resistance and the nodal membrane capacitance. Equations (1) are known as the **discrete FitzHugh-Nagumo equations**.

## 2.4 ACTIVATION FUNCTION

The nonlinear function  $f$  in discrete FitzHugh-Nagumo equations represents a current-voltage relation (activation function) and is supposed to satisfy the following conditions:

$$\begin{aligned} f \in C^1([0, 1]), \quad f(0) = f(a) = f(1) = 0, \\ f(v) < 0, \text{ if } 0 < v < a; \\ f(v) > 0, \text{ if } a < v < 1. \end{aligned} \tag{2}$$

In many applications this function is taken as

$$f(v) = bv(v - a)(1 - v), \tag{3}$$

where  $b > 0$ .

## 2.5.REDUCTION TO A SINGLE EQUATION

The discrete FitzHugh-Nagumo equations can be simplified by neglecting the recovery process (that is, it is assumed that the constants  $\sigma$  and  $\gamma$  are so small that the recovery process has no influence in propagation). Let us assume that

$$v_{k+1}(t) = v_k(t - \tau),$$

where  $\tau$  is a certain delay, which is proportional to the space between nodes and to the reciprocal of propagation speed. Then we obtain a mixed-type functional differential equation:

$$\frac{1}{R}(v(t - \tau) - 2v(t) + v(t + \tau)) + f(v(t)) = C \frac{dv(t)}{dt}, \quad (4)$$

### 3. LEAKY INTEGRATE AND FIRE MODELS

In the LIF (Leaky Integrate and Fire) model, each neuron  $i$  can be fully described in terms of a single internal variable, namely the depolarization potential  $V_i(t)$  of the neural membrane.

$$\tau \frac{dV_i}{dt} = - (V_i(t) - V_L) + RI_i(t),$$

where  $V_L$  -leaky (resting) potential;  $RI_i$ - total synaptic current (the sum of the action of all the synapses):

$$RI_i(t) = J \sum_{j=1}^N K_{ij} \sum_k \delta(t - t_j^{(k)}),$$

$N$  - number of neurons connected with  $i$ ;  $K_{ij}$  -efficacy of the connection between  $i$  and  $j$ ;  $t_j^{(k)}$  -time of the  $k_{th}$  spike of the  $j_{th}$  neuron;  $J$  -constant. When  $V_i$  reaches a certain threshold  $\theta$ , the  $i$ -th neuron fires and the system is reset:  $V_i$  is set to the resting value  $V_L$ .



## 4. NEURAL FIELDS

A new approach was introduced in the years 70:

Wilson and Cowan, 1972 and Amari, 77

Consider a region  $\Omega$  of the  $n$ -dimensional space and a function  $V(\bar{x}, t)$ , with  $\bar{x} \in \Omega$ .

We assume that the neurons are **very densely distributed**, so that we can assign a certain electric potential  $V$  to each point of  $\Omega$ .

This approach is realistic when considering **regions of the cortex**.

$V(\bar{x}, t)$  represents the spatiotemporal structure of the neuronal population:

- **spatial** distribution of potential;
- **time** evolution.

## 4.1 NEURAL FIELD EQUATION

Neural Field Equation (NFE):

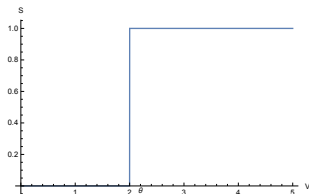
$$c \frac{\partial}{\partial t} V(\bar{x}, t) = I(\bar{x}, t) - V(\bar{x}, t) + \int_{\Omega} K(\|\bar{x} - \bar{y}\|_2) S(V(\bar{y}, t)) d\bar{y}, \quad (5)$$

$$t \in [0, T], \bar{x} \in \Omega \subset \mathbb{R}^2;$$

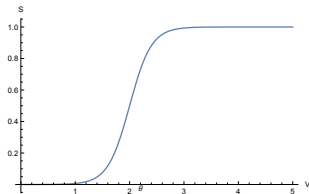
Initial Condition:  $V(\bar{x}, 0) = V_0(\bar{x})$ ,  $\bar{x} \in \Omega$ .

- $V(\bar{x}, t)$  - the membrane potential in point  $\bar{x}$  at time  $t$ ;
- $I(\bar{x}, t)$  - external sources of excitation;
- $S(V)$  - dependence between the firing rate of the neurons and their membrane potentials (sigmoidal or Heaviside function);
- $K(\|\bar{x} - \bar{y}\|_2)$  - connectivity between neurons at  $\bar{x}$  and  $\bar{y}$ .

## 4.2 EXAMPLES OF FIRING RATE FUNCTIONS

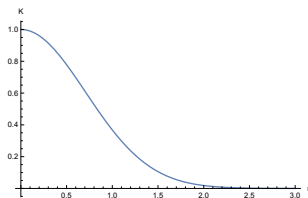


**Heaviside function** - the neuron is inactive ( $S = 0$ ) while the potential does not reach the **threshold value  $\theta$**  and then becomes fully activated ( $S = 1$ ).

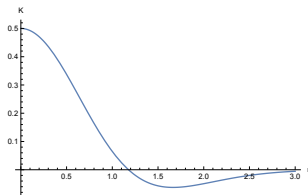


**Sigmoidal function** - as the potential increases the activation ( $S$ ) **varies continuously from 0 to 1**.

## 4.3 EXAMPLES OF CONNECTIVITY FUNCTIONS



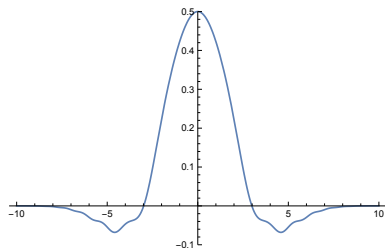
**Gaussian function** - the connectivity is positive everywhere (**excitatory**) and decreases with distance.



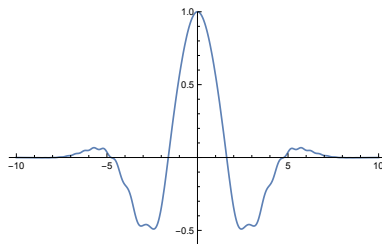
**Mexican hat** - the connectivity is positive (**excitatory**) at short distances and negative (**inhibitory**) at long ones.

## 4.4 MULTIBUMP SOLUTIONS

**Activation Domain** : subset of  $\Omega$  where the potential is higher than the **threshold**. In this domain there is a **strong connection between neurons**. The stationary solutions of NFE often have one or several activation domains (**multibump solutions**).



one-bump solution



three-bump solution

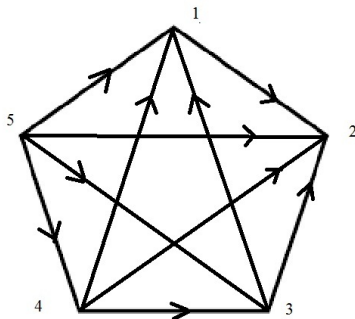
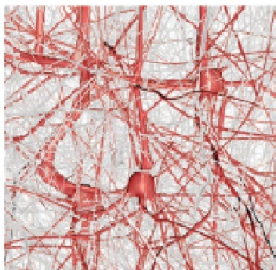
## 5.ALGEBRAIC TOPOLOGY METHODS

### Blue Brain Project

*M. Reimann et al., Cliques of Neurons Bound into Cavities Provide a Missing Link between Structure and Function, Frontiers of Mathematical Neuroscience, June 2017.*

Construct graphs of a network that **reflect the direction of information flow** and analyse these directed graphs using **algebraic topology**.

## 5.1 CLIQUES OF NEURONS AND GRAPHS



clique of neurons	directed graph
neuron	node
synapsis	directed edge
number of connected neurons	dimension

**source:** node that is source of all edges (5);

**sink:** node that is target of all edges (2)

## 5.3 DIRECTED SIMPLICES AND SIMPLICIAL COMPLEXES

directed simplex of dimension  $n - 1$  - clique of  $n$  all-to-all connected neurons.

Each neuron belongs to many directed simplices of various dimensions. A neural network contains in general many simplices.

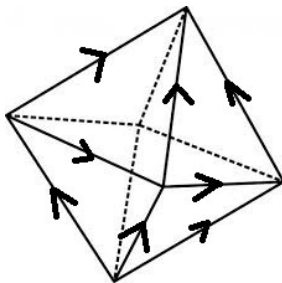
**Definition.** A simplicial complex  $K$  is a set of simplices that satisfy:

- Every face (subset) of a simplex from  $K$  is also in  $K$ .
- The intersection of two simplices  $S_1, S_2$  of  $K$  is a face of  $S_1$  and  $S_2$ .

The dimension of a simplicial complex is the maximal dimension of the simplices that compose it.

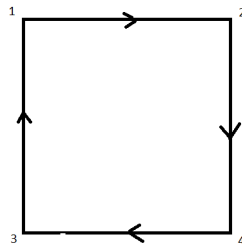
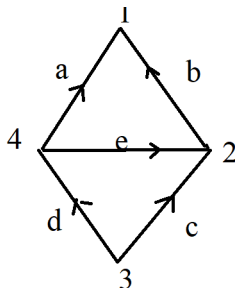


## 5.4 EXAMPLES OF A SIMPLICIAL COMPLEX



The octahedron is a **simplicial complex** because it is composed of 2D-simplices (**triangles**) and the intersection of these triangles is a 1D-simplex (**an edge**). The dimension of the octahedron is 2 (dimension of the faces).

## 5.4 MORE EXAMPLES



The lozenge (left-hand side) is a simplicial complex: each face of the complex is a **triangle** and the intersection of the two triangles is the **edge e** (a 1D-simplex). The dimension of this complex is 2 (dimension of the faces).

The **square** (right-hand side) is also a simplicial complex: it is a set of **edges** and the intersection of two edges is a **vertice** (a 0D-simplex). The dimension of this complex is 1 (dimension of the edges).

## 5.5 EULER CHARACTERISTIC OF A SIMPLICIAL COMPLEX

Euler characteristic -  $\chi(S) = \sum_{n=0}^{n_{\max}} (-1)^n |S_n|$ ,

where  $S_n$  is the number of  $n$ -dimensional simplices contained in  $S$ .

### EXAMPLES

In the case of the **lozenge**:

$S_0 = 4$  - number of 0-dimensional simplices (vertices);

$S_1 = 5$  - number of 1-dimensional simplices (edges);

$S_2 = 2$  - number of 2-dimensional simplices (faces);

Euler characteristic:  $\chi(S) = 4 - 5 + 2 = 1$ .

In the case of the **octahedron**:

$S_0 = 6$  - number of 0-dimensional simplices (vertices);

$S_1 = 12$  - number of 1-dimensional simplices (edges);

$S_2 = 8$  - number of 2-dimensional simplices (faces);

Euler characteristic:  $\chi(S) = 6 - 12 + 8 = 2$ .

## 5.5 EULER CHARACTERISTIC OF POLYHEDRA

The Euler characteristic was first introduced for **polyhedra** and defined as

$$\chi(P) = V - E + F,$$

where  $F$  is the number of **faces**,  $E$  is the number of **edges** and  $V$  is the number of **vertices**. In this context, Euler has stated the well-known **polyhedron formula**:

If  $P$  is a convex polyhedron, then

$$\chi(P) = 2.$$

For example, in the case of a cube:

$$V = 8, E = 12, F = 6,$$

then

$$\chi(P) = 8 - 12 + 6 = 2.$$

## 5.6 BETTI NUMBERS OF SIMPLICIAL COMPLEXES

- $\beta_0$ - number of connected parts.
- $\beta_1$ - number of one-dimensional circular holes (regions surrounded by one-dimensional simplices)
- $\beta_2$ -number of two-dimensional cavities (regions surrounded by two-dimensional simplices)

## 5.7 EXAMPLES

Consider the **lozenge**: There is

- one connected component in this figure -  $\beta_0 = 1$ ;
- two holes -  $\beta_1 = 2$ ;
- no two-dimensional cavities-  $\beta_2 = 0$ .

Consider the **octaedr**: There is

- one connected component in this figure -  $\beta_0 = 1$ ;
- eight holes -  $\beta_1 = 8$ ;
- one two-dimensional cavity (the interior of the octaedr) -  $\beta_2 = 1$ .

## 5.9 LOCAL AND GLOBAL MEASURES OF INFORMATION

How do the topologic measures of geometrical objects reflect the properties of **neural networks**?

- **Local flow of information** is well described by **directed graphs**, identifying sources and sinks.
- **Global measures of information** are given by **Betti numbers** and **Euler characteristic**.

## 5.10 TOPOLOGICAL MEASURES AND NEURAL ACTIVITY

"The variation in Betti numbers and Euler characteristic over time (in response to stimulus) indicates that **neurons become bound into cliques and cavities by correlated activity.**"

"**A stimulus may be processed by binding neurons into cliques of increasingly higher dimension, as a specific class of cell assemblies, possibly to represent features of the stimulus.**"

"'The presence of **high-dimensional topological structures** is a general phenomenon across nervous systems'".

Michael Reinmann et al., 2017

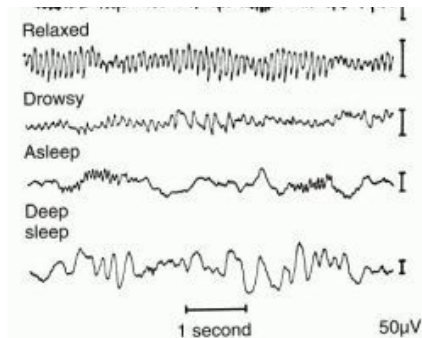


## 6. MATHEMATICAL TOOLS IN NEUROSCIENCE

- Differential equations
- Dynamical systems
- Bifurcation theory
- Algebraic topology
- Stochastic processes (essential to take into account the influence of random factors)
- Computational methods (most of the considered equations cannot be solved analytically)

# 7. APPLICATIONS

## INTERPRETATION OF MEDICAL DATA



Output of a [Electroencephalogram \(EEG\)](#). The EEG registrates neuronal activity with a good [time resolution](#).

## 7.1 APPLICATIONS TO MEDICINE

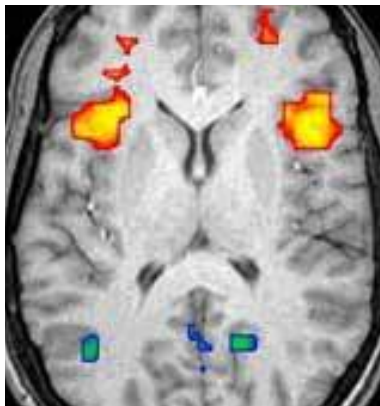


Image obtained by means of **Magnetic Resonance (fMRI)**, showing the neural activity during the perception of a visual signal.

**Neural field models** provide a framework for **unifying data** from different imaging modalities, for example, **EEG** (which has a good time resolution) and **fMRI** (good spatial resolution).

## 7.2 APPLICATIONS TO ROBOTICS

"To efficiently interact with another agent in solving a mutual task, a robot should be endowed with cognitive skills such as memory, decision making, action understanding and prediction. The proposed architecture is strongly inspired by our current understanding of the processing principles and the neuronal circuitry underlying these functionalities in the primate brain."

W. Erlhagen and E. Bicho, The dynamic neural field approach to cognitive robotics, J. Neural Eng. 3 (2006) R36 – R54

Neural fields are a good tool to simulate working memory.

They simulate how a population of neurons can encode in its firing pattern the features of an external stimulus.

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