

Riemannian Geometry, Fall 2017/18
Instituto Superior Técnico

September 23, 2017

- 1.** Consider the torus T^2 equal to the quotient of $[0, 1]^2$ by the equivalence relation

$$(x, y) \sim (x + 1, y) \sim (x, y + 1).$$

- a)** For $p = (x, 0)$, with $0 < x < 1$, give a parameterization of a neighborhood of p .
b) Give a parameterization of a neighborhood of $(0, 0)$.
- 2.** Consider the topological manifold $\mathbb{R}P^2$ equal to the quotient of $[0, 1]^2$ by the equivalence relation

$$(x, y) \sim (x + 1, 1 - y) \sim (1 - x, y + 1).$$

Give a parameterization of a neighborhood of $(0, 0)$.

- 3.** Consider the paraboloid

$$P = \{(x, y, z) \in \mathbb{R}^3 : z = x^2 + y^2\}.$$

- a)** Show that the functions ϕ and ψ , defined by

$$\phi(x, y) = (x, y, x^2 + y^2), \quad \psi(r, \theta) = (r \cos \theta, r \sin \theta, r^2),$$

define the same differential structure on $P \setminus \{(0, 0, 0)\}$.

- b)** Does there exist a parameterization φ of a neighborhood in P of $(0, 0, 0)$ such that the parameterizations φ together with ψ form an atlas for P , with φ incompatible with ϕ ?
- 4.** Let $a > 0$. Consider the catenoid C parameterized by

$$(a \cosh v \cos u, a \cosh v \sin u, av)$$

and the helicoid H parameterized by

$$(w \cos z, w \sin z, az).$$

Consider the function $f : C \rightarrow H$, defined by

$$f(x, y, z) = \left(a \frac{x}{\sqrt{x^2 + y^2}} \sinh \frac{z}{a}, a \frac{y}{\sqrt{x^2 + y^2}} \sinh \frac{z}{a}, a \arctan \frac{y}{x} \right),$$

where $\arctan \frac{y}{x}$ denotes the argument of $x + iy$.

- a) Check that, indeed, f has range in H .
- b) Determine the representation of f in local coordinates. Is f differentiable?

October 1, 2017

5. Consider $\mathbb{R}P^2$ parameterized by

$$\varphi_1(y, z) = [1, y, z], \quad \varphi_2(x, z) = [x, 1, z], \quad \varphi_3(x, y) = [x, y, 1],$$

and $f : \mathbb{R}P^2 \rightarrow \mathbb{R}P^2$, defined by

$$f([x, y, z]) = [y, x, z].$$

Verify that f is differentiable.

6. Consider the immersion $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$, defined by

$$f(x, y) = (x, y, x^2 + y^2).$$

- a) Give local coordinates around $p = (0, 0)$ and $f(p) = (0, 0, 0)$ on which f is the canonical immersion.
- b) Give local coordinates around $p = (1, 2)$ and $f(p) = (1, 2, 5)$ on which f is the canonical immersion, with p having coordinates $(0, 0)$ and $f(p)$ having coordinates $(0, 0, 0)$.

7. Consider the submersion $f : \mathbb{R}^3 \rightarrow \mathbb{R}$, defined by

$$f(x, y, z) = x - yz.$$

Give coordinates around $p = (0, 0, 0)$ and $f(p) = 0$ on which f is the canonical projection.

October 7, 2017

8. Consider the vector fields defined on \mathbb{R}^2 by

$$X(x, y) = (x + y)\partial_y,$$

$$Y(x, y) = (-2x + y)\partial_x + (x - 2y)\partial_y.$$

- a) Compute the bracket $[X, Y]$.
- b) Compute the flow of X , $\phi_t(x_0, y_0)$, and the flow of Y , $\psi_t(x_0, y_0)$.
- c) Compute $(d\phi_{-t})_{\phi_t(x_0, y_0)} Y_{\phi_t(x_0, y_0)}$.

d) Compute the Lie derivative $L_X Y$ using your answer to **c**).

9. Consider the vector fields defined on \mathbb{R} by

$$X(x) = x\partial_x, \quad Y(x) = x^2\partial_x.$$

a) Compute the bracket $[X, Y]$.

b) Compute the flow of X , $\phi_t(x_0)$, and the flow of Y , $\psi_t(x_0)$.

c) Compute $\eta_t(x_0) = (\psi_{-t} \circ \phi_{-t} \circ \psi_t \circ \phi_t)(x_0)$.

d) Verify that

$$\left. \frac{1}{2} \frac{d^2}{dt^2} \eta_t(x_0) \right|_{t=0} = [X, Y](x_0).$$

October 13, 2017

10. Let J be the $(2n) \times (2n)$ matrix

$$J = \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix}.$$

Consider the group

$$Sp(2n, \mathbb{R}) = \{A \in \mathcal{M}_{(2n) \times (2n)} : AJA^T = J\}.$$

a) Prove that $Sp(2n, \mathbb{R})$ is a submanifold of $\mathbb{R}^{(2n)^2}$. What is the dimension of $Sp(2n, \mathbb{R})$?

b) Compute the Lie algebra $\mathfrak{sp}(2n, \mathbb{R})$. Compute directly the dimension of $\mathfrak{sp}(2n, \mathbb{R})$.

c) Check directly that for $B \in \mathfrak{sp}(2n, \mathbb{R})$, we have $e^B \in Sp(2n, \mathbb{R})$.

d) Compute the tangent space to $Sp(2n, \mathbb{R})$ at J , $T_J Sp(2n, \mathbb{R})$.

e) Can you guess a $B \in \mathfrak{sp}(2n, \mathbb{R})$ for which $e^B = J$? (Note: $J^2 = -I$.)

11. Consider the manifold $M = \mathbb{C}^3 \setminus \{0\}$ and the Lie group $G = (\mathbb{C} \setminus \{0\}, \cdot)$ acting on M by $\lambda \cdot (z^1, z^2, z^3) = (\lambda z^1, \lambda z^2, \lambda z^3)$. Argue that M/G is a manifold and compute its dimension.

12. Construct a two sheeted covering of the Klein bottle [given by the quotient of $[0, 1]^2$ by the equivalence relation

$$(x, y) \sim (x + 1, y) \sim (1 - x, y + 1)]$$

by the Torus T^2 [given by the quotient of $[0, 1]^2$ by the equivalence relation

$$(x, y) \sim (x + 1, y) \sim (x, y + 1)].$$

October 22, 2017

13. Let V belong to $\mathfrak{so}(3)$.

- a) Compute X_A^V , the left invariant vector field generated by V at $A \in SO(3)$.
- b) Characterize the tangent space to $SO(3)$ at A , and verify directly that X_A^V belongs to $T_A SO(3)$.
- c) Let $\psi_t = F(\cdot, t)$ for F the flow of X^V . What is $\psi_t(A)$?

14. Suppose φ and $\psi : G \rightarrow H$ are two homomorphisms of Lie groups such that $\varphi_* = \psi_*$, with G connected. Show that $\varphi = \psi$.

15.

- a) Compute $\text{Alt}(dx^1 \otimes dx^2)$ and $\text{Alt}(dx^1 \otimes dx^2 \otimes dx^3)$.
- b) Expand $dx^1 \wedge dx^2 \wedge dx^3$ using tensor products.
- c) Let u, v, w belong to \mathbb{R}^5 . Write $dx^2 \wedge dx^3 \wedge dx^5(u, v, w)$ as a determinant.
- d) Let X belong to \mathbb{R}^5 . Simplify $\iota(X) dx^1 \wedge dx^3 \wedge dx^5$.

October 29, 2017

16. Consider the 2-covariant tensor field $g \in \mathcal{T}^2(\mathbb{R}^3)$ defined by

$$g = dx \otimes dx + dy \otimes dy + dz \otimes dz,$$

let i be the inclusion of S^2 in \mathbb{R}^3 , and r be the parameterization of S^2 given by

$$r(\varphi, \theta) = (\cos \theta \sin \varphi, \sin \theta \sin \varphi, \cos \varphi).$$

- a) Calculate $h = r^* i^* g$.
- b) Calculate $\int_{r^{-1}(S^2)} \sqrt{\det h} d\varphi \wedge d\theta$.
- c) Consider the one form $\omega = \cos \varphi d\theta$ and the region R of S^2 such that $0 < \theta < \theta_0$ and $\varphi_0 < \varphi < \frac{\pi}{2}$, where θ_0 and φ_0 are fixed. Calculate directly $\int_{\partial R} (r^{-1})^* \omega$ and $\int_R d((r^{-1})^* \omega)$, verifying the equality of Stokes' Theorem.

17. Consider the two torus T^2 with cartesian equation

$$\left(\sqrt{x^2 + y^2} - R \right)^2 + z^2 = r^2$$

and the parameterization of a neighborhood of T^2 given by

$$p(\rho, \theta, \varphi) = ((R + \rho \cos \varphi) \cos \theta, (R + \rho \cos \varphi) \sin \theta, \rho \sin \varphi).$$

- a) Calculate $\omega := p^*(dx \wedge dy \wedge dz)$.
- b) Calculate $\eta := \iota\left(\frac{\partial}{\partial \rho}\right)\omega$.
- c) Calculate $\int_{p^{-1}(T^2)} \eta$.

November 5, 2017

18. Let ω be a one form. Check that

$$d\omega(X, Y) = X \cdot (\omega(Y)) - Y \cdot (\omega(X)) - \omega([X, Y]).$$

19. Consider the vector field

$$X = -\frac{y}{x^2 + y^2} \partial_x + \frac{x}{x^2 + y^2} \partial_y.$$

and $\omega = dx \wedge dy$.

- a) Compute $L_X \omega$ using

$$L_X(\omega_1 \wedge \omega_2) = (L_X \omega_1) \wedge \omega_2 + \omega_1 \wedge (L_X \omega_2)$$

and

$$d(L_X \omega) = L_X(d\omega).$$

- b) Compute $L_X \omega$ using Cartan's formula.
- c) Calculate X and ω in polar coordinates.
- d) Compute $L_X \omega$ using polar coordinates and $L_X \omega = \frac{d}{dt} \phi_t^* \omega|_{t=0}$, where ϕ_t is the flow of X .

20. Let $\alpha > 1$. Verify directly the equality of the Divergence Theorem,

$$\int_{\Omega} \operatorname{div} (p_*(\rho^\alpha \partial_\rho)) dx \wedge dy \wedge dz = \int_{T^2} (p_*(\rho^\alpha \partial_\rho)) \cdot \nu \bar{\eta},$$

where Ω is the interior of the torus T^2 of exercise **17**, p and ρ are as in the same exercise, ν is the unit outer normal to the torus, and $\bar{\eta} = \iota(\nu) dx \wedge dy \wedge dz$ is the area form on T^2 .

November 27, 2017

21. Consider the sphere S^2 with the metric induced by the euclidean metric on \mathbb{R}^3 , i.e., using the parameterization $r(\theta, \varphi) = (\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$, with metric

$$ds^2 = d\theta^2 + \sin^2 \theta d\varphi^2,$$

and with Levi-Civita connection.

- a) Write the equation for the geodesics.
 - b) What are the nonzero Christoffel symbols?
 - c) Let $0 \leq \theta_0 < \frac{\pi}{2}$. Consider the parallel $c(\varphi) = (\theta_0, \varphi)$. Let V be a vector field defined on c which is parallel along c . Write down the differential equations satisfied by V .
 - d) Solve the equations in c) knowing that $V(\theta_0, 0) = V_0^\theta \partial_\theta + V_0^\varphi \partial_\varphi$. In particular, compute $V(\theta_0, 2\pi)$.
 - e) Indicate the covariant derivatives $\nabla_{\dot{c}} d\theta$ and $\nabla_{\dot{c}} d\varphi$. Use them to compute the covariant derivative of the metric along c .
- 22.** Consider the hyperbolic plane $H^2 = \{(x, y) \in \mathbb{R}^2 : y > 0\}$ with the metric

$$ds^2 = \frac{dx^2 + dy^2}{y^2}$$

and Levi-Civita connection.

- a) Write the equation for the geodesics.
 - b) What are the nonzero Christoffel symbols?
 - c) Let $y_0 > 0$. Consider the line $c(x) = (x, y_0)$. Let V be a vector field defined on c which is parallel along c . Write down the differential equations satisfied by V .
 - d) Solve the equations in c) knowing that $V(0, y_0) = V_0^x \partial_x + V_0^y \partial_y$.
 - e) Indicate the covariant derivatives $\nabla_{\dot{c}} dx$ and $\nabla_{\dot{c}} dy$. Use them to compute the covariant derivative of the metric along c .
- 23.** Consider the hyperbolic plane H^2 with the metric

$$ds^2 = \frac{dx^2 + dy^2}{y^2}$$

and Levi-Civita connection.

- a) Let $f : H^2 \rightarrow \mathbb{R}$. Compute $\text{grad } f$.
- b) What is the Riemannian volume element, ω on H^2 ? Calculate the Lie derivative

$$L_{\text{grad } f} \omega.$$

What is the divergence of the gradient of f , i.e., the Laplacian of f ?

December 3, 2017

- 24.** Consider the sphere S^2 with the metric

$$ds^2 = d\theta^2 + \sin^2 \theta d\varphi^2$$

and Levi-Civita connection.

- a) Using the results of **21.b**), calculate $R(\partial_\theta, \partial_\varphi)\partial_\theta$ and $R(\partial_\theta, \partial_\varphi)\partial_\varphi$. Write the Riemann tensor and the curvature tensor.
- b) Calculate the curvature of S^2 .

25. Consider the hyperbolic plane H^2 with the metric

$$ds^2 = \frac{dx^2 + dy^2}{y^2}$$

and Levi-Civita connection.

- a) Using the results of **22.b**), calculate $R(\partial_x, \partial_y)\partial_x$ and $R(\partial_x, \partial_y)\partial_y$. Write the Riemann tensor and the curvature tensor.
- b) Calculate the curvature of H^2 .

26. Show that the curvature tensor of a 3-dimensional Riemannian manifold is entirely determined by its Ricci tensor.

December 11, 2017

27. Consider the spherically symmetric Riemannian metric given by

$$ds^2 = (B(r))^2 dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\varphi^2$$

and the orthonormal frame

$$\{E_r, E_\theta, E_\varphi\} = \left\{ \frac{1}{B} \partial_r, \frac{1}{r} \partial_\theta, \frac{1}{r \sin \theta} \partial_\varphi \right\}$$

The function B is positive.

- a) Compute the connection forms ω_r^θ , ω_θ^φ and ω_r^φ .
- b) Compute the curvature forms Ω_r^θ , Ω_θ^φ and Ω_r^φ .
- c) Compute the sectional curvatures $R_{r\theta r\theta}$, $R_{\theta\varphi\theta\varphi}$ and $R_{r\varphi r\varphi}$ and the curvature tensor.
- d) Compute the Ricci tensor.
- e) Compute the scalar curvature.

28. Consider the cylinder $C :=]0, \infty[\times S^1$ with metric

$$ds^2 = dr^2 + \sinh^2 r d\theta^2.$$

- a) Compute ω_r^θ , Ω_r^θ and $R_{r\theta r\theta}$. What is the curvature of C ?

b) Verify the equality of the Gauss-Bonnet Theorem,

$$\int_{\Omega} K + \int_{\partial\Omega} k_g = 2\pi \sum_i I_{p_i},$$

when $\Omega =]r_0, r_1[\times S^1$.

December 30, 2017

29. Let S be a compact orientable surface with a Riemannian metric with constant negative Gauss curvature. Let γ be a geodesic without self-intersections that separates S in two surfaces S_1 and S_2 with boundary, i.e.

$$S = S_1 \cup S_2, \quad \partial S_1 = \partial S_2 = \gamma.$$

Show that the quotient of the areas of S_1 and S_2 is a rational number.

30. Consider the paraboloid $z = f(x, y) = \frac{1}{2}(x^2 + y^2)$, $E_1 = \frac{f_x}{\|f_x\|}$, $E_2 = \frac{f_y}{\|f_y\|}$ and $n = E_1 \times E_2$. Note that E_1 and E_2 are not orthogonal. Check that the matrix representation of the second fundamental form of the surface in the basis (E_1, E_2) is

$$II(x, y) = \frac{1}{\sqrt{(1+x^2+y^2)^3}} \begin{bmatrix} 1+y^2 & -\frac{xy\sqrt{1+y^2}}{\sqrt{1+x^2}} \\ -\frac{xy\sqrt{1+x^2}}{\sqrt{1+y^2}} & 1+x^2 \end{bmatrix}$$

and that the curvature of the surface is

$$K = \frac{1}{(1+x^2+y^2)^2}.$$

31. Consider the surface represented parametrically by

$$(u, v) \mapsto f(u, v) = (f^1(u, v), f^2(u, v), f^3(u, v)),$$

$$E_1 = \frac{f_u}{\|f_u\|}, \quad E_2 = \frac{f_v}{\|f_v\|} \quad \text{and} \quad N = \frac{E_1 \times E_2}{\|E_1 \times E_2\|}.$$

a) Check that

$$\begin{aligned} p &:= (-\nabla_{E_1} N, E_1) = \frac{1}{\|f_u\|^2} (N, f_{uu}) =: \frac{l}{\|f_u\|^2}, \\ q &:= (-\nabla_{E_1} N, E_2) = \frac{1}{\|f_u\| \|f_v\|} (N, f_{uv}) = \frac{m}{\|f_u\| \|f_v\|}, \\ r &:= (-\nabla_{E_2} N, E_2) = \frac{1}{\|f_v\|^2} (N, f_{vv}) = \frac{n}{\|f_v\|^2}. \end{aligned}$$

- b)** Let $\Delta = 1 - (E_1, E_2)^2$. Check that the second fundamental form of the surface is

$$II(u, v) = \frac{1}{\Delta} \begin{bmatrix} p & q \\ q & r \end{bmatrix} \begin{bmatrix} 1 & -(E_1, E_2) \\ -(E_1, E_2) & 1 \end{bmatrix}.$$

- c)** Check that the curvature of the surface is

$$K = \frac{ln - m^2}{\|f_u\|^2 \|f_v\|^2 - (f_u, f_v)^2}.$$