

Algebraic and Geometric Methods in Engineering and Physics

2024/2025

1st Exam - 23 January 2025 - 10:30

Duration: 2 hours

- (9/20) 1. Consider the finite group $D_5 = \{e, r, r^2, r^3, r^4, s, sr, sr^2, sr^3, sr^4\}$, where the generators s and r satisfy the relations $s^2 = r^5 = e$ and $r^{-1} = sr s$.

- (a) List all subgroups of D_5 .
- (b) Determine all 1-dimensional (irreducible) representations of D_5 .
- (c) Show that if $\alpha = \frac{2\pi}{5}$ or $\alpha = \frac{4\pi}{5}$ then

$$\varphi_s = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad \varphi_r = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$$

determines a 2-dimensional irreducible representation $D_5 \curvearrowright \mathbb{C}^2$.

Hint: Recall that the matrix φ_r represents a rotation by an angle α .

- (d) Compute the characters of all the irreducible representations above.
- (e) How many equivalence classes of irreducible representations does D_5 have? What are their dimensions?
- (f) List the conjugacy classes of D_5 .

- (2/20) 2. Find all points with integer coordinates in the line $22x + 15y = 2$.

- (3/20) 3. Let $(M, \mathcal{T})$ be a compact topological space. Show that any closed set $F \subset M$ is also compact.

- (6/20) 4. Let $G \subset GL(n, \mathbb{C})$ be a matrix Lie group with Lie algebra $\mathfrak{g} \subset \mathfrak{gl}(n, \mathbb{C})$. The **fundamental** representation of G on $\mathbb{C}^n$ is the representation $G \curvearrowright \mathbb{C}^n$ given by

$$\varphi_A(v) = Av.$$

The **dual representation** of G on $(\mathbb{C}^n)^* = \{\omega : \mathbb{C}^n \rightarrow \mathbb{C} \mid \omega \text{ is complex linear}\}$ is the representation $G \curvearrowright^* (\mathbb{C}^n)^*$ determined by

$$\varphi_A^*(\omega)(\varphi_A(v)) = \omega(v).$$

Show that:

- (a) If we identify $(\mathbb{C}^n)^*$ with $\mathbb{C}^n$ by setting $\omega(v) = \omega^t v$ for all $\omega, v \in \mathbb{C}^n$ then we have $\varphi_A^*(\omega) = (A^{-1})^t \omega$.
- (b) The dual representation of $SU(2)$ is equivalent to the fundamental representation of $SU(2)$.
- (c) The dual representation of $SU(3)$ is **not** equivalent to the fundamental representation of $SU(3)$.
- (d) If $X^V \in \mathfrak{X}(G)$ the left-invariant vector field associated to $V \in \mathfrak{g}$ then its flow is given by $\phi_t^{X^V}(A) = Ae^{Vt}$.