

Riemannian Geometry

Homework 6

Due on October 27

1. Given the differential forms

$$\alpha = xdx + ydy \in \Omega^1(\mathbb{R}^2)$$

$$\beta = -\frac{y}{x^2 + y^2}dx + \frac{x}{x^2 + y^2}dy \in \Omega^1(\mathbb{R}^2 \setminus \{0\})$$

$$\omega = e^{xz}dx + x \cos z dy + y^2 dz \in \Omega^1(\mathbb{R}^3)$$

$$\eta = xdx \wedge dy - zdx \wedge dz + xyzdy \wedge dz \in \Omega^2(\mathbb{R}^3)$$

$$\zeta = dx^1 \wedge dx^2 + \dots + dx^{2n-1} \wedge dx^{2n} \in \Omega^2(\mathbb{R}^{2n})$$

and the smooth maps

$$\begin{array}{lll} f : \mathbb{R} \rightarrow \mathbb{R}^2 & g : (0, +\infty) \times (0, 2\pi) \rightarrow \mathbb{R}^2 & h : \mathbb{R}^3 \rightarrow \mathbb{R}^3 \\ f(t) = (t, t^2) & g(r, \theta) = (r \cos \theta, r \sin \theta) & h(u, v, w) = (uv, vw, uw) \end{array}$$

compute:

- (a) $\alpha \wedge \beta, \omega \wedge \eta, \eta \wedge \eta$;
- (b) $\zeta \wedge \dots \wedge \zeta$ (wedge product with n factors);
- (c) $d\alpha, d\beta, d\omega, d\eta, d\zeta$.
- (d) $f^*\alpha, g^*\alpha, g^*\beta, h^*\eta$.

2. Given the vector isomorphisms $i_1 : \mathfrak{X}(\mathbb{R}^3) \rightarrow \Omega^1(\mathbb{R}^3)$ and $i_2 : \mathfrak{X}(\mathbb{R}^3) \rightarrow \Omega^2(\mathbb{R}^3)$ defined by

$$\begin{aligned} i_1 \left(X^1 \frac{\partial}{\partial x} + X^2 \frac{\partial}{\partial y} + X^3 \frac{\partial}{\partial z} \right) &= X^1 dx + X^2 dy + X^3 dz \\ i_2 \left(X^1 \frac{\partial}{\partial x} + X^2 \frac{\partial}{\partial y} + X^3 \frac{\partial}{\partial z} \right) &= X^1 dy \wedge dz + X^2 dz \wedge dx + X^3 dx \wedge dy \end{aligned}$$

show that for $f \in C^\infty(\mathbb{R}^3)$ and $X, Y \in \mathfrak{X}(\mathbb{R}^3)$:

- (a) $df = i_1(\nabla f)$, where $\nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right)$ is the **gradient** of f ;
- (b) $d(i_1(X)) = i_2(\nabla \times X)$, where $\nabla \times X = \left(\frac{\partial X^3}{\partial y} - \frac{\partial X^2}{\partial z}, \frac{\partial X^1}{\partial z} - \frac{\partial X^3}{\partial x}, \frac{\partial X^2}{\partial x} - \frac{\partial X^1}{\partial y} \right)$ is the **curl** of X ;

- (c) $d(i_2(X)) = (\nabla \cdot X) dx \wedge dy \wedge dz$, where $\nabla \cdot X = \frac{\partial X^1}{\partial x} + \frac{\partial X^2}{\partial y} + \frac{\partial X^3}{\partial z}$ is the **divergence** of X ;
- (d) $d(df) = 0$ implies $\nabla \times (\nabla f) = 0$;
- (e) $d(d(i_1(X))) = 0$ implies $\nabla \cdot (\nabla \times X) = 0$;
- (f) $\nabla \times (fX) = (\nabla f) \times X + f(\nabla \times X)$;
- (g) $\nabla \cdot (X \times Y) = (\nabla \times X) \cdot Y - X \cdot (\nabla \times Y)$.

3. **(Optional)** A k -form ω is called **closed** if $d\omega = 0$. If it exists a $(k-1)$ -form β such that $\omega = d\beta$ then ω is called **exact**. Note that every exact form is closed. Let Z^k be the set of all closed k -forms on M and define a relation between forms on Z^k as follows: $\alpha \sim \beta$ if and only if they differ by an exact form, that is, if $\beta - \alpha = d\theta$ for some $(k-1)$ -form θ .

- (a) Show that this relation is an equivalence relation.
- (b) Let $H^k(M)$ be the corresponding set of equivalence classes (called the **k -dimensional de Rham cohomology space** of M). Show that addition and scalar multiplication of forms define indeed a vector space structure on $H^k(M)$.
- (c) Let $f : M \rightarrow N$ be a smooth map. Show that:
- the pull-back f^* carries closed forms to closed forms and exact forms to exact forms;
 - if $\alpha \sim \beta$ on N then $f^*\alpha \sim f^*\beta$ on M ;
 - f^* induces a linear map on cohomology $f^\# : H^k(N) \rightarrow H^k(M)$ naturally defined by $f^\#[\omega] = [f^*\omega]$;
 - if $g : L \rightarrow M$ is another smooth map, then $(f \circ g)^\# = g^\# \circ f^\#$.
- (d) Show that the dimension of $H^0(M)$ is equal to the number of connected components of M .
- (e) Show that $H^k(M) = 0$ for every $k > \dim M$.

4. **(Optional)** Let M be a manifold of dimension n , let U be an open subset of \mathbb{R}^n and let ω be a k -form on $\mathbb{R} \times U$. Writing ω as

$$\omega = dt \wedge \sum_I a_I dx^I + \sum_J b_J dx^J,$$

where $I = (i_1, \dots, i_{k-1})$ and $J = (j_1, \dots, j_k)$ are increasing index sequences, (x^1, \dots, x^n) are coordinates in U and t is the coordinate in \mathbb{R} , consider the operator \mathcal{Q} defined by

$$\mathcal{Q}(\omega)_{(t,x)} = \sum_I \left(\int_{t_0}^t a_I ds \right) dx^I,$$

which transforms k -forms ω in $\mathbb{R} \times U$ into $(k-1)$ -forms.

- (a) Let $f : V \rightarrow U$ be a diffeomorphism between open subsets of \mathbb{R}^n . Show that the induced diffeomorphism $\tilde{f} := \text{id} \times f : \mathbb{R} \times V \rightarrow \mathbb{R} \times U$ satisfies

$$\tilde{f}^* \circ Q = Q \circ \tilde{f}^*.$$

- (b) Using (a), construct an operator Q which carries k -forms on $\mathbb{R} \times M$ into $(k-1)$ -forms and, for any diffeomorphism $f : M \rightarrow N$, the induced diffeomorphism $\tilde{f} := \text{id} \times f : \mathbb{R} \times M \rightarrow \mathbb{R} \times N$ satisfies $\tilde{f}^* \circ Q = Q \circ \tilde{f}^*$. Show that this operator is linear.
- (c) Considering the operator Q defined in (b) and the inclusion $i_{t_0} : M \rightarrow \mathbb{R} \times M$ of M at the “level” t_0 , defined by $i_{t_0}(p) = (t_0, p)$, show that $\omega - \pi^* i_{t_0}^* \omega = dQ\omega + Qd\omega$, where $\pi : \mathbb{R} \times M \rightarrow M$ is the projection on M .
- (d) Show that the maps $\pi^\# : H^k(M) \rightarrow H^k(\mathbb{R} \times M)$ and $i_{t_0}^\# : H^k(\mathbb{R} \times M) \rightarrow H^k(M)$ are inverses of each other (and so $H^k(M)$ is isomorphic to $H^k(\mathbb{R} \times M)$).
- (e) Use (d) to show that, for $k > 0$ and $n > 0$, every closed k -form in \mathbb{R}^n is exact, that is, $H^k(\mathbb{R}^n) = 0$ if $k > 0$.
- (f) Use (d) to show that, if $f, g : M \rightarrow N$ are two **smoothly homotopic maps** between smooth manifolds (meaning that there exists a smooth map $H : \mathbb{R} \times M \rightarrow N$ such that $H(t_0, p) = f(p)$ and $H(t_1, p) = g(p)$ for some fixed $t_0, t_1 \in \mathbb{R}$), then $f^\# = g^\#$.
- (g) We say that M is **contractible** if the identity map $\text{id} : M \rightarrow M$ is smoothly homotopic to a constant map. Show that \mathbb{R}^n is contractible.
- (h) Let M be a contractible smooth manifold. Show that every closed form on M is exact, that is, $H^k(M) = 0$ for all $k > 0$ (**Poincaré Lemma**).