# On the partial regularity of suitable weak solutions: Pointwise estimates and space-time decay 

## Francesca Crispo

Department of Mathematics and Physics
Second University of Naples

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The subject of the talk is part of two papers with P. Maremonti:
F. C. and P. Maremonti, A remark on the partial regularity of a suitable weak solution to the Navier-Stokes Cauchy problem, submitted.
F. C. and P. Maremonti, On the spatial asymptotic decay of a suitable weak solution to the Navier-Stokes Cauchy problem, submitted.

## Introduction

## We study the Navier-Stokes Cauchy problem:

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\begin{align*}
& v_{t}+v \cdot \nabla v+\nabla \pi_{v}=\Delta v, \nabla \cdot v=0, \text { in }(0, T) \times \mathbb{R}^{3},  \tag{1}\\
& v(0, x)=v_{\circ}(x) \text { on }\{0\} \times \mathbb{R}^{3} .
\end{align*}
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[CKN82] L. Caffarelli, R. Kohn and L. Nirenberg, Comm. Pure Appl. Math., 35 (1982) the following existence result is proved:

Theorem 1 (Here $J^{2}\left(\mathbb{R}^{3}\right):=$ completion of $\mathscr{C}_{0}\left(\mathbb{R}^{3}\right)$ in $L^{2}$-norm)
For all $v_{\circ} \in J^{2}\left(\mathbb{R}^{3}\right)$ there exists a suitable weak solution.

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i) for all $T>0, v \in L^{2}\left(0, T ; J^{1,2}\left(\mathbb{R}^{3}\right)\right)$ and $\pi_{v} \in L^{\frac{5}{3}}\left((0, T) \times \mathbb{R}^{3}\right)$,

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\|v(t)\|_{2}^{2}+2 \int_{0}^{t}\|\nabla v(\tau)\|_{2}^{2} d \tau \leq \| v_{v_{2}}^{2}, t>0
$$

ii) $\lim _{t \rightarrow 0}\left\|v(t)-v_{0}\right\|_{2}=0$,
iii) for all $t, s \in(0, T)$ and for all $\varphi \in C_{0}^{1}\left([0, T) \times \mathbb{R}^{3}\right)$ :

$$
\int_{s}^{t}\left[\left(v, \varphi_{\tau}\right)-(\nabla v, \nabla \varphi)+(v \cdot \nabla \varphi, v)+\left(\pi_{v}, \nabla \cdot \varphi\right)\right] d \tau+(v(s), \varphi(s))=(v(t), \varphi(t))
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iv) for all $t \geq s$, for $s=0$ and a.e. in $s \geq 0$, and for all nonnegative $\phi \in C_{0}^{\infty}\left(\mathbb{R} \times \mathbb{R}^{3}\right)$ :

$$
\begin{aligned}
\int_{\mathbb{R}^{3}}|v(t)|^{2} \phi(t) & +2 \int_{s}^{t} \int_{\mathbb{R}^{3}}|\nabla v|^{2} \phi \leq \int_{\mathbb{R}^{3}}|v(s)|^{2} \phi(s) d x \\
& +\int_{s}^{t} \int_{\mathbb{R}^{3}}|v|^{2}\left(\phi_{\tau}+\Delta \phi\right) d x d \tau+\int_{s}^{t} \int_{\mathbb{R}^{3}}^{t}\left(|v|^{2}+2 \pi_{v}\right) v \cdot \nabla \phi d x d \tau .
\end{aligned}
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However in [CKN82] and, subsequently in several papers,
[1] R. Farwig, Progress in partial differential equations: the Metz surveys, 4, 205-215, Pitman Res. Notes Math. Ser., 345, Longman, Harlow, 1996.
[2] O.A. Ladyzhenskaya and G.A. Seregin, J. Math. Fluid Mech. 1 (1999), 356-387.
[3] F. Lin, Comm. Pure Appl. Math. 51 (1998), 241-257.
[4] G.A. Seregin, Russian Math. Surveys 62 (2007), 595-614.
[5] A. Vasseur, Nonlin. Diff. Eq. Appl. 14 (2007), 753-785.
the partial regularity of a suitable weak solution is studied.

## Following [CKN82] we set

$$
M(r):=r^{-2} \iint_{Q_{r}}\left(|v|^{3}+|v|\left|\pi_{v}\right|\right) d y d \tau+r^{-\frac{13}{4}} \int_{t-r^{2}}^{t}\left(\int_{|x-y|<r}\left|\pi_{v}\right| d y\right)^{\frac{5}{4}} d \tau
$$

where $r \in\left(0, t^{\frac{1}{2}}\right)$, and

$$
\begin{gathered}
Q_{r}(t, x):=\left\{(\tau, y): t-r^{2}<\tau<t \text { and }|y-x|<r\right\}, \\
Q_{r}^{*}(t, x):=\left\{(\tau, y): t-\frac{7}{8} r^{2}<\tau<t+\frac{1}{8} r^{2} \text { and }|y-x|<r\right\} .
\end{gathered}
$$

In [CKN82] it is proved:

## Proposition 1

Let $\left(v, \pi_{v}\right)$ be a suitable weak solution in some parabolic cylinder $Q_{r}(t, x)$. There exist $\varepsilon_{1}>0$ and $c_{0}>0$ independent of $\left(v, \pi_{v}\right)$ such that, if $M(r) \leq \varepsilon_{1}$, then

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\begin{equation*}
|v(\tau, y)| \leq c_{1}^{\frac{1}{2}} r^{-1} \text {, a. e. in }(\tau, y) \in Q_{\frac{r}{2}}(t, x) \tag{2}
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## Proposition 2

There exists a constant $\varepsilon_{3}>0$ with the following property. If $\left(v, \pi_{v}\right)$ is a suitable weak solution in some parabolic cylinder $Q_{r}^{*}(t, x)$ and

$$
\limsup _{r \rightarrow 0} r^{-1} \iint_{Q_{r}^{*}}|\nabla v|^{2} d y d \tau \leq \varepsilon_{3}
$$

then $(t, x)$ is a regular point.

In [CKN82], the above propositions are crucial to deduce a partial regularity for a suitable weak solution. However in both the results no dependence on the initial data is given.

Also in the case of their applications, in particular Theorem C and Theorem D, and its Corollary, the results of regularity express on the geometry of regular points, but a behavior in a neighborhood of $t=0$ does not seem an immediate consequence

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## A first result and comments

## We define

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\begin{equation*}
\left\|v_{0}\right\|_{2, w(x)}:=\left(\int_{\mathbb{R}^{3}} \frac{\left|v_{0}(y)\right|^{2}}{|x-y|} d y\right)^{\frac{1}{2}}, \quad \mathscr{E}_{0}\left(x_{0}, R_{0}\right):=\underset{B\left(x_{0}, R_{0}\right)}{\left.\operatorname{ess} \sup \left\|v_{o}\right\|_{2, w(x)},{ }_{2}\right)} \tag{3}
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provided that $(t, x)$ is a Lebesgue point with $\left\|v_{0}\right\|_{2, w(x)}<\infty$ and $x \in B\left(x_{0}, R_{0}\right)$.
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## Theorem 2

Let $\left(v, \pi_{v}\right)$ be a suitable weak solution corresponding to $v_{\circ} \in J^{2}\left(\mathbb{R}^{3}\right)$. There exist absolute constants $\varepsilon_{1}, C_{1}$ and $C_{2}$ such that if

$$
\begin{equation*}
C_{1} \mathscr{E}_{0}\left(x_{0}, R_{0}\right)<1 \text { and } C_{2}\left(\mathscr{E}_{0}^{3}+\mathscr{E}_{0}^{\frac{5}{2}}\right) \leq \varepsilon_{1} \tag{4}
\end{equation*}
$$

then

$$
\begin{equation*}
|v(t, x)| \leq c\left(\mathscr{E}_{0}^{3}+\mathscr{E}_{0}^{\frac{5}{2}}\right)^{\frac{1}{3}} t^{-\frac{1}{2}} \tag{5}
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## A first result and comments: About the assumption (4).

We remark that for all $v_{\circ} \in J^{2}\left(\mathbb{R}^{3}\right)$, by virtue of the Hardy-Littlewood-Sobolev theorem, we have that $\left\|v_{\circ}\right\|_{2, w(x)}<\infty$ almost everywhere in $x \in \mathbb{R}^{3}$.

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Hence, a data in $L^{2}$ inherently defines functional (3) $)_{1}$.
But in condition (4) there is more, that is the smallness of the norm $\left\|\left\|v_{0}\right\|_{2, w(x)}\right\|_{L^{\infty}\left(B\left(x_{0}, R_{0}\right)\right)}$. We can find several sufficient conditions on $v_{\circ} \in J^{2}\left(\mathbb{R}^{3}\right)$ such that assumption (4) is verified. For example, if we consider the assumption made in [CKN82] (in the Corollary), that is $v_{\circ} \in W^{1,2}\left(\mathbb{R}^{3} \backslash B_{R}\right)$, then $\left\|v_{\circ}\right\|_{2, w(x)}$ is a continuous function of $x$ that we can make small outside a suitable ball of radius $R^{\prime} \geq R$.

## A first result and comments: On the proof of the regularity result

The proof of Theorem 2 is based on Proposition 1.
Also in [CKN82] the regularity result is based on Proposition 1, but our approach to the regularity via the Proposition 1 is different. Indeed, we prove a weighted energy relation (the norm is $\left.\|v(t)\|_{2, n(v)}\right)$ which holds for $t>0$. provided that $(4)_{1}$ holds:

Thanks to estimate (6) we can apply Proposition 1 by [CKN82] to deduce regularity.

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\int_{\mathbb{R}^{3}} \frac{|v(t, y)|^{2}}{|x-y|} d y+c\left(\mathscr{E}_{0}\right) \int_{0}^{t} \int_{\mathbb{R}^{3}} \frac{|\nabla v(\tau, y)|^{2}}{|x-y|} d y d \tau \leq c \int_{\mathbb{R}^{3}} \frac{\left|v_{0}(y)\right|^{2}}{|x-y|} d y \tag{6}
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for all $t>0$, a.e. in $B\left(x_{0}, R_{0}\right)$.

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The partial regularity has a local character in the sense that condition (4) can be not satisfied on $\mathbb{R}^{3} \backslash B\left(x_{0}, R_{0}\right)$, and the regularity is ensured a.e. in $B\left(x_{0}, R_{0}\right)$.
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For this reason our result improves the previous one (that is $\nabla v_{0} \in L^{2}\left(\mathbb{R}^{3} \backslash B_{R}\right)$ ) proved in [CKN82], in the sense that our thesis gives a bound and a behavior in neighborhood of $t=0$ :

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|v(t, x)| \leq c\left(v_{o}\right) t^{-\frac{1}{2}},(t, x) \in(0, \infty) \times \mathbb{R}^{3} \backslash B_{R^{\prime}} .
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In particular, if $B\left(x_{0}, R_{0}\right) \equiv \mathbb{R}^{3}$, then we get a new sufficient condition for the existence of global smooth solutions.

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Of course estimate (5) also gives a pointwise asymptotic behavior of the solution for large $t$. However such a behavior is not optimal under the assumption $v_{0} \in J^{2}\left(\mathbb{R}^{3}\right)$. Indeed for a suitable weak solution the pointwise asymptotic behavior is of the kind $O\left(\left\|v_{0}\right\|_{2} t^{-\frac{3}{4}}\right)$, according to the fact that a weak solution becomes smooth for $t>T_{0}$, where $T_{0}$ is connected with the $L^{2}$-norm of $v_{0}$, and the behavior is stated considering the $L^{2}$-norm of the initial data.

## Introduction to the second result

To better explain our aim, we start from two basic results, one due to Leray (1934) (structure theorem) and the other contained in [CKN82].

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Further, in the light of our Theorem 2 we can claim:

$$
|v(t, x)| \leq c\left(v_{0}\right) t^{-\frac{1}{2}}, \text { for all }(t, x) \in(0, \infty) \times \mathbb{R}^{3}-B_{R^{\prime}}
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Roughly speaking, following Leray and the results in [CKN82], we say that the possible turbulence of a weak solution not only appears in a finite time ( $t<T_{0}$ ), but also in a bounded region of the space $\left(B_{R^{\prime}}\right)$, whose $\mathscr{P}^{1}$-measure is null (this last is true as soon as a suitable weak solution exists).

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The aim of our note goes in the direction of the last claims. We prove that, not only the possible turbulence does not perturb the regularity of a weak solution in a neighborhood of infinity, but, if an asymptotic spatial behavior of the initial data $v_{\circ}$ is given, then the same behavior holds for a suitable weak solution for all $t>0$.

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As far as we know, such a property to date was ensured only for small data, [Knightly66], [F.C. and P.Maremonti 04].

## The second result

## Theorem 3

Let $v_{\circ} \in J^{2}\left(\mathbb{R}^{3}\right)$ and, for some $\alpha \in[1,3)$ and $R_{0}>0$, let be $\left|v_{0}(x)\right| \leq V_{\circ}|x|^{-\alpha}$, for $|x|>R_{0}$. Let $\left(v, \pi_{v}\right)$ be a suitable weak solution to the Navier-Stokes Cauchy problem. Then, there exists a constant $M \geq 1$ such that

$$
\begin{equation*}
|v(t, x)| \leq c\left(v_{0}\right)|x|^{-\alpha}, \text { for all }(t, x) \in(0, \infty) \times \mathbb{R}^{3} \backslash B_{M R_{0}} \tag{7}
\end{equation*}
$$

where $M$ is independent of $v_{0}$. Moreover,

$$
|v(t, x)| \leq c\left(v_{0}\right) t^{-\frac{\alpha}{2}},(t, x) \in\left(T_{0}, \infty\right) \times \mathbb{R}^{3} .
$$

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We are able to give a representation formula in $\mathbb{R}^{3} \backslash B_{M_{0} R_{0}}$, where the existence of $M_{0}$ is proved in the first result.
Then, we get for all $t>0$ and almost a.e. in $x \in \mathbb{R}^{3} \backslash B_{M_{0} R_{0}}$ :

$$
\begin{gather*}
v(t, x)=\mathbb{H}\left[v_{0}\right](t, x)+\mathbb{T}[v \otimes v](t, x),  \tag{8}\\
\mathbb{H}\left[v_{0}\right](t-s, x):=\int_{\mathbb{R}^{3}} H(t-\tau, y) v_{0}(y) d y=: w(t, x), \\
\mathbb{T}[v \otimes v](t, x):=\int_{0}^{t} \int_{\mathbb{R}^{3}} v(\tau, y) \cdot \nabla T_{i}(t-\tau, x-y) \cdot v(\tau, y) d y d \tau .
\end{gather*}
$$

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$$

It is not difficult to discuss the terms which contain the linear part $w$.
As far as it concerns the term $\mathbb{T}[u, u]$, that we call non-smooth term, we employ the following estimate

This behavior derives from a suitable discussion of the generalized energy inequality (it is not trivial). Of course, an iterative procedure is needed to perform the same order of decay of the initial data:

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It is not difficult to discuss the terms which contain the linear part $w$.
As far as it concerns the term $\mathbb{T}[u, u]$, that we call non-smooth term, we employ the following estimate

$$
\|u(t)\|_{L^{2}\left(\mathbb{R}^{3} \backslash B_{R}\right)}^{2} \leq c\left(v_{\circ}\right) R^{-1}
$$

This behavior derives from a suitable discussion of the generalized energy inequality (it is not trivial). Of course, an iterative procedure is needed to perform the same order of decay of the initial data:

$$
|v(t, x)| \leq c\left(v_{\circ}\right)|x|^{-\alpha}, t>0,|x|>M_{0} R_{0}
$$

## Thank for your attention.

